



University  
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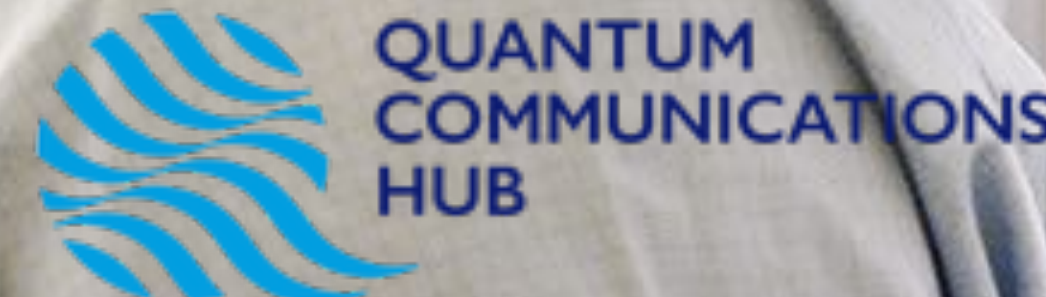
# Ge on Si SPADs for LiDAR & Quantum Technology Applications

**Douglas J. Paul**<sup>1</sup>, J. Kirdoda<sup>1</sup>, L. Ferre Llin<sup>1</sup>, K. Kuzmenko<sup>2</sup>, P. Vines<sup>2</sup>, F.E. Thorburn<sup>2</sup>, L.L. Huddleston<sup>2</sup>, Z. Greener<sup>2</sup>, D.C.S. Dumas<sup>1</sup>, R.W. Miller<sup>1</sup>, M.M. Mirza<sup>1</sup>, A. Halimi<sup>2</sup>, R.J. Collins<sup>2</sup>, A. Maccarone<sup>2</sup>, A. McCarthy<sup>2</sup> & Gerald S. Buller<sup>2</sup>

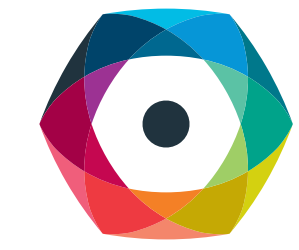
<sup>1</sup>James Watt School of Engineering, University of Glasgow, U.K

<sup>2</sup>Institute of Photonics and QT, Heriot-Watt University, U.K.

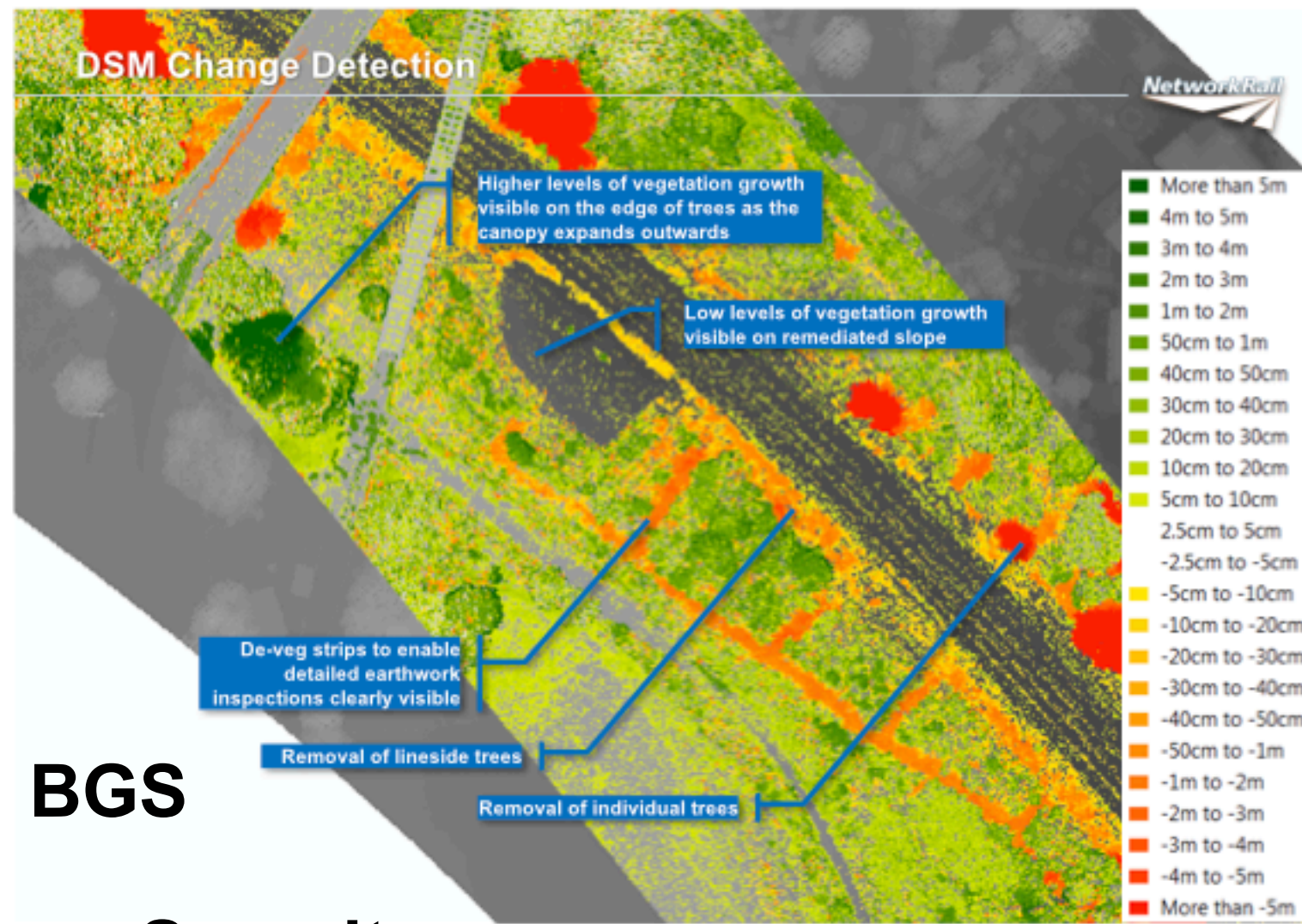
<http://userweb.eng.gla.ac.uk/douglas.paul/>



Innovate UK

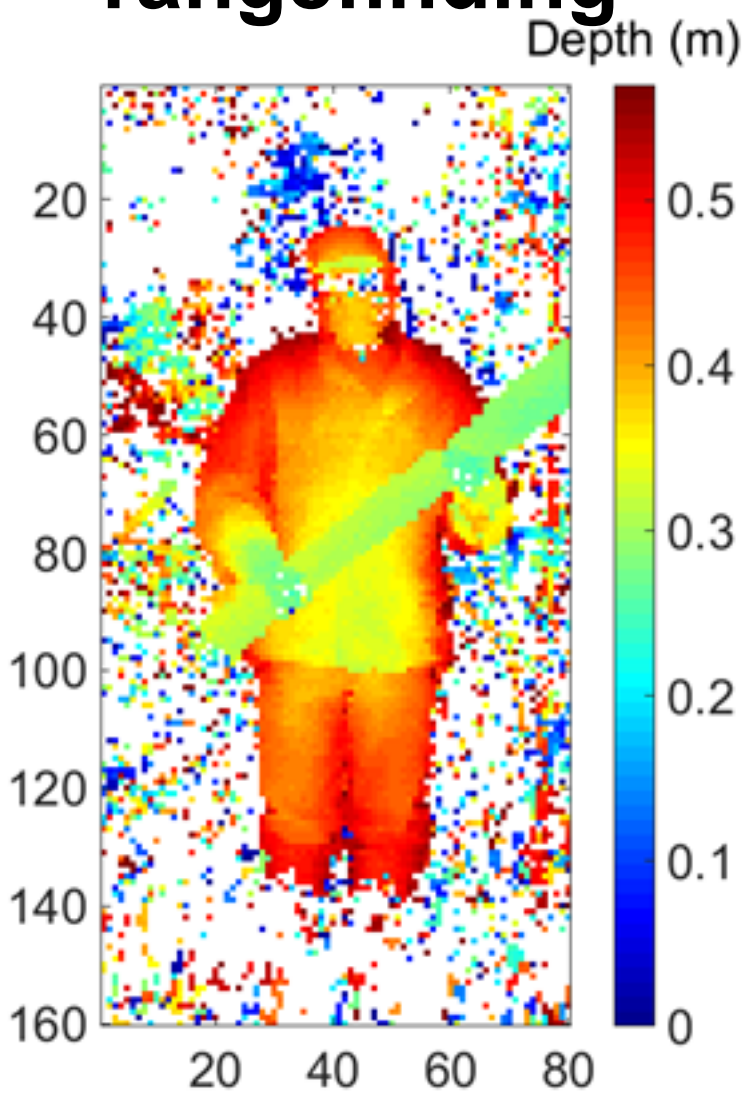


## Erosion measurement



BGS

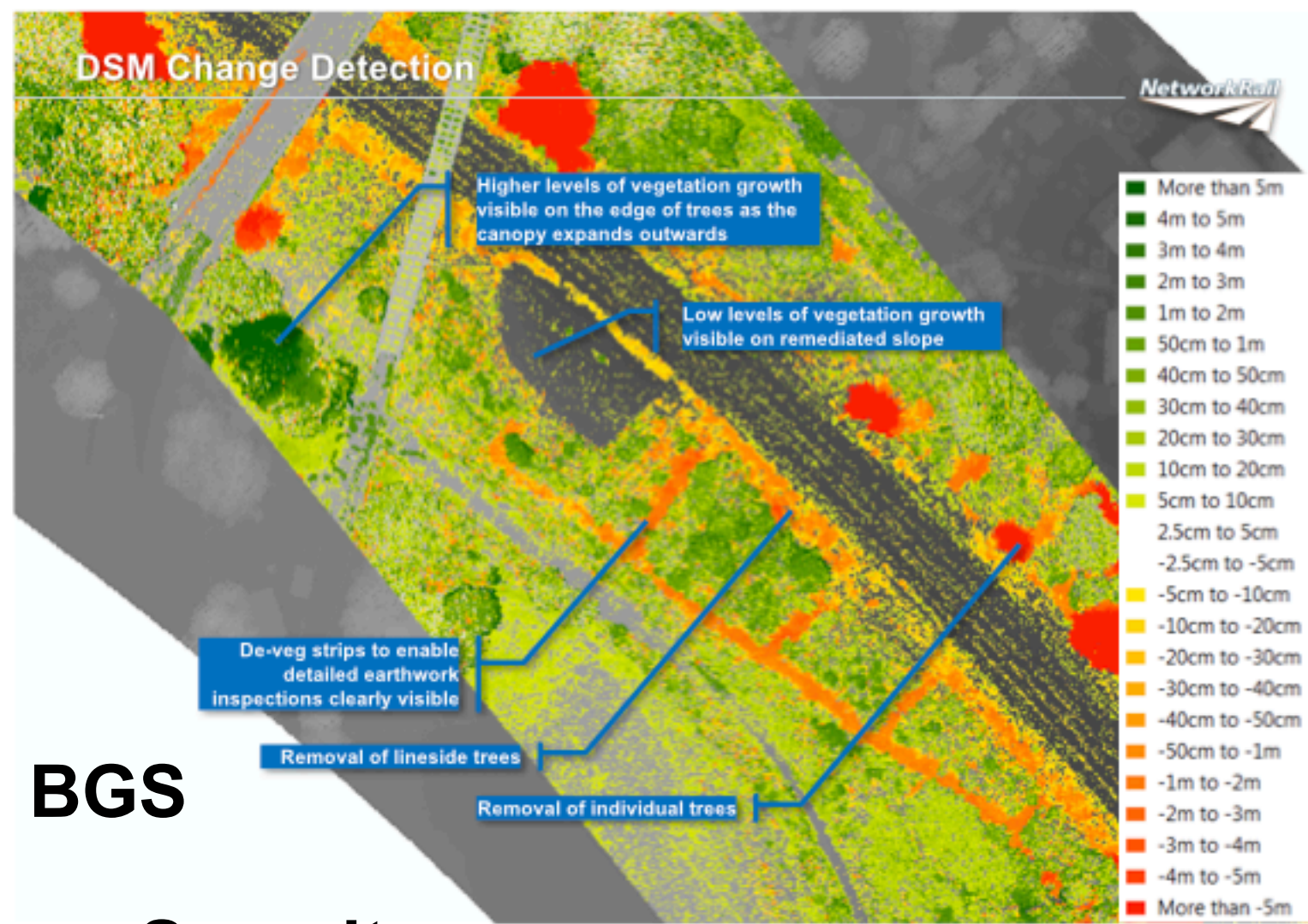
## Security rangefinding



## Automotive & autonomous vehicle lidar



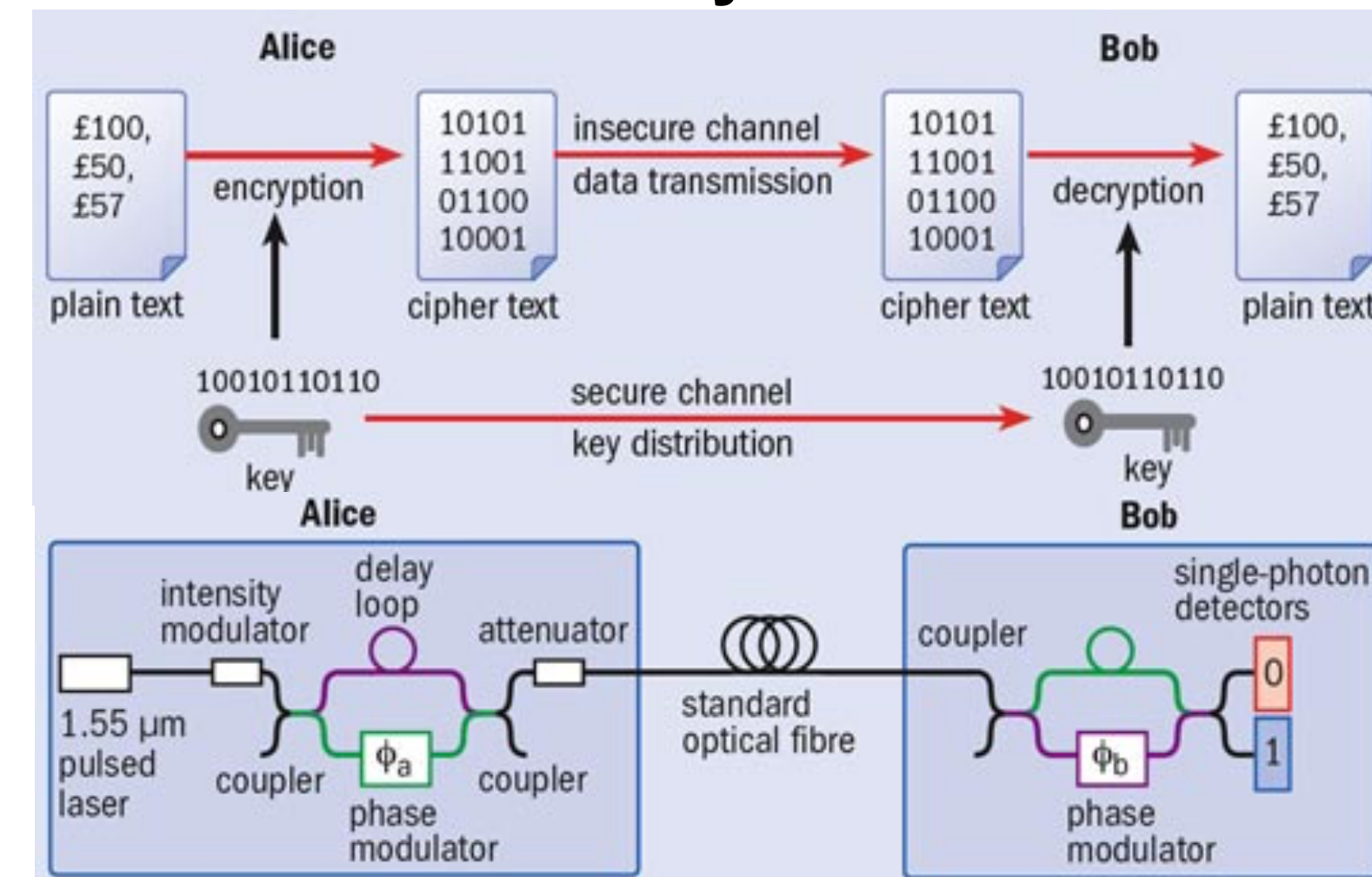
## Erosion measurement



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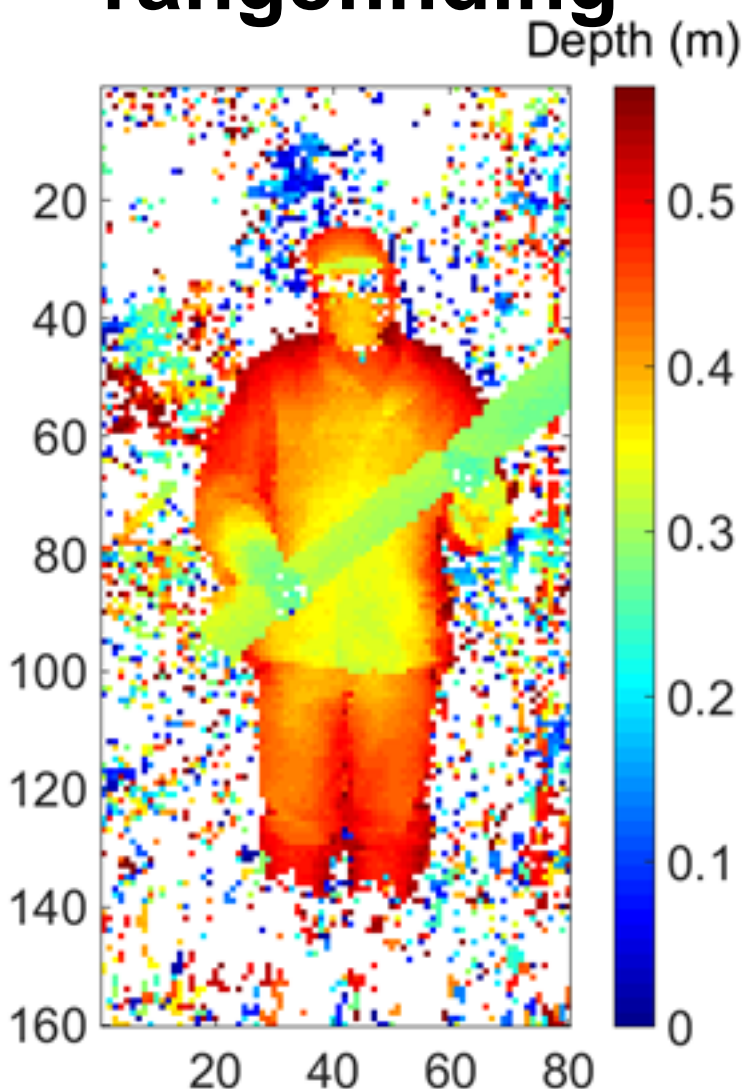


## Quantum key distribution

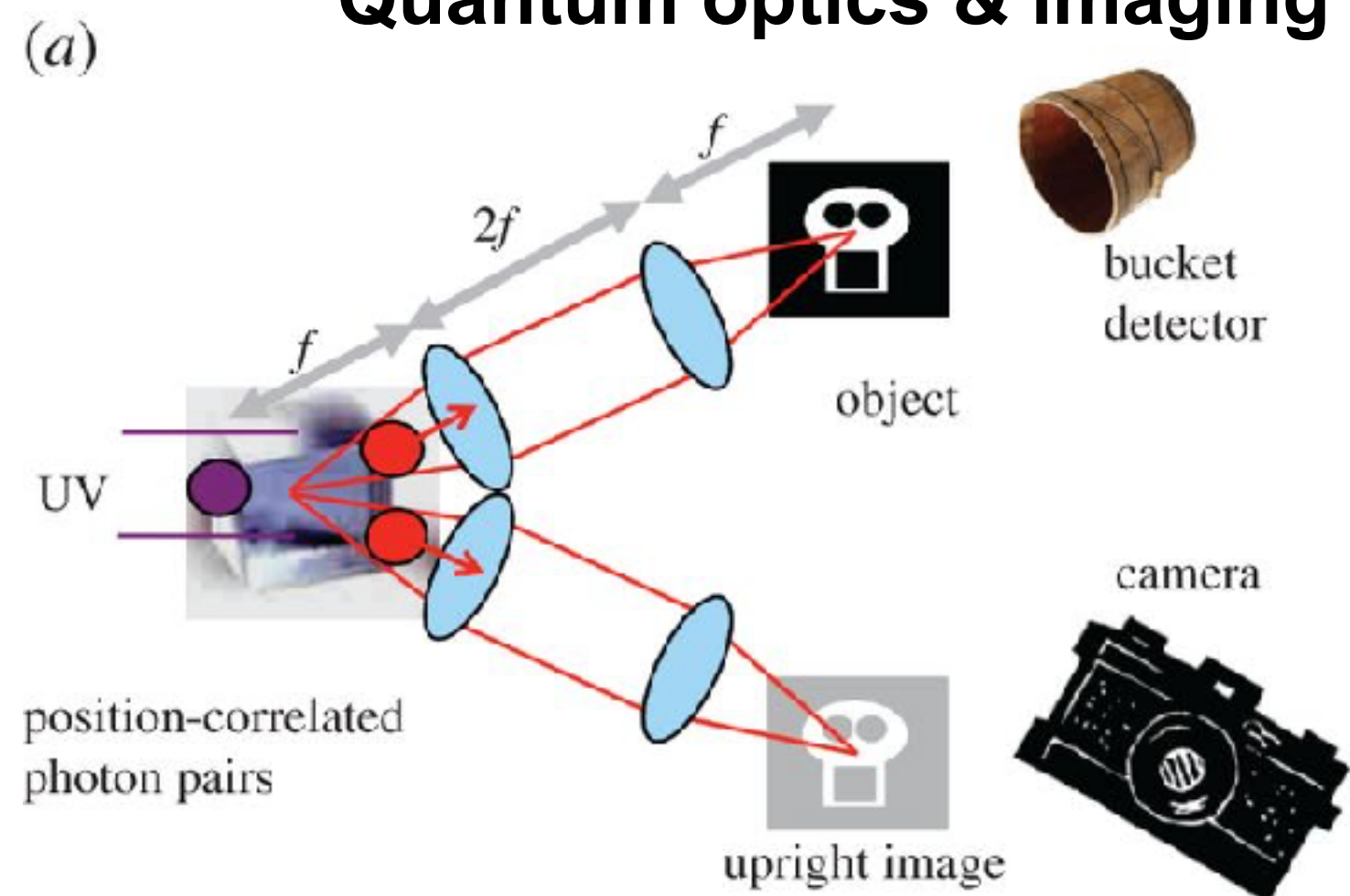


Andrew Shields, *Phys. World* (2007)

## Security rangefinding

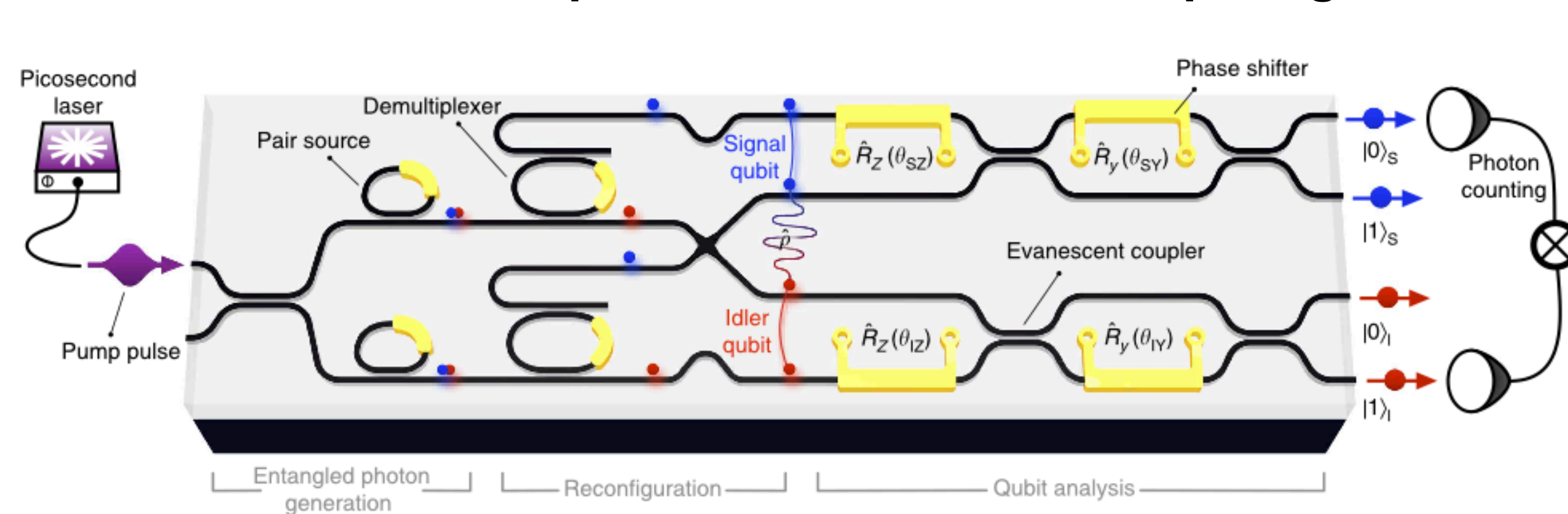


## Quantum optics & imaging



Padgett & Boyd, *Phil. Trans. Roy. Soc. A* 375, 20160233 (2017)

## Photonic quantum simulation / computing



J.W. Singleton et al. *Nature Comms.* 6, 7948 (2015)



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# Practical LIDAR: Imaging Through Obscurants

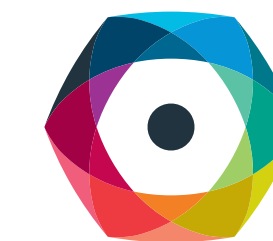




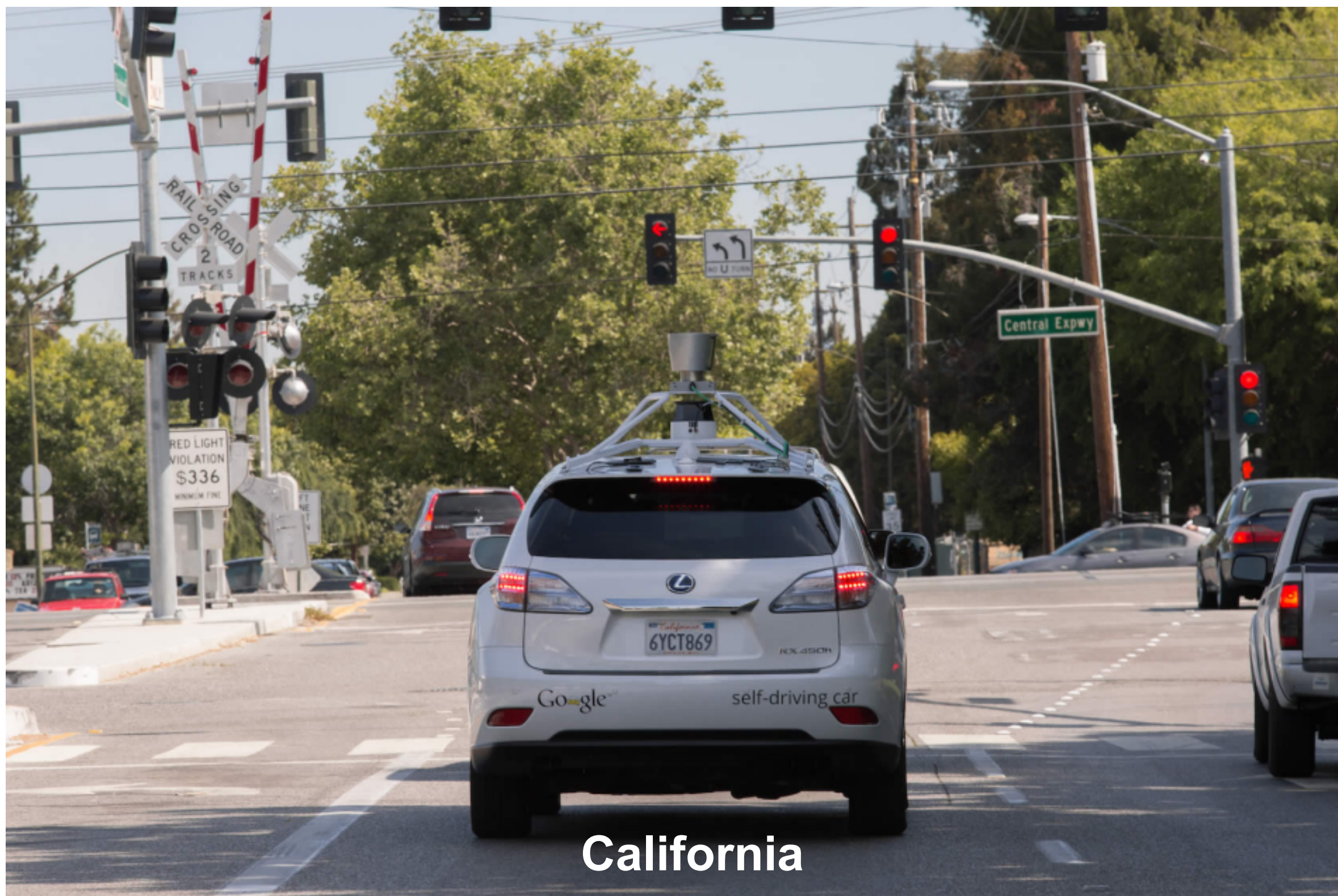
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# Practical LIDAR: Imaging Through Obscurants



QUANTIC



California



Cambridge

<https://youngcardriver.com/driving/driving-in-heavy-rain/>



# Practical LIDAR: Imaging Through Obscurants



California



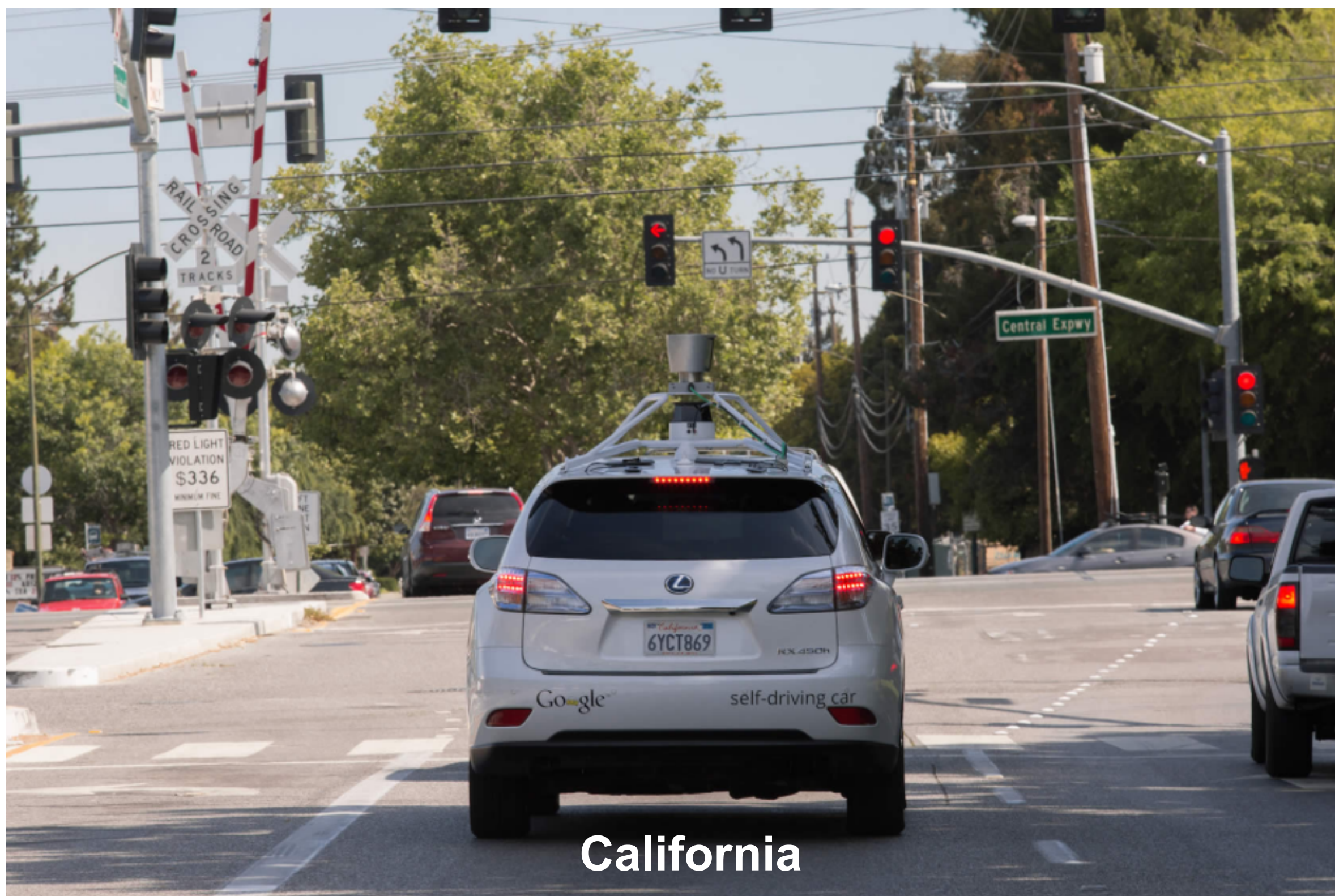
Cambridge

<https://youngcardriver.com/driving/driving-in-heavy-rain/>

- UK motorway or A-class road requirement: Level 4 autonomy requires identification of objects in 10 ms at 300 m



# Practical LIDAR: Imaging Through Obscurants



California

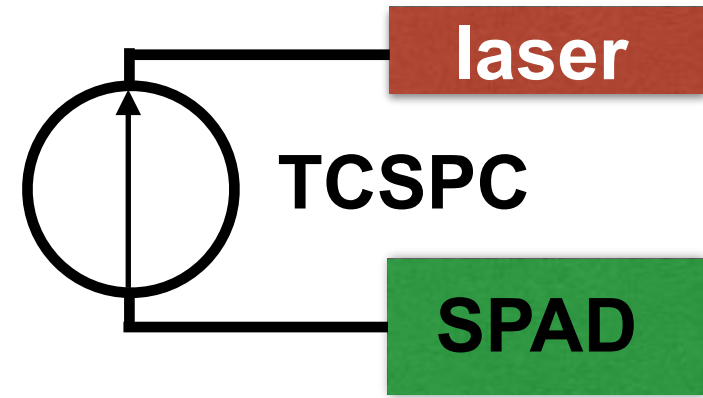


Cambridge

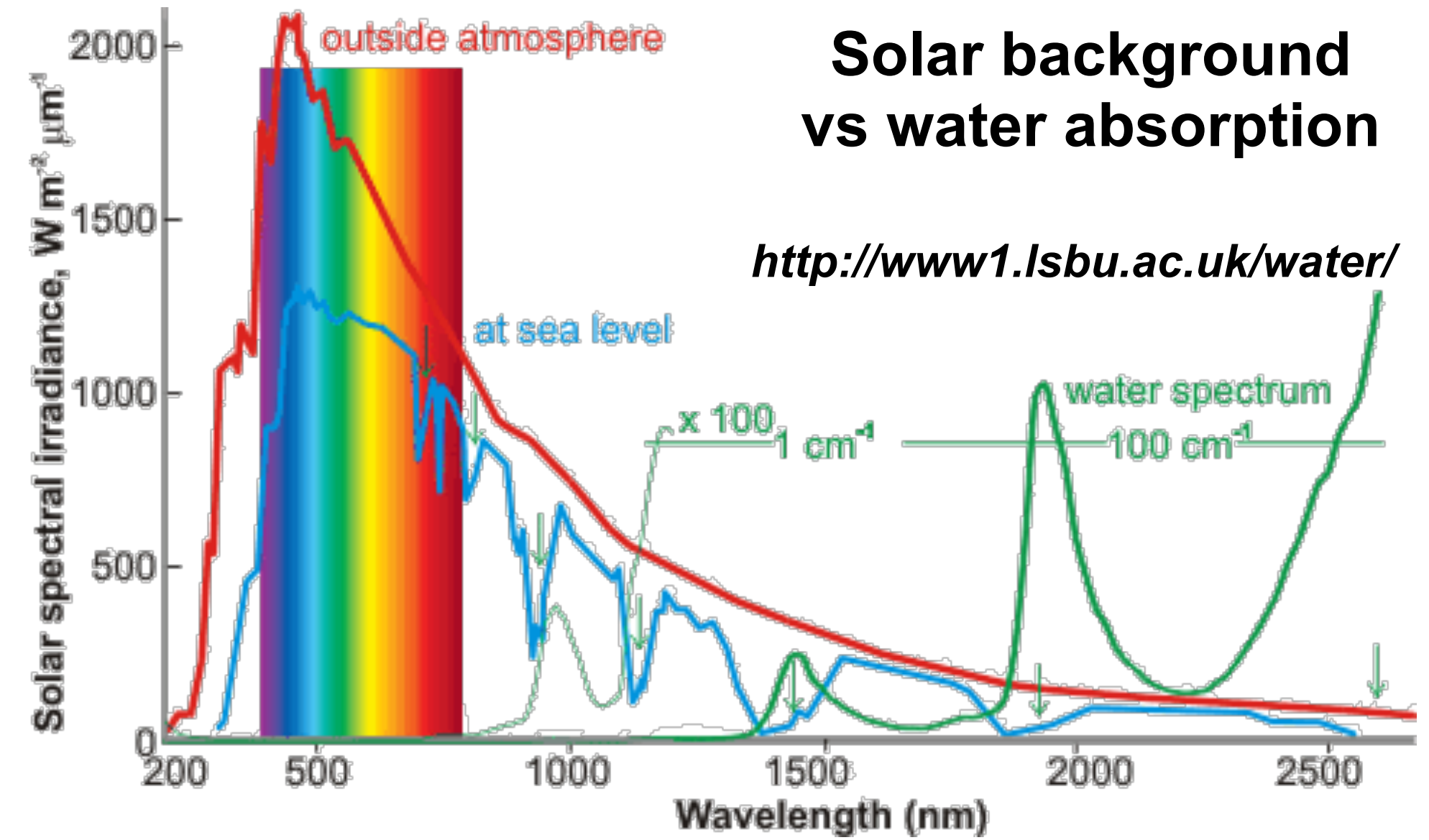
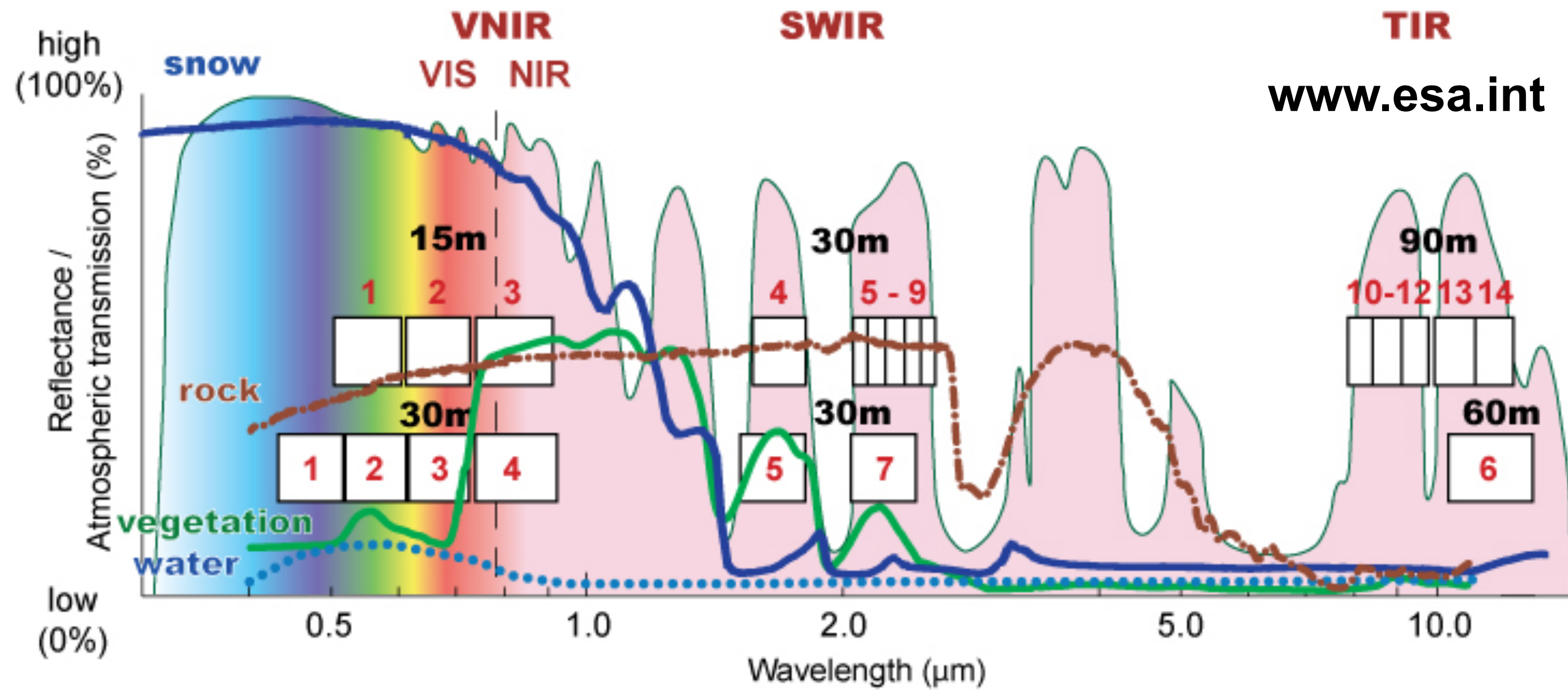
<https://youngcardriver.com/driving/driving-in-heavy-rain/>

- UK motorway or A-class road requirement: Level 4 autonomy requires identification of objects in 10 ms at 300 m
- Military rangefinders & lidar \$803.4M by 2023 with 6.29% CAGR (Reuters 2018)
- UK market for autonomous vehicle lidar, radar & GPS of £2.7Bn (£63Bn globally) by 2035 (UK Dept. Transport 2016)

# Longer Wavelengths

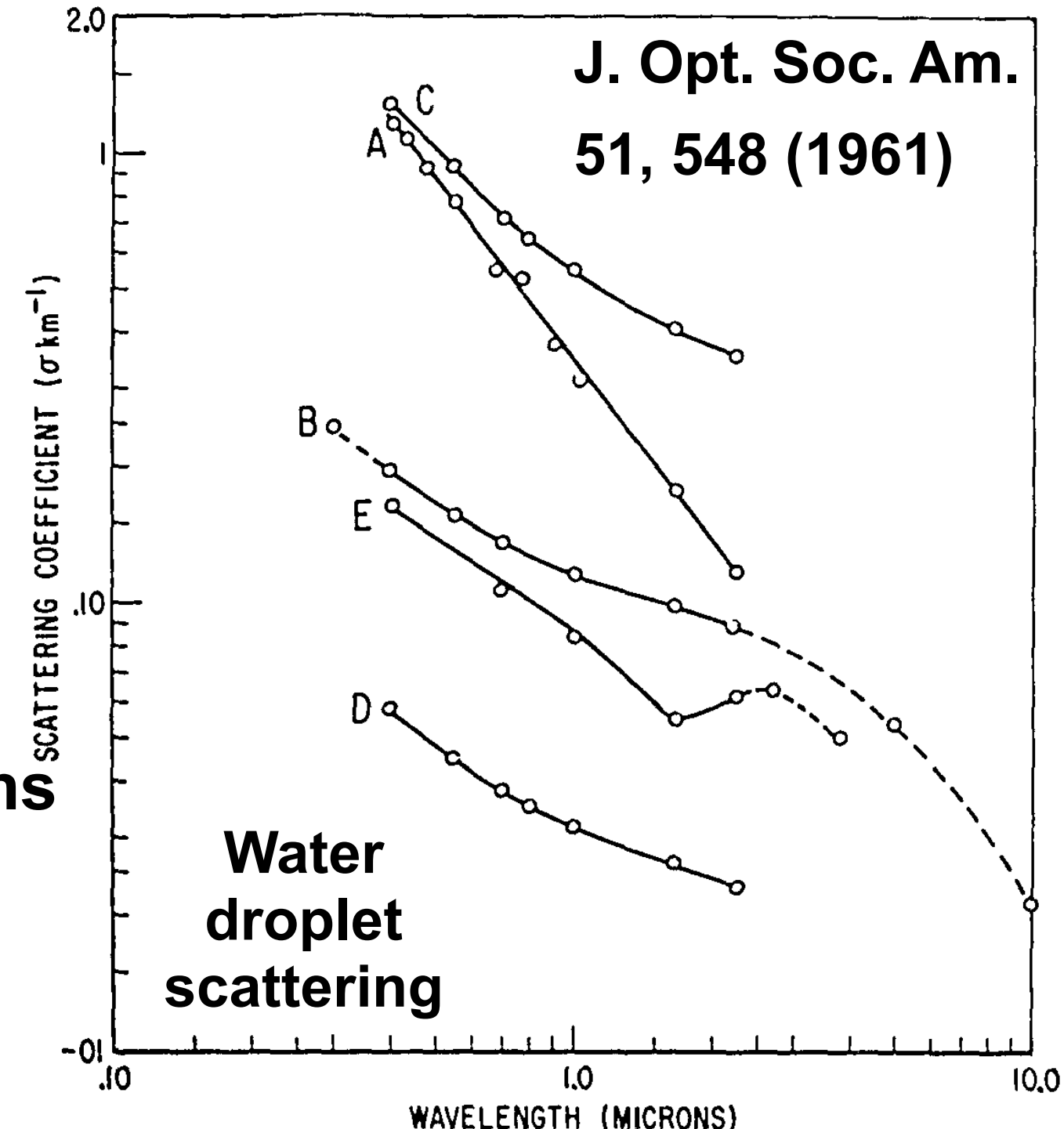


www.esa.int



Solar background vs water absorption

<http://www1.lsbu.ac.uk/water/>

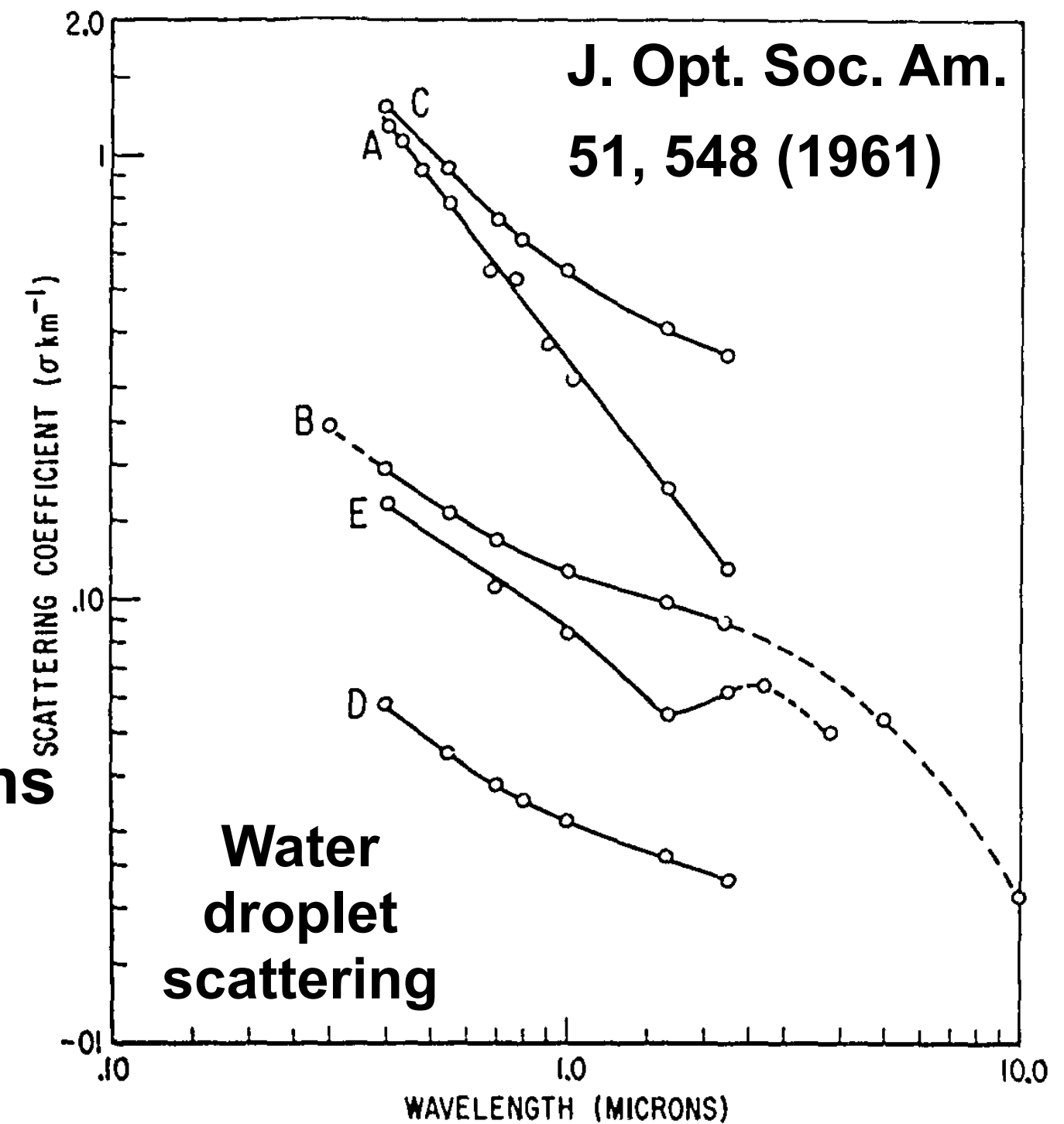
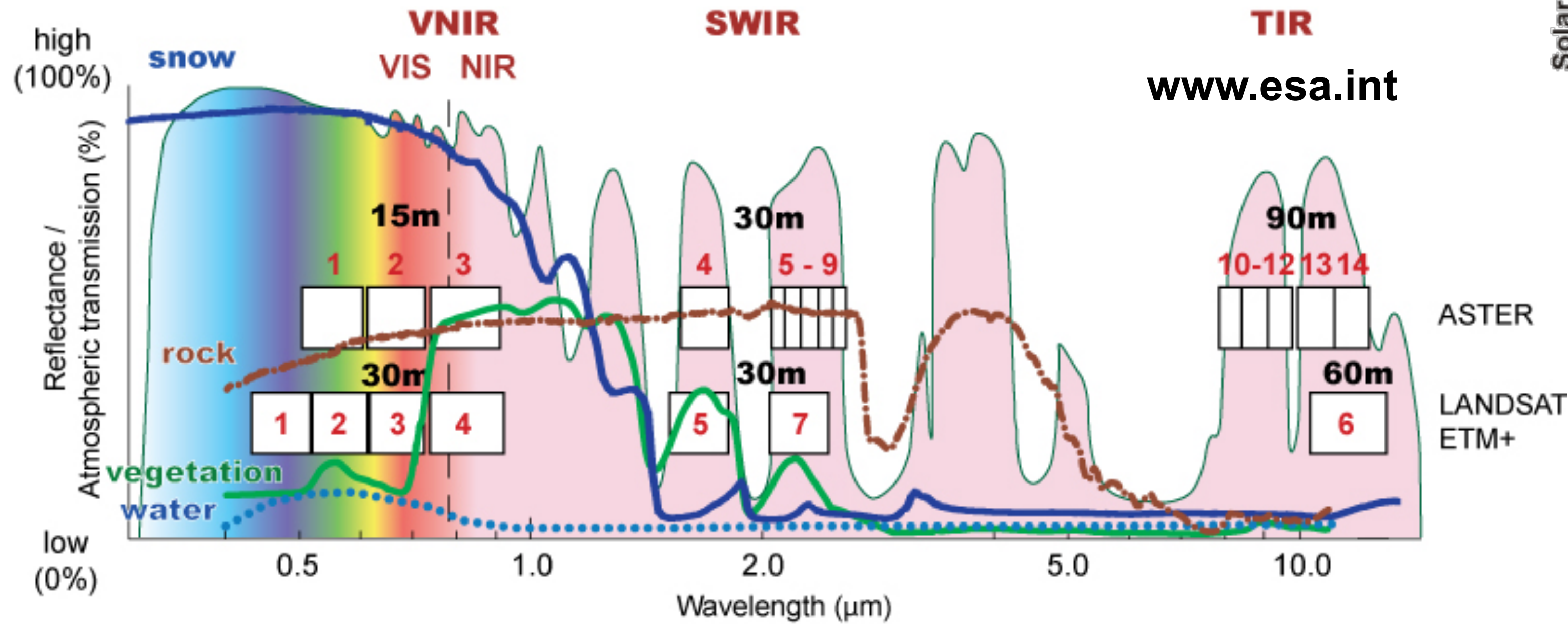
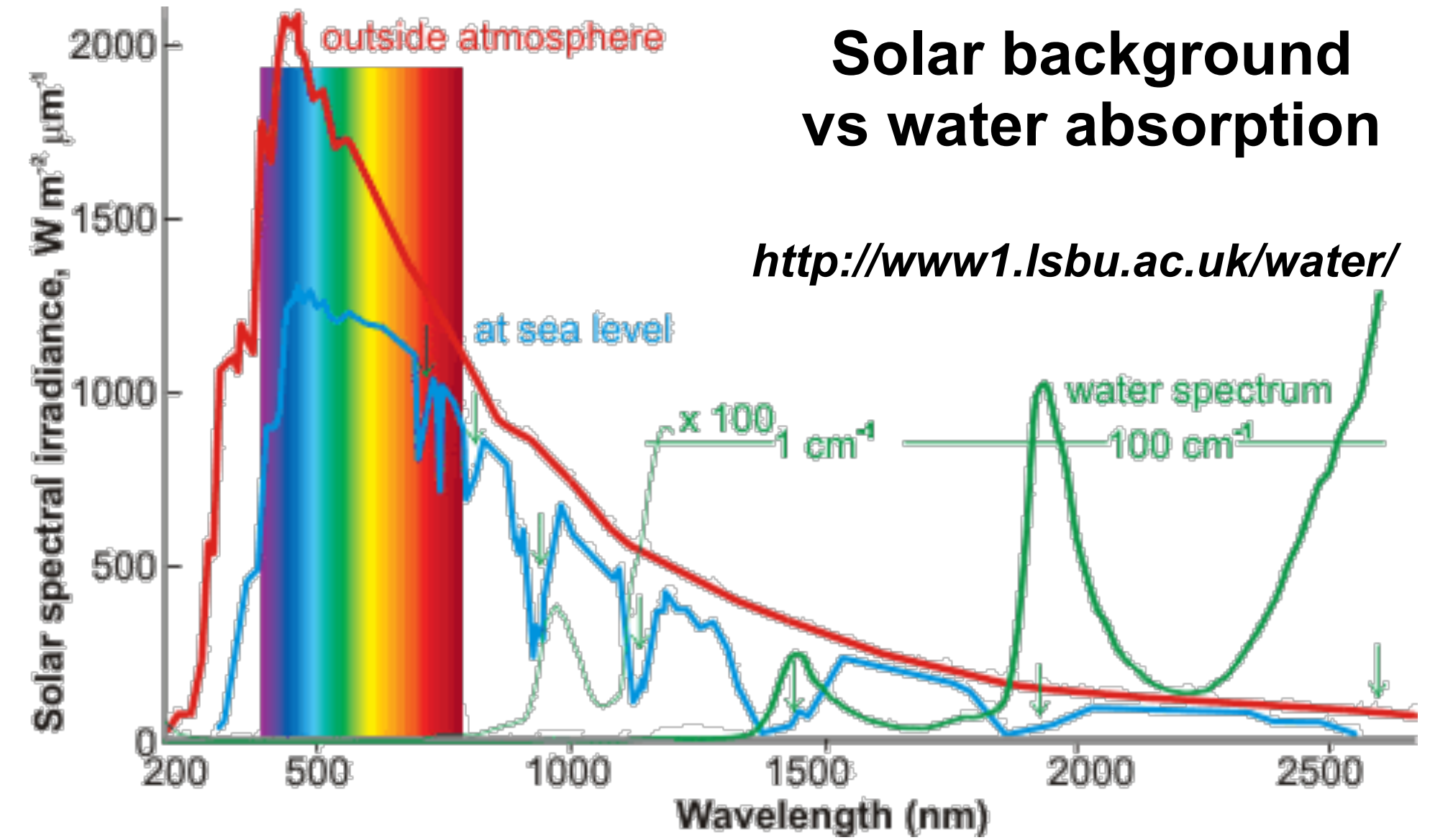
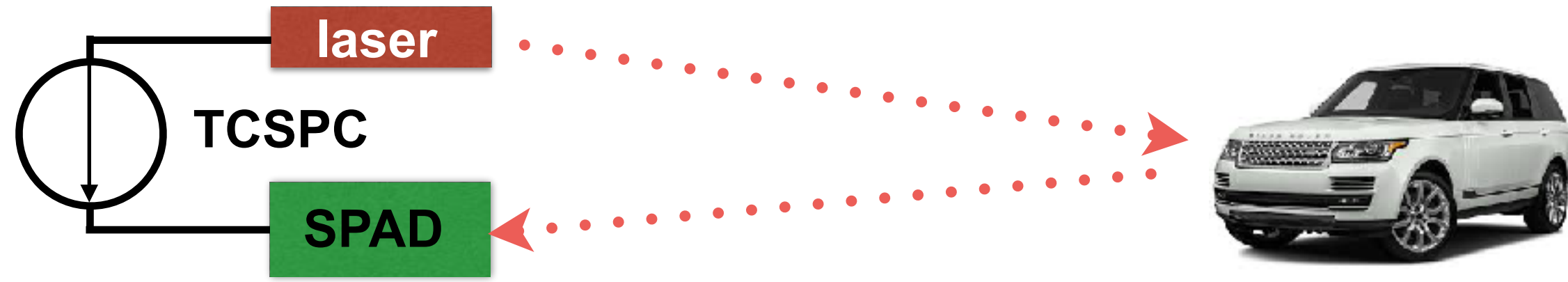


J. Opt. Soc. Am. 51, 548 (1961)

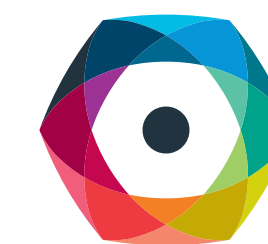
- Mie scattering from water droplets & solar background reduce at longer wavelengths
- IEC-60825-1 eye safe ~ 8 mW > 1400 nm wavelength – outside retina hazard region



# Longer Wavelengths



- Mie scattering from water droplets & solar background reduce at longer wavelengths
- IEC-60825-1 eye safe  $\sim 8$  mW  $> 1400$  nm wavelength – outside retina hazard region



RGB photograph

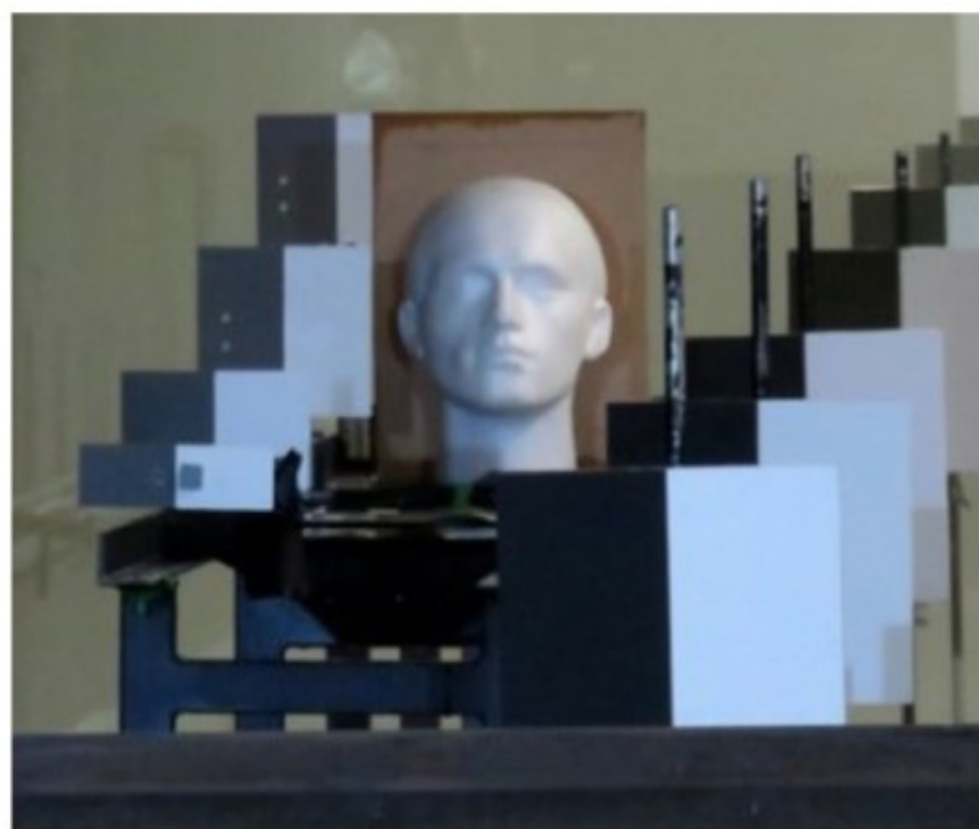
Cross-Correlated Depth profiles

Cross-Correlated Intensity profiles

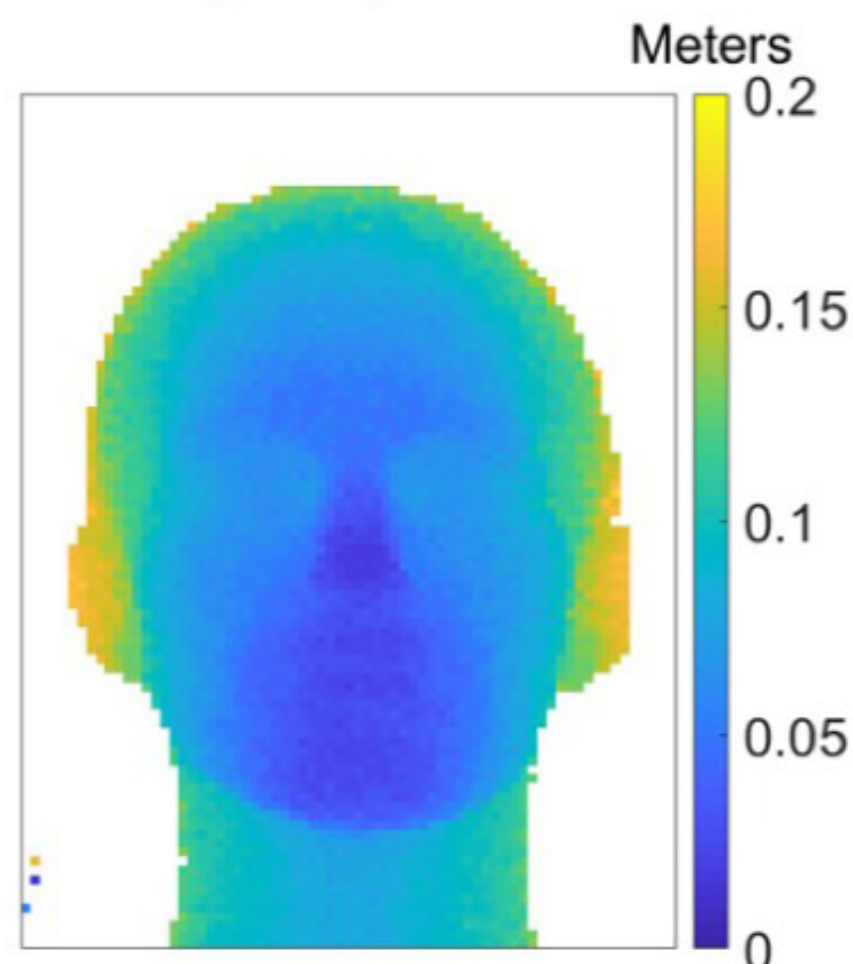
(a)

White Canister Smoke

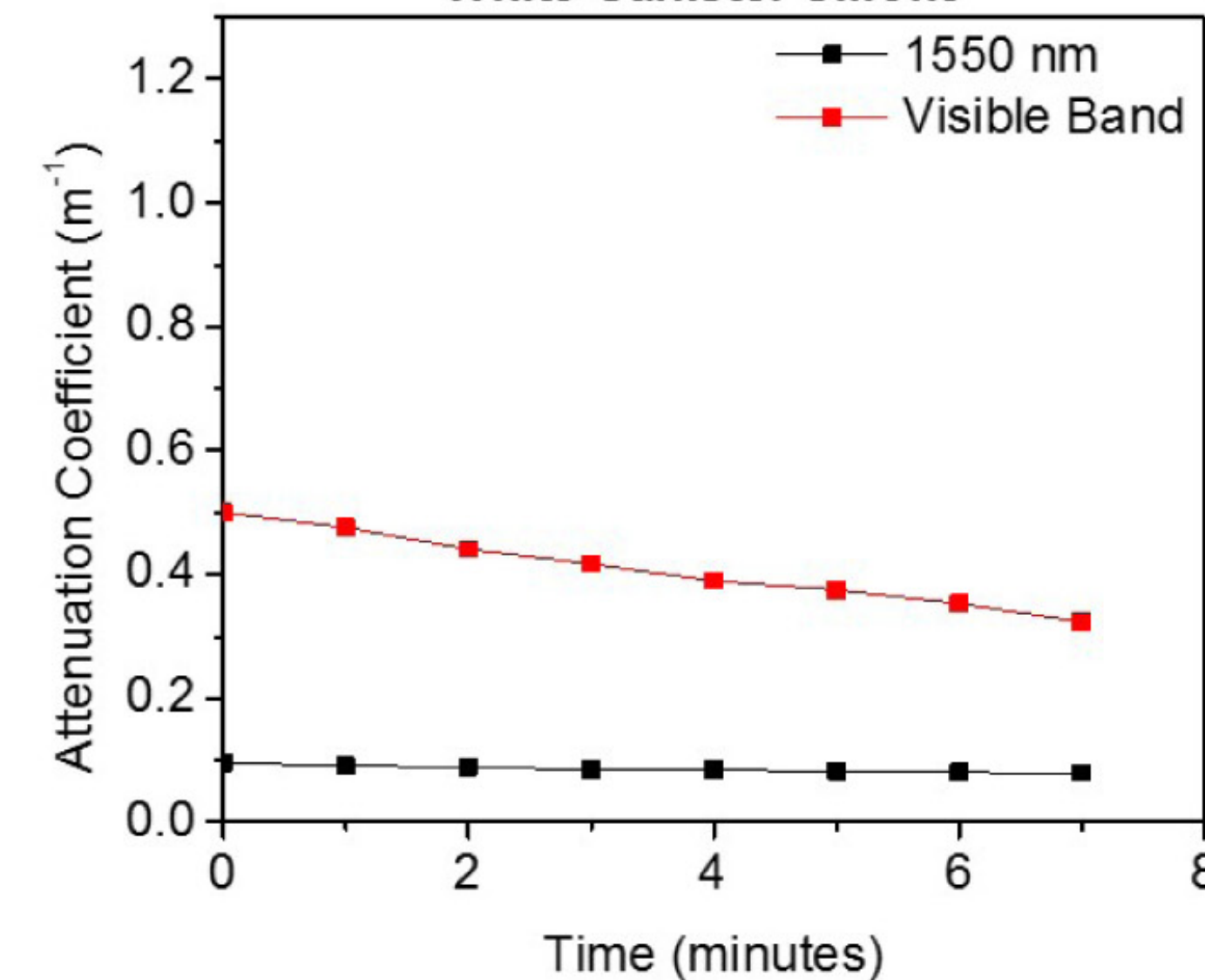
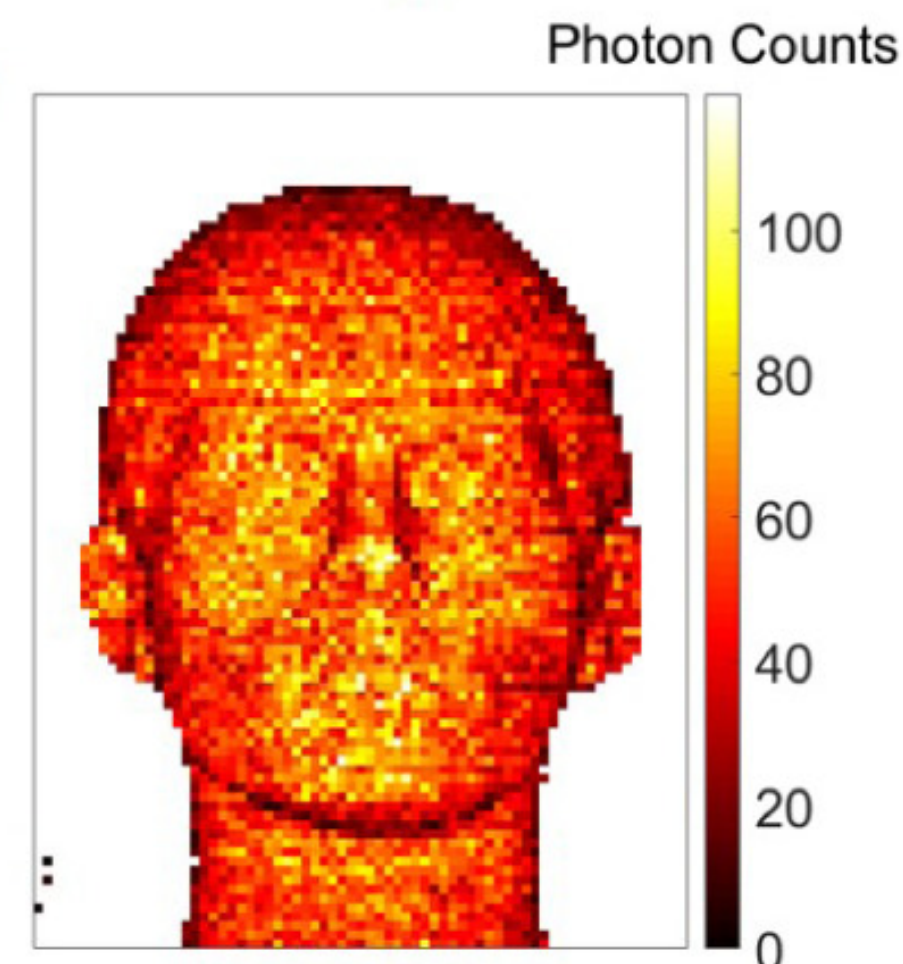
(a)



(b)



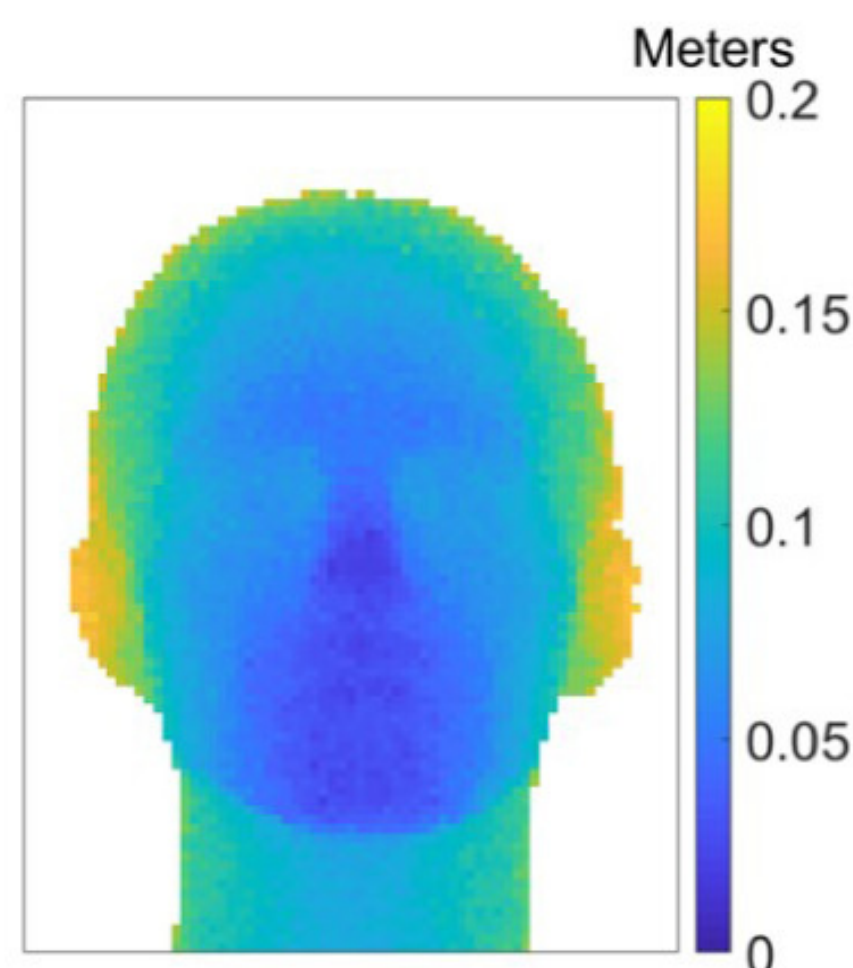
(c)



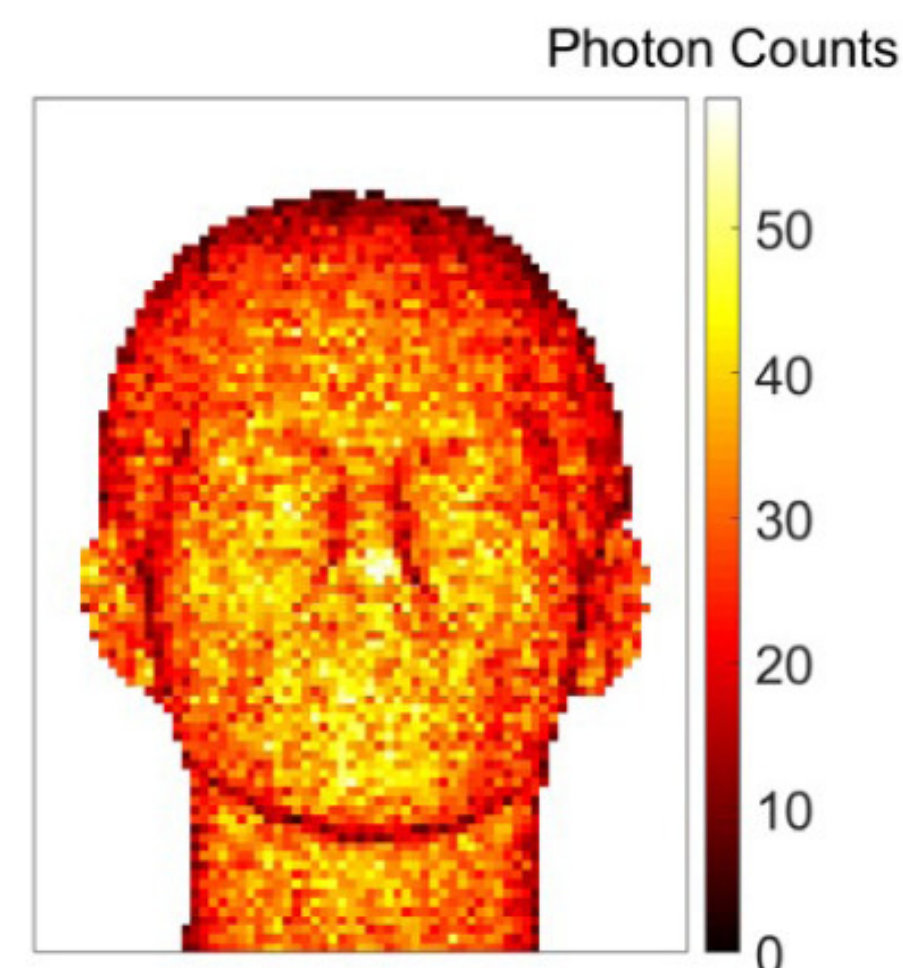
(d)



(e)



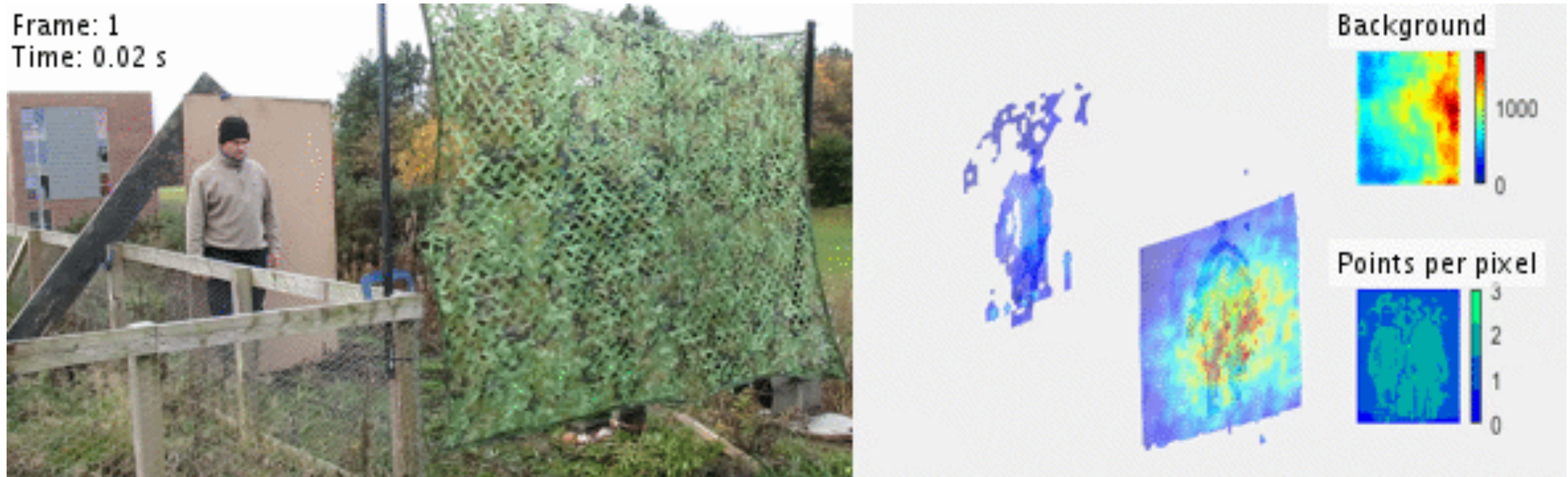
(f)



- 1.5 mW laser at 1550 nm
- Princeton Lightwave SWIR SPAD camera at £150k
- $f = 200$  mm lens, 3 ms / pixel
- 12 attenuation lengths in visible  
2.4 attenuation lengths at 1550 nm

1550 nm 3D images at 24 m through smoke

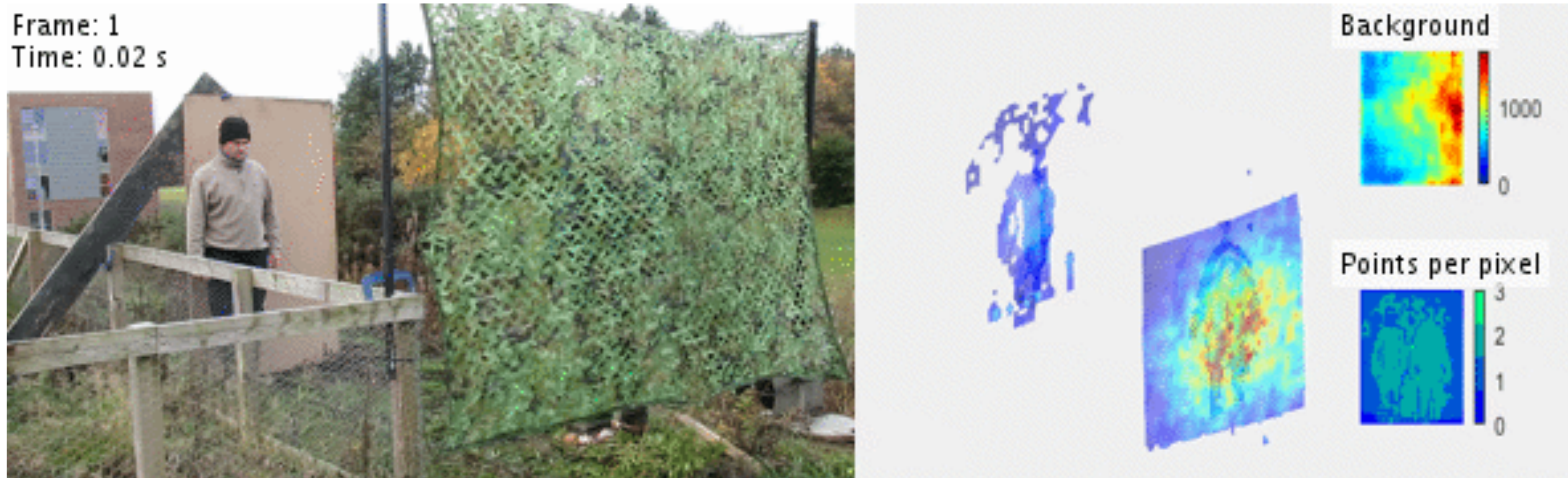
# Real Time Reconstruction of Multi-Surface Moving Scenes using Single-Photon Detection at 330 Meters Range



- Multiple surfaces resolved – more than one surface per pixel, on average
- 50 grayscale frames per second of 32 x 32 pixels at 1550 nm
- Real-time processing
- Eye-safe illumination in presence of solar background

J. Tachella, et al. "Real-time 3D reconstruction of complex scenes using single-photon lidar: when image processing meets computer graphics" *Nature Comms.* 10, 4984 (2019)

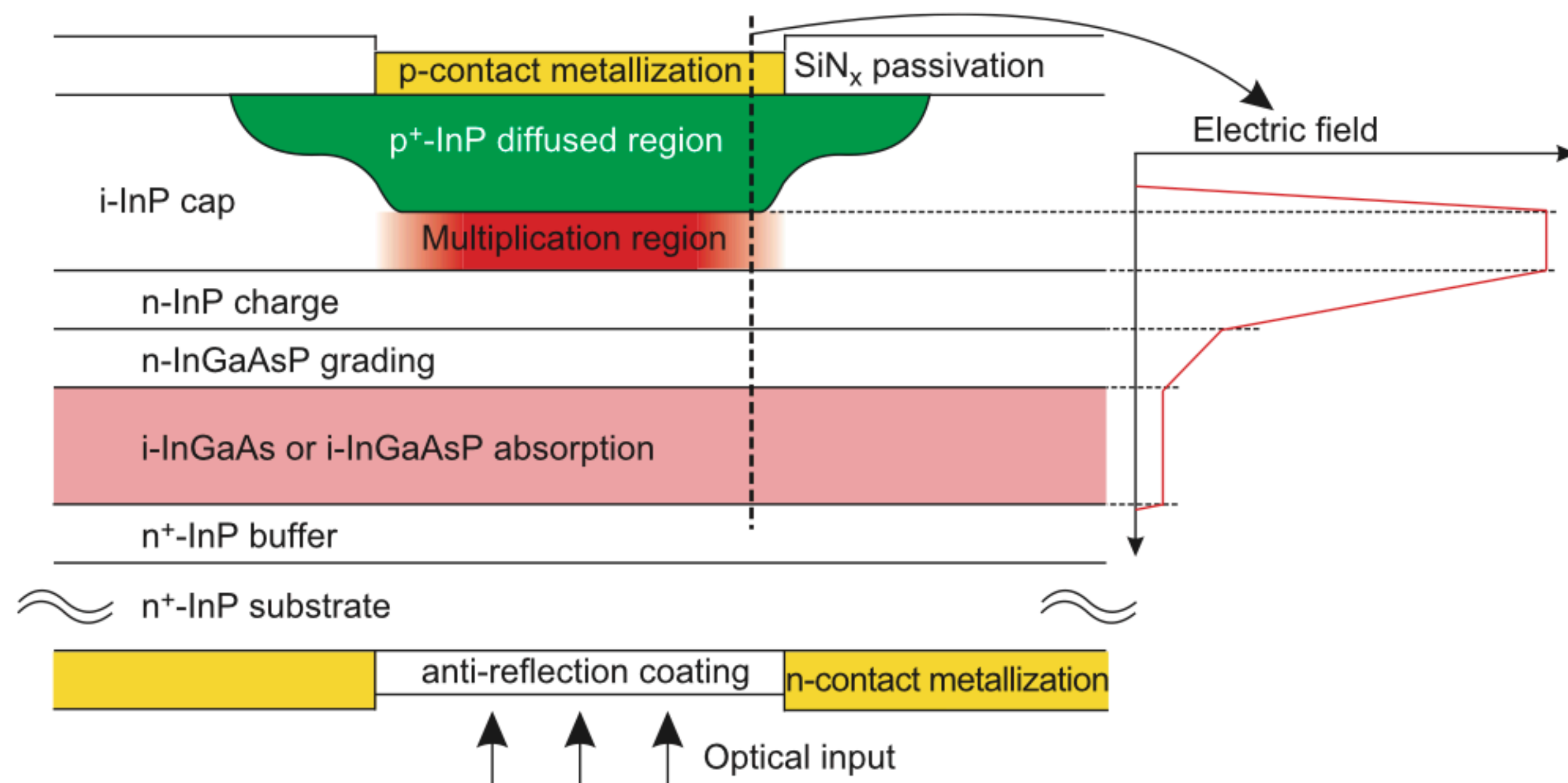
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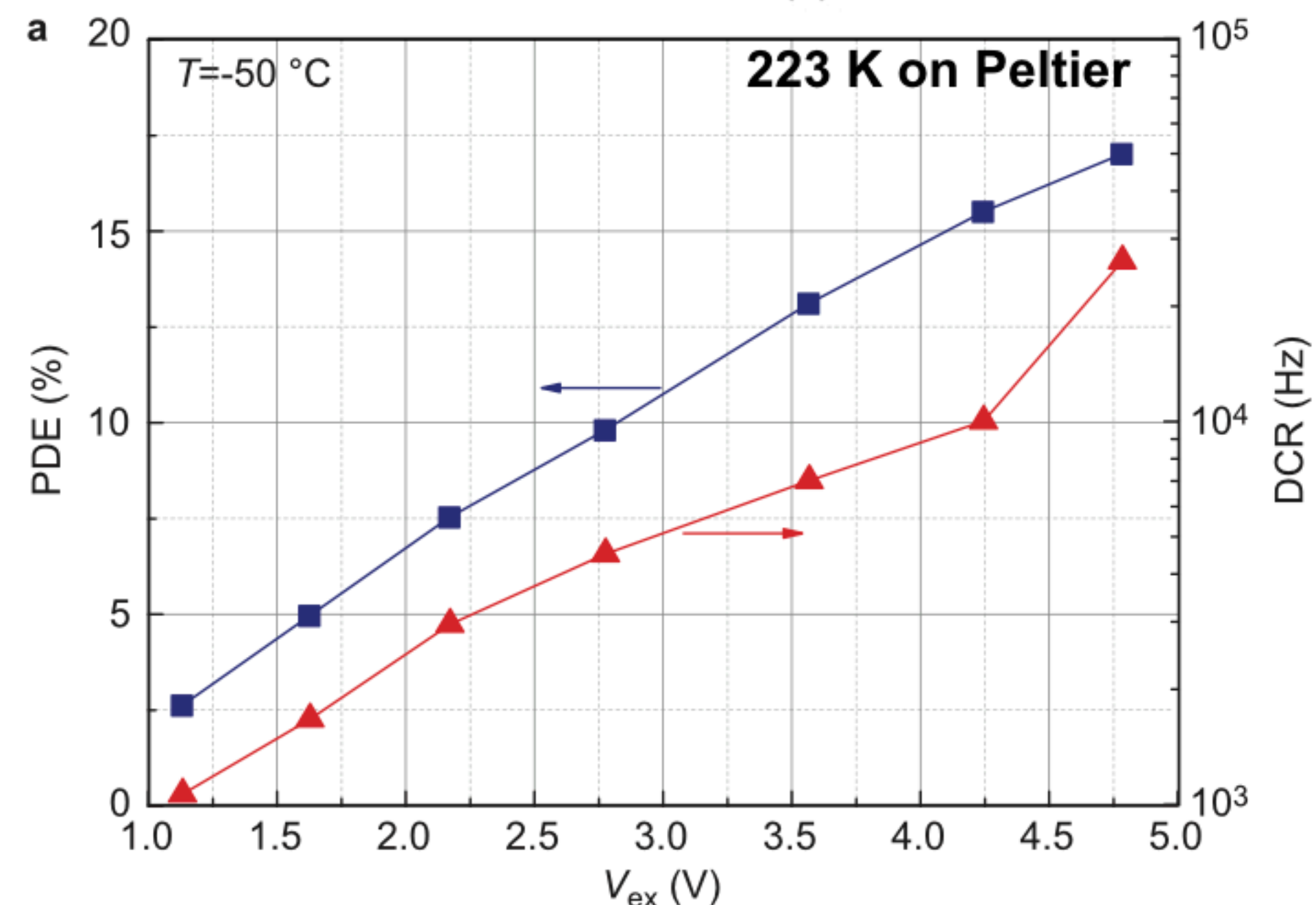
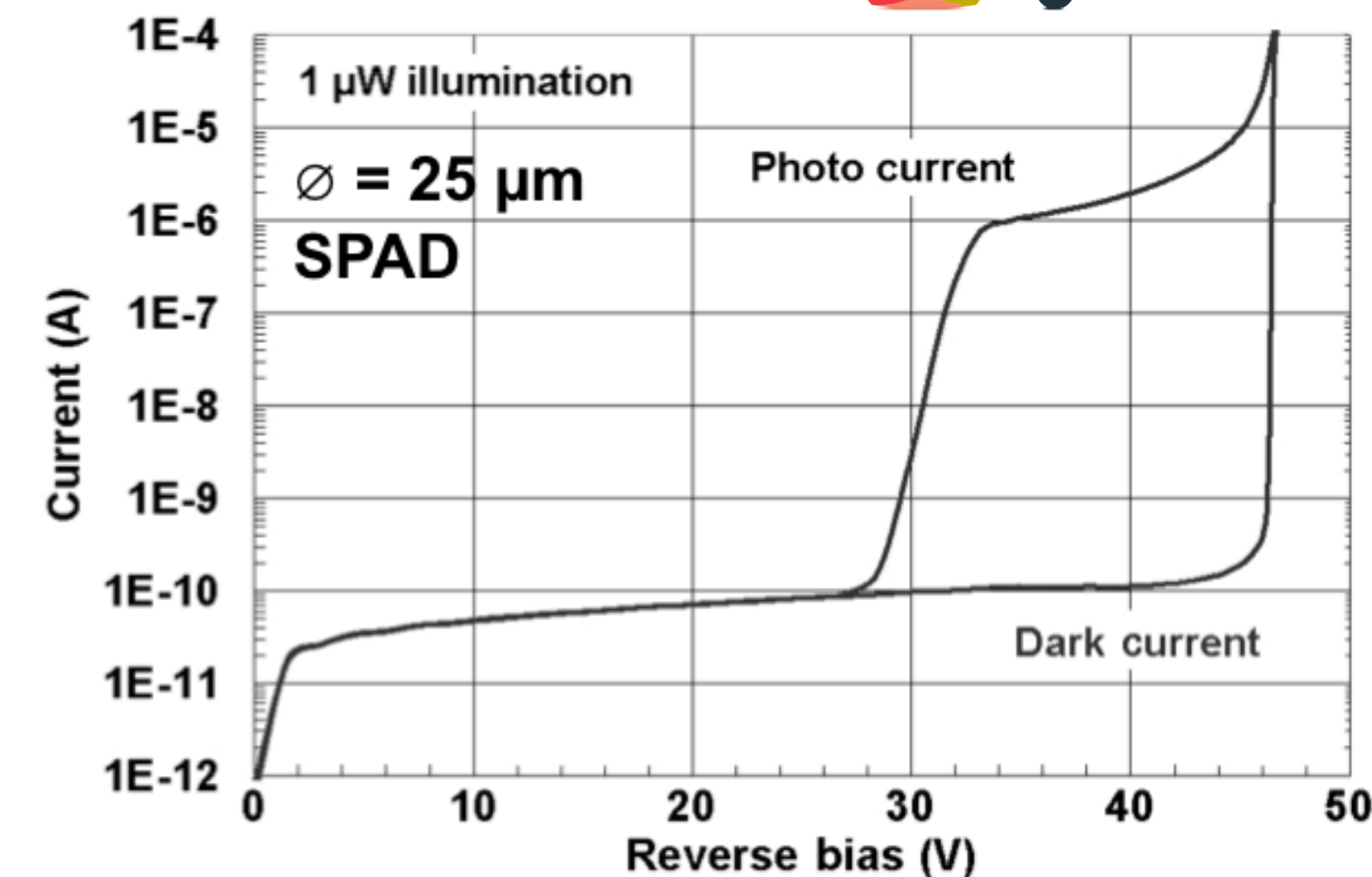
J. Tachella, et al. "Real-time 3D reconstruction of complex scenes using single-photon lidar: when image processing meets computer graphics" *Nature Comms.* 10, 4984 (2019)

- Princeton Lightwave (now Argo AI): significant funding over decades & commercial leader in InGaAs SPADs on InP



area =  $4.91 \times 10^{-10} \text{ m}^{-2}$   
 = x16 smaller than Ge on Si

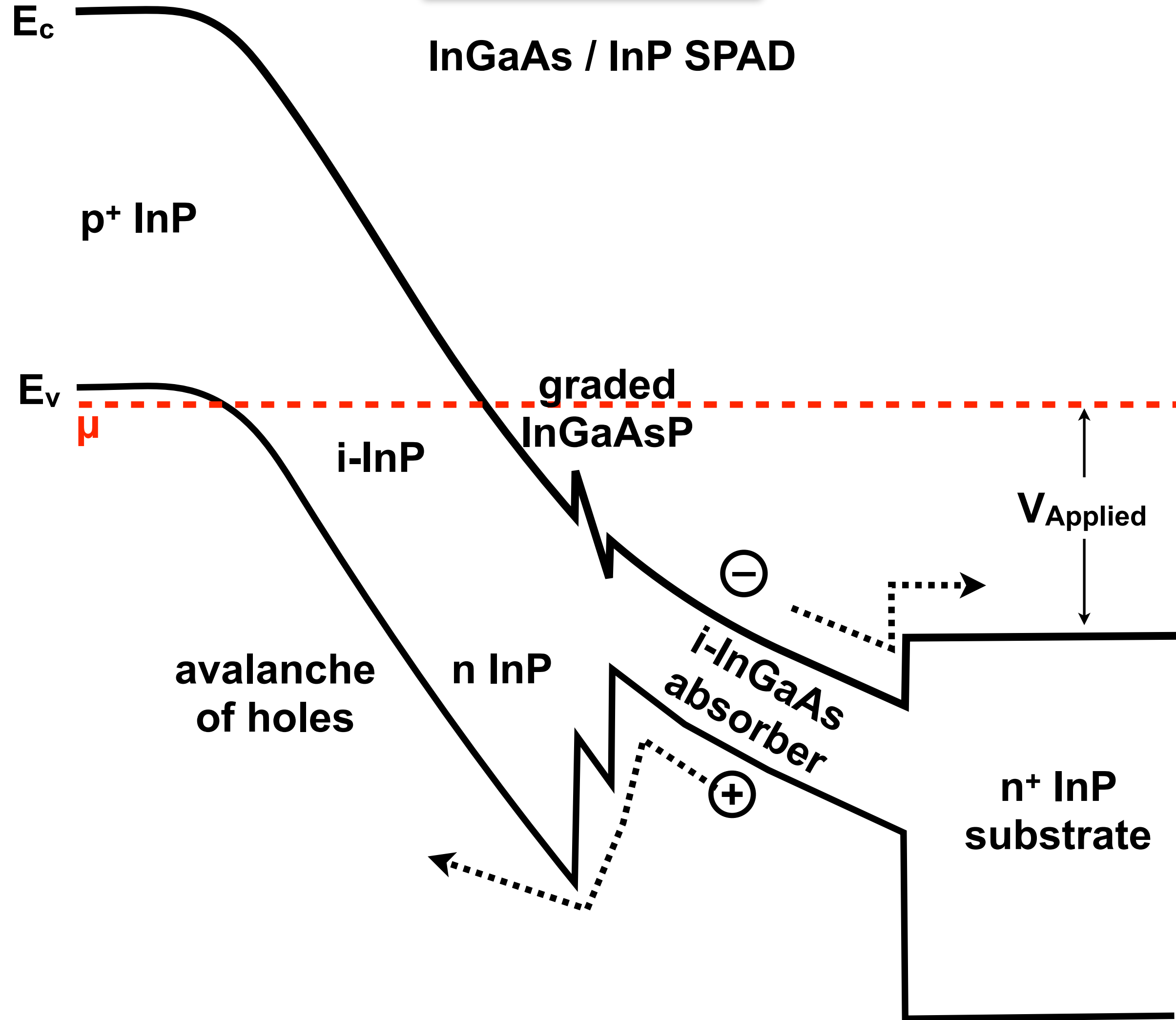
J. Zhang et al., Light Sci. App. 4, e286 (2015)



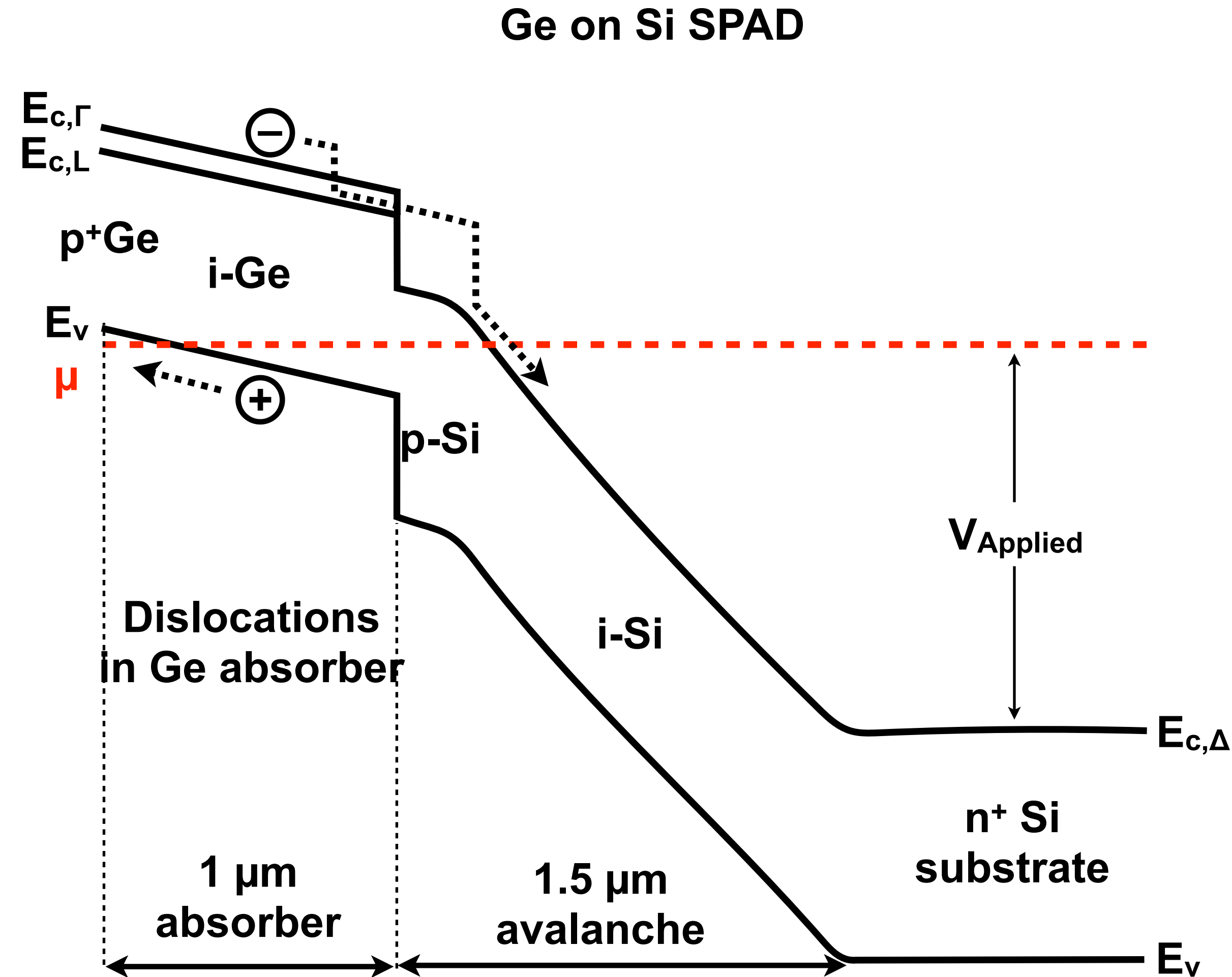
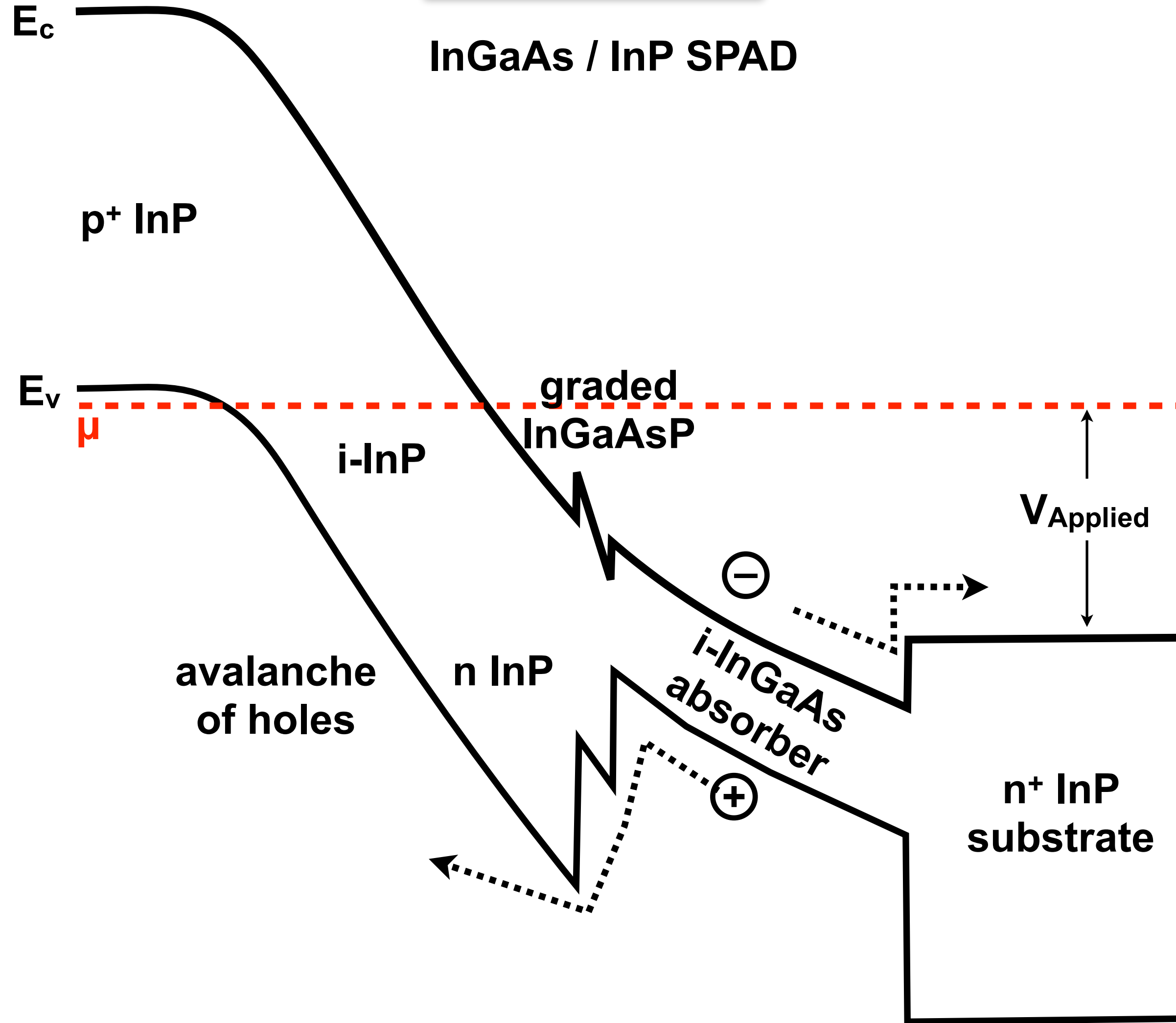
\$20k single pixel, \$150k for 32 x 32 camera



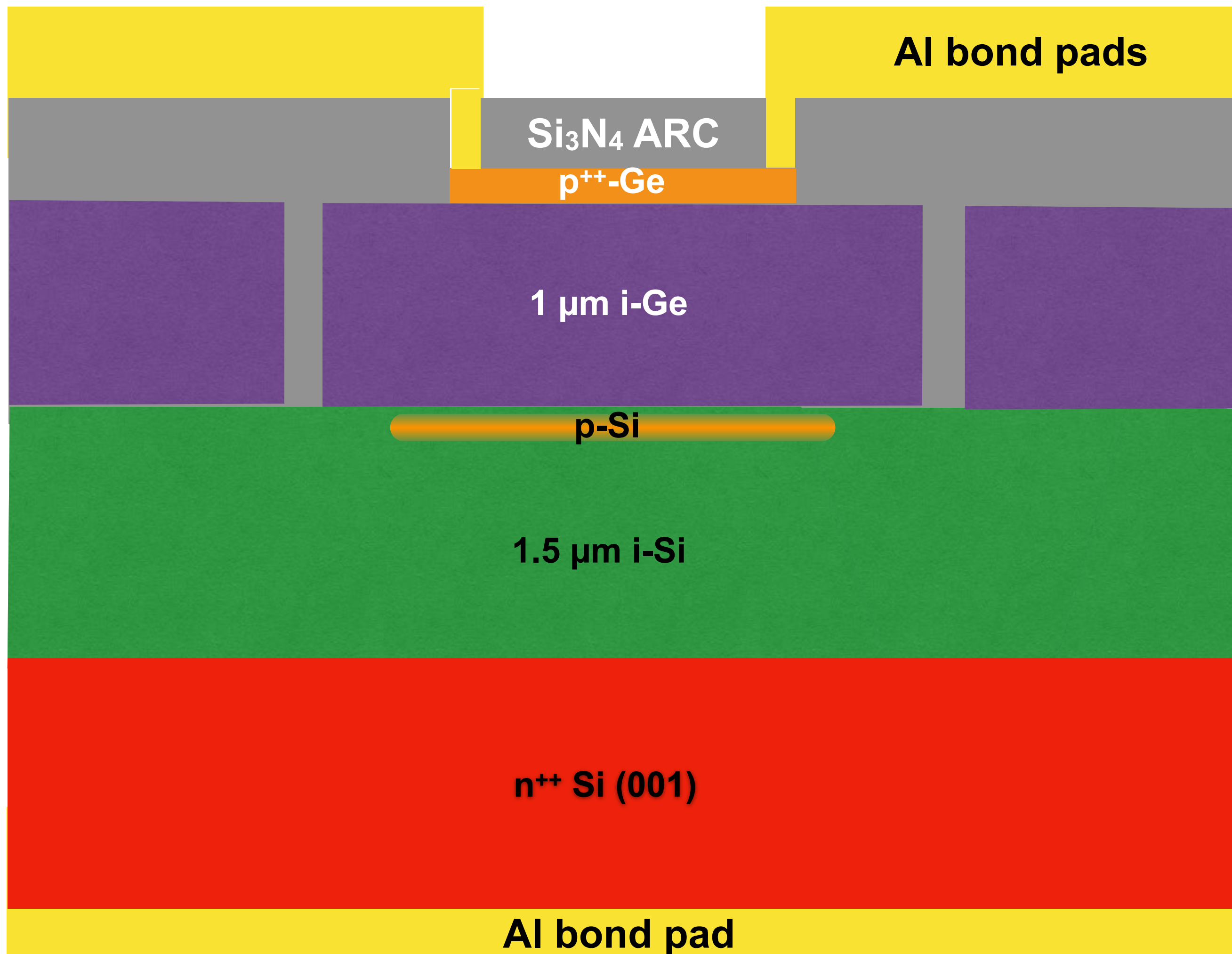
# Band Structure



# Band Structure



**Si has the best impact ionisation coefficients for any material**



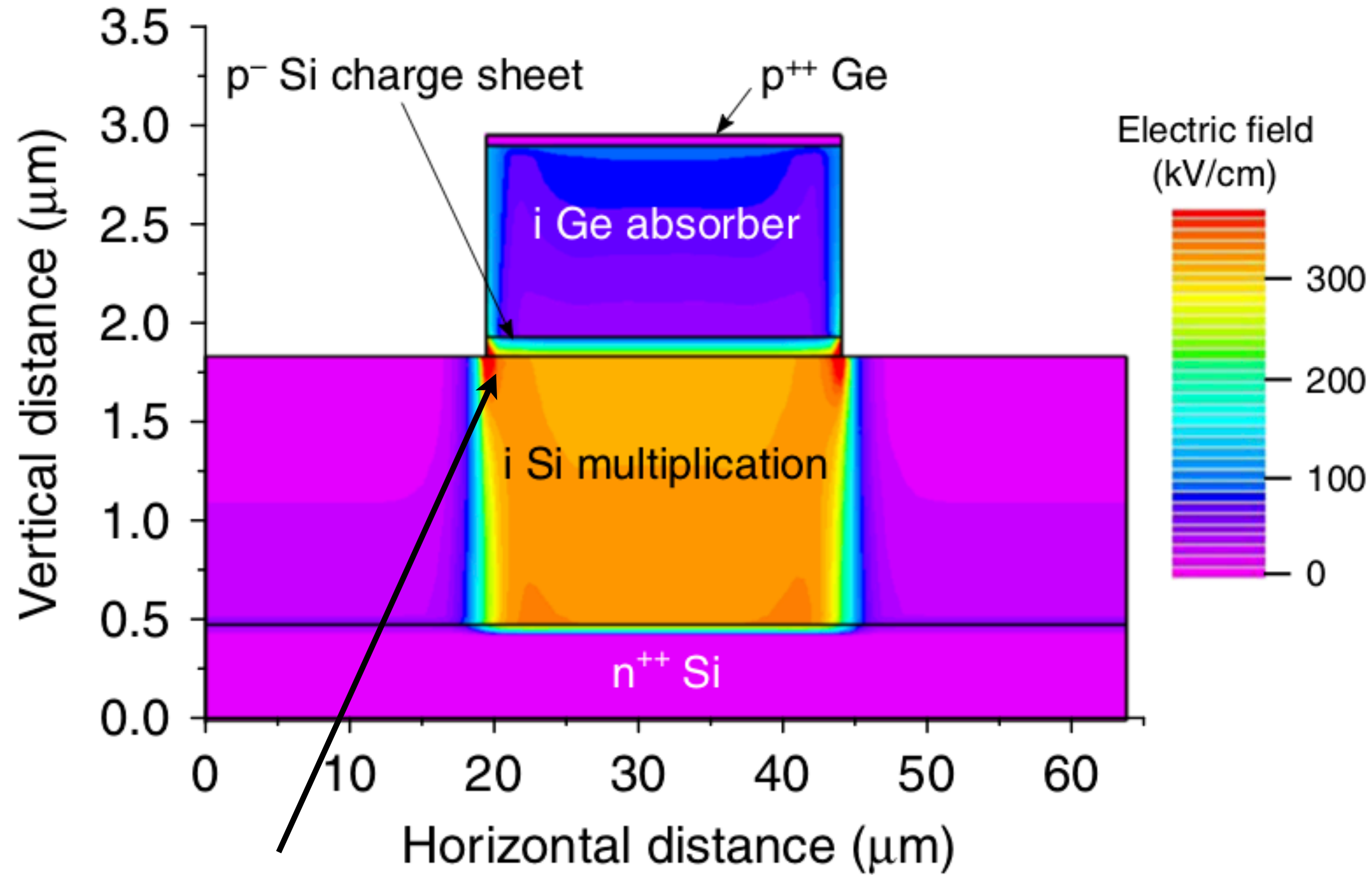
- ASM Epsilon 2000E LPCVD with 150 mm Si (001) wafers
- 1.5 μm i-Si epi for avalanche on n<sup>++</sup> Si
- Implant p<sup>-</sup> sheet charge layer
- 1 μm i-Ge absorber with 50 nm p<sup>++</sup>-Ge contact
- All silicon foundry compatible processing





Silvaco Athena TCAD

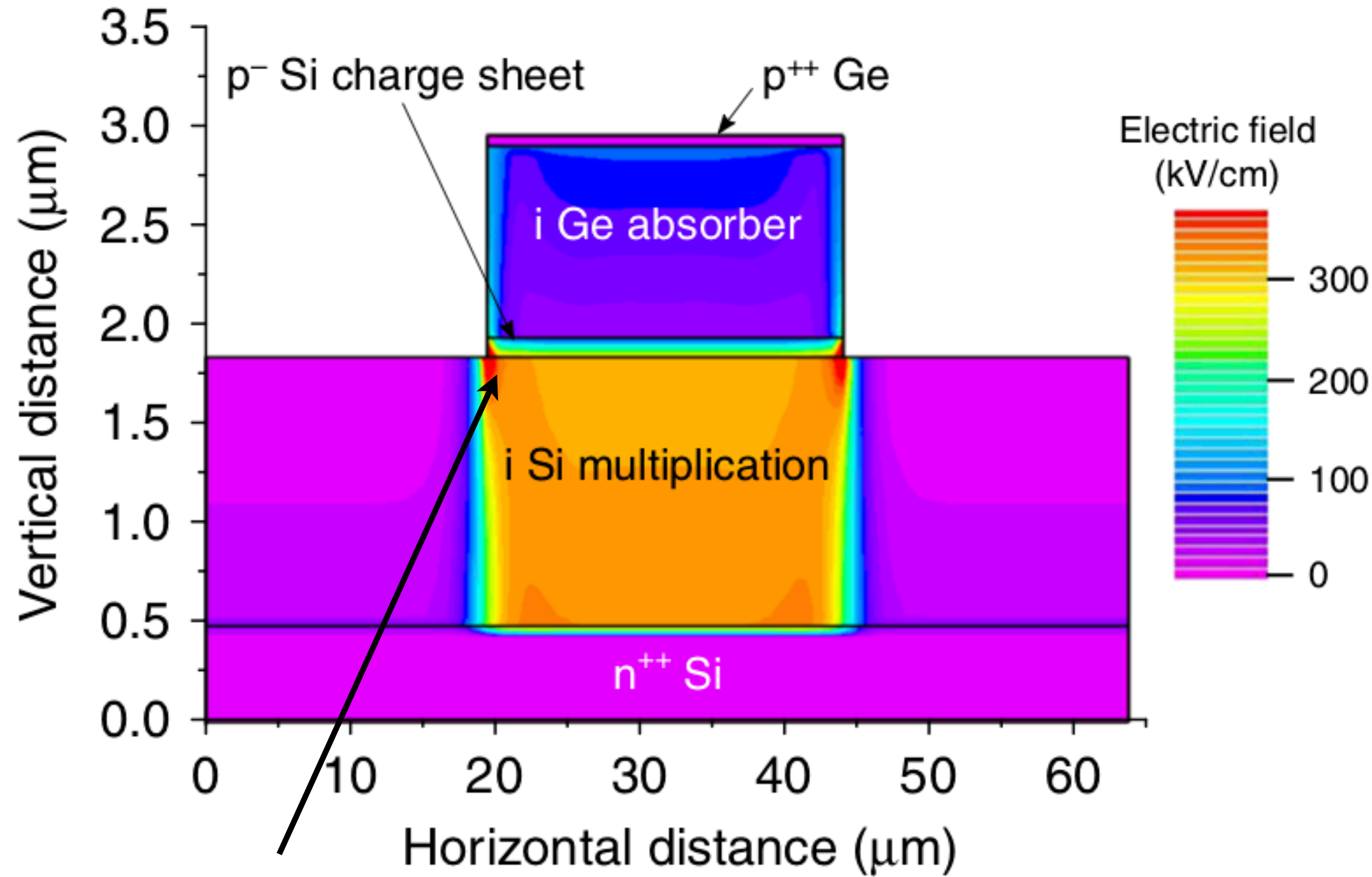
### Mesa device



**Hot spots  
increase DCR**

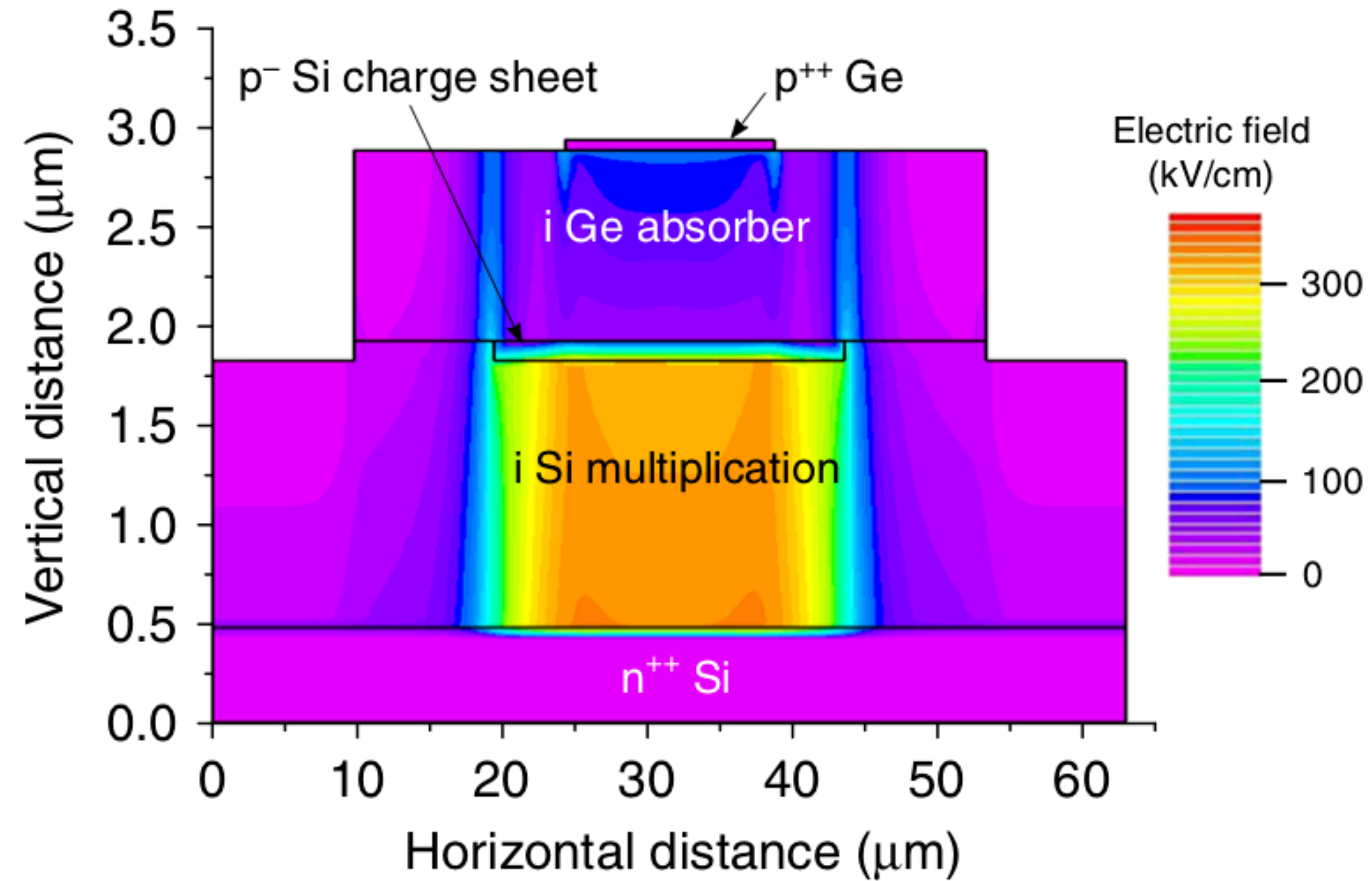
Silvaco Athena TCAD

**Mesa device**



**Hot spots  
increase DCR**

**Planar device**

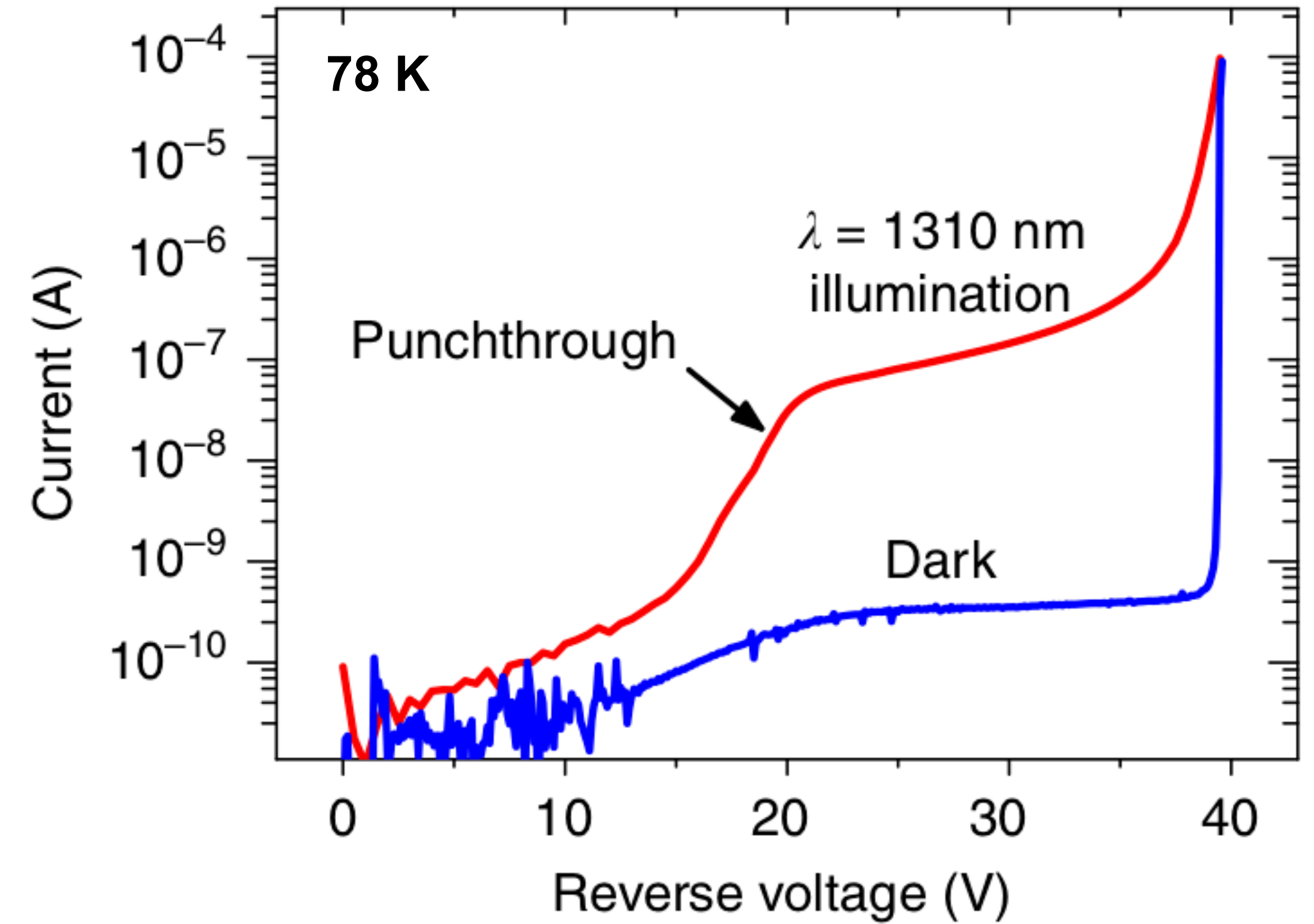
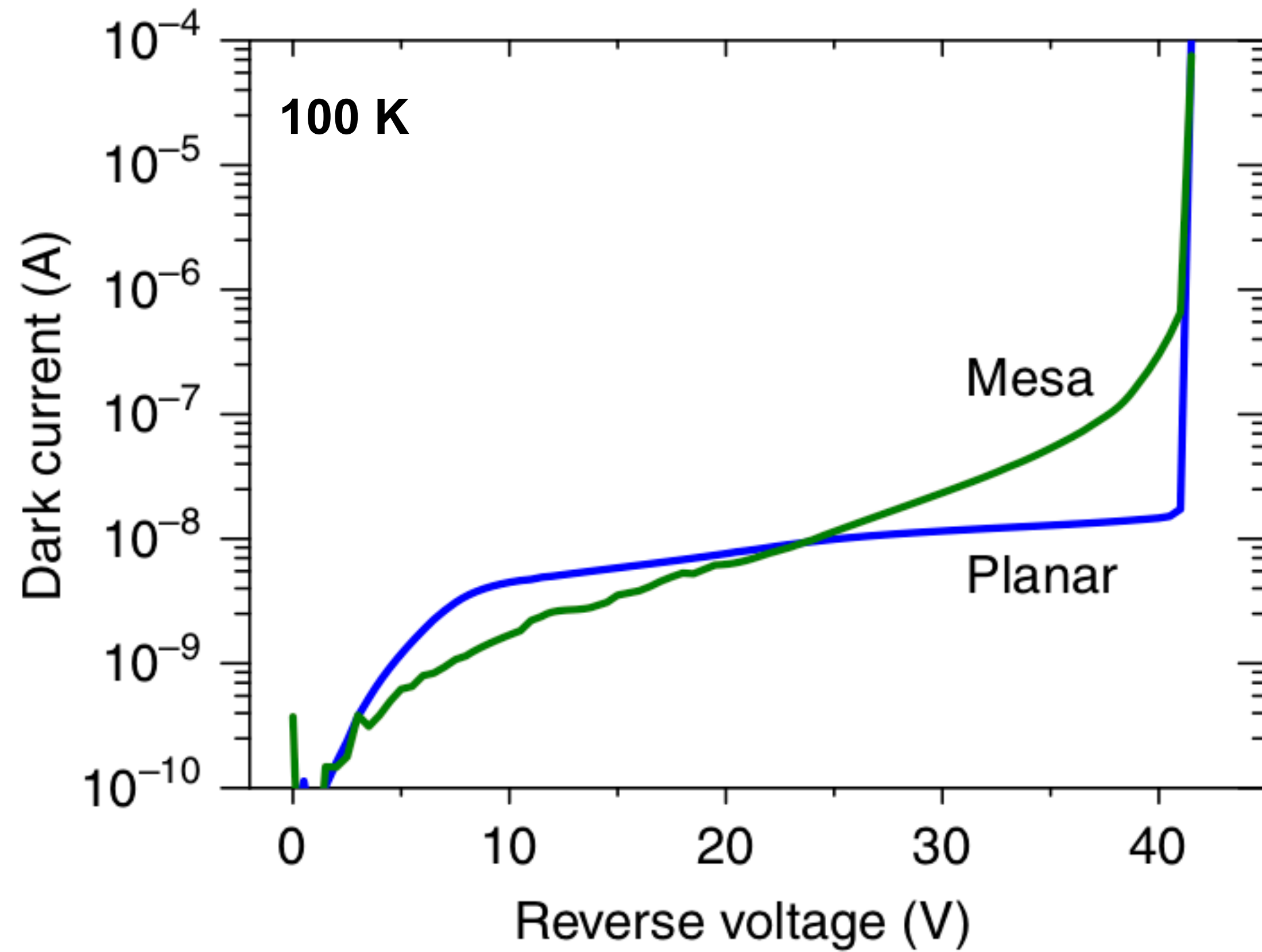


GB Patent application no. 1814688.6 (10<sup>th</sup> September 2018)



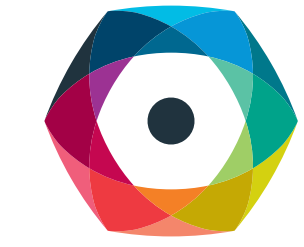
# Ge SPADs Planar vs Mesa

100  $\mu\text{m}$  diameter Ge on Si SPAD

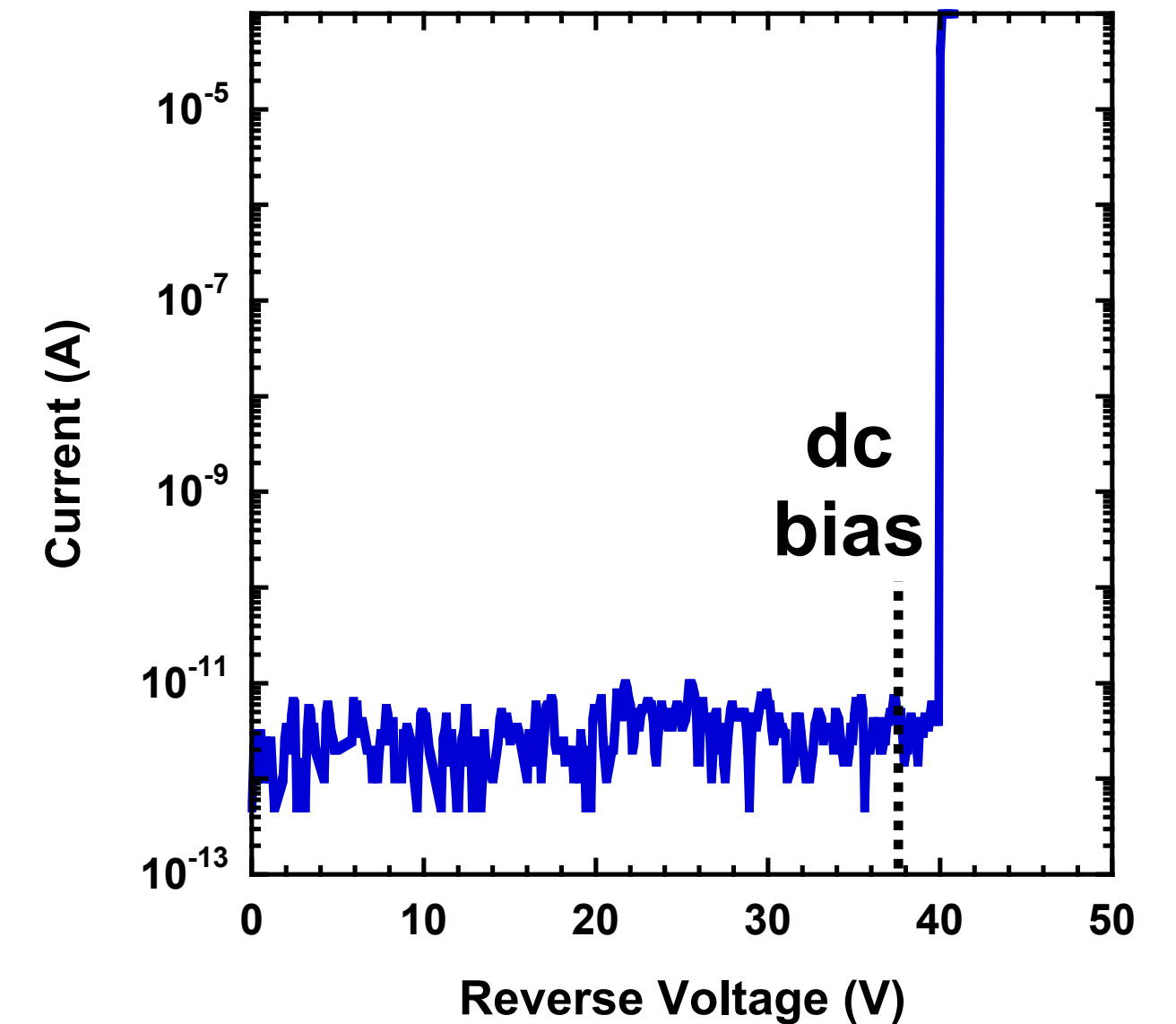
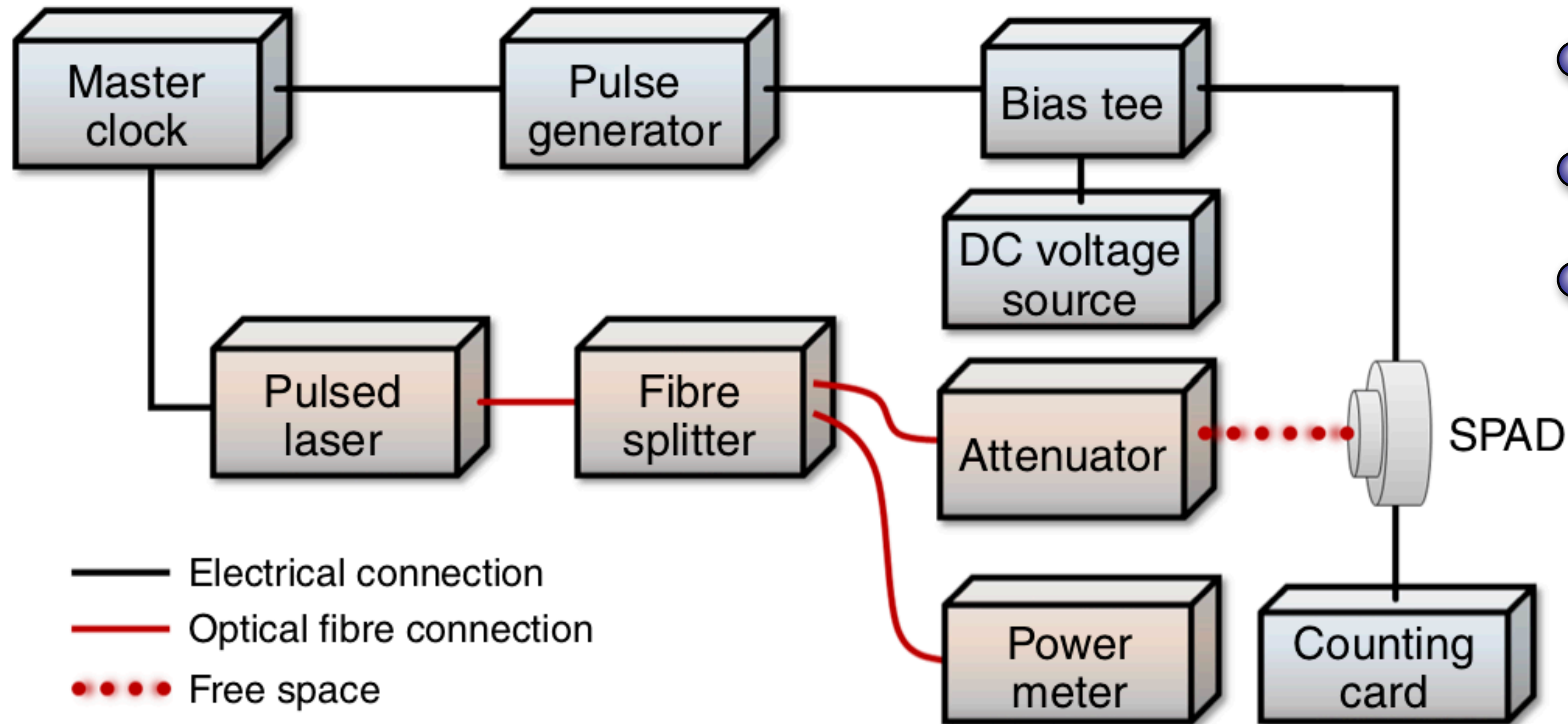




# Geiger Mode Measurements



- 50 ns detector gate at 1 kHz rep. rate
- Picoquant ps pulsed 1310 nm laser
- NKT ps supercontinuum laser
- Photon flux  $< 0.1$  photons / pulse
- 19.5 ps timing bin for jitter measurements

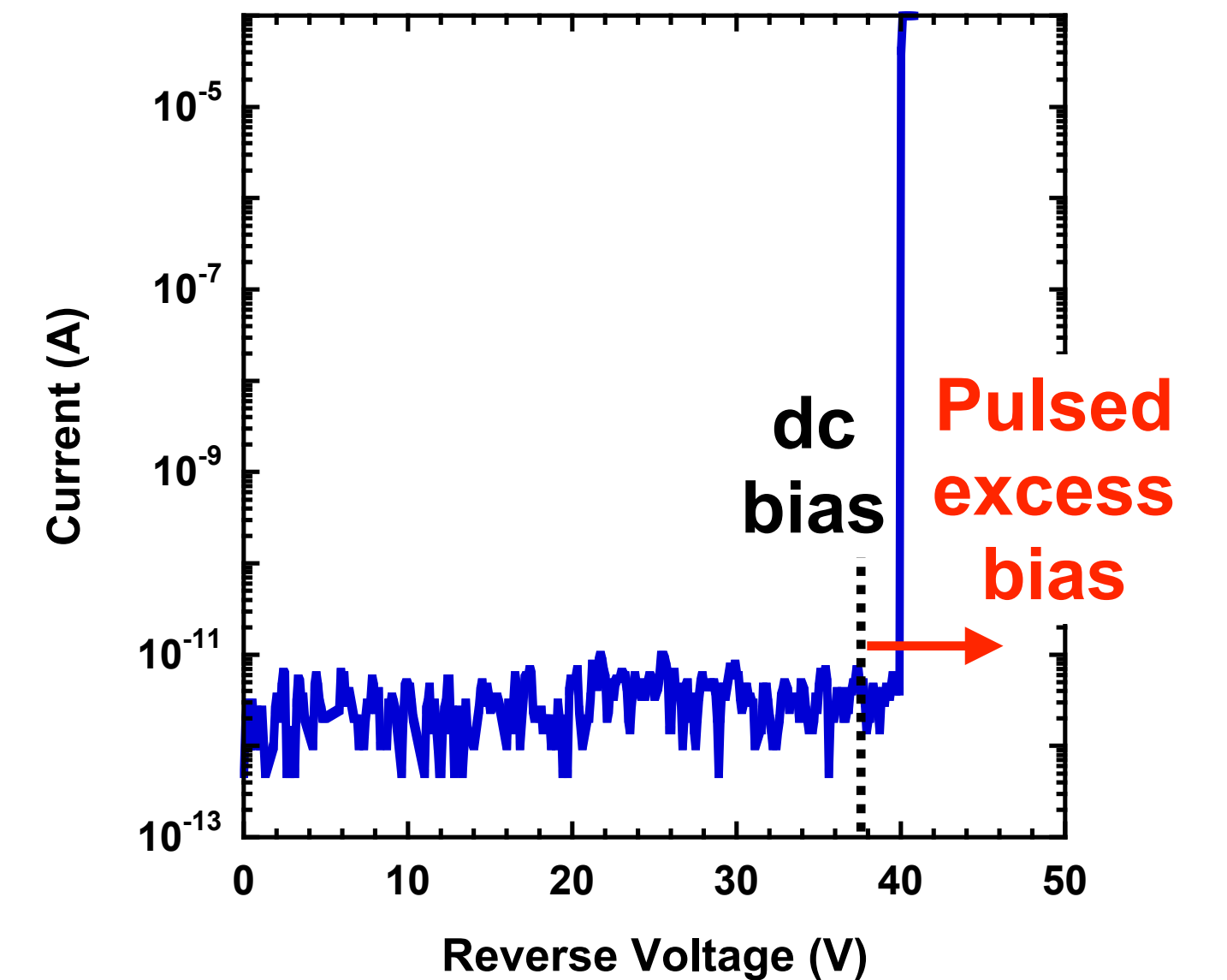
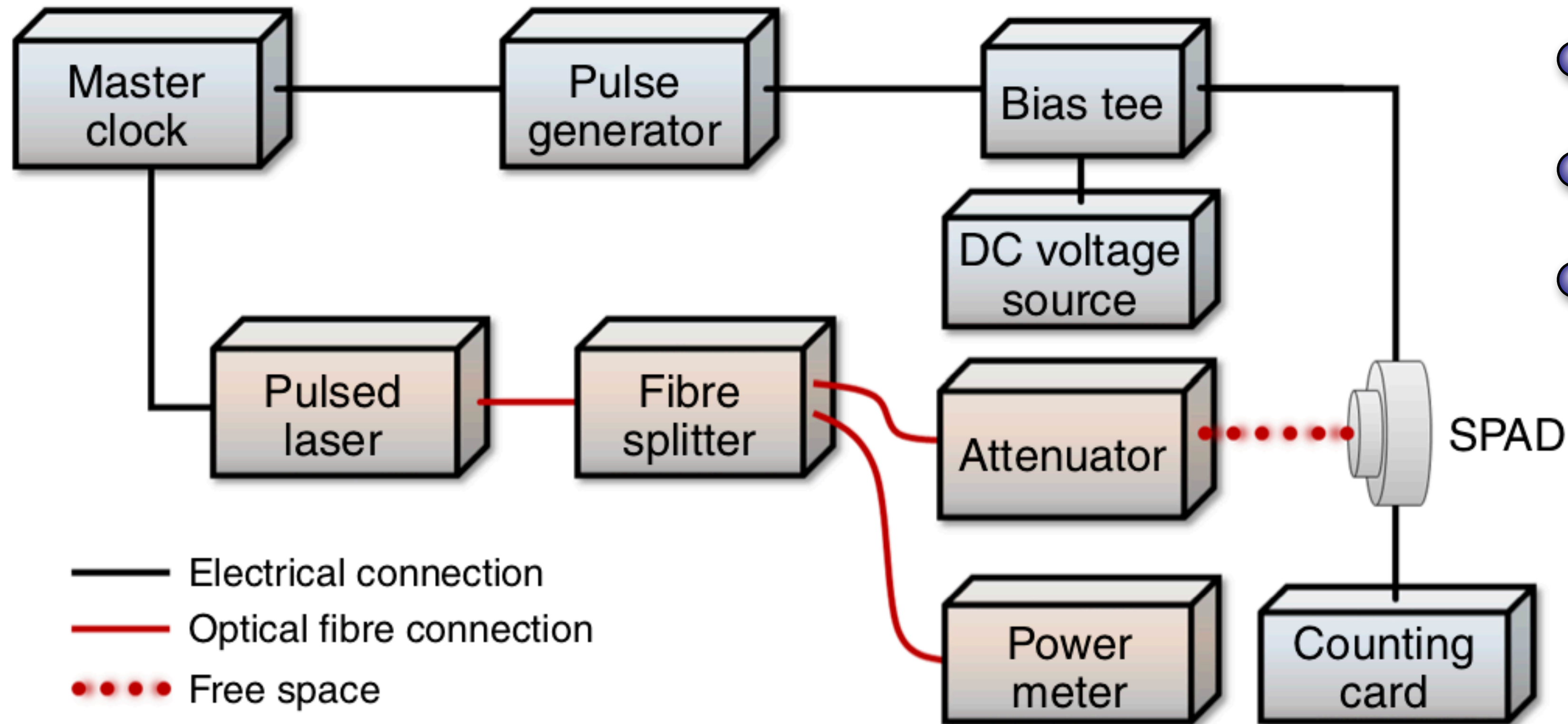




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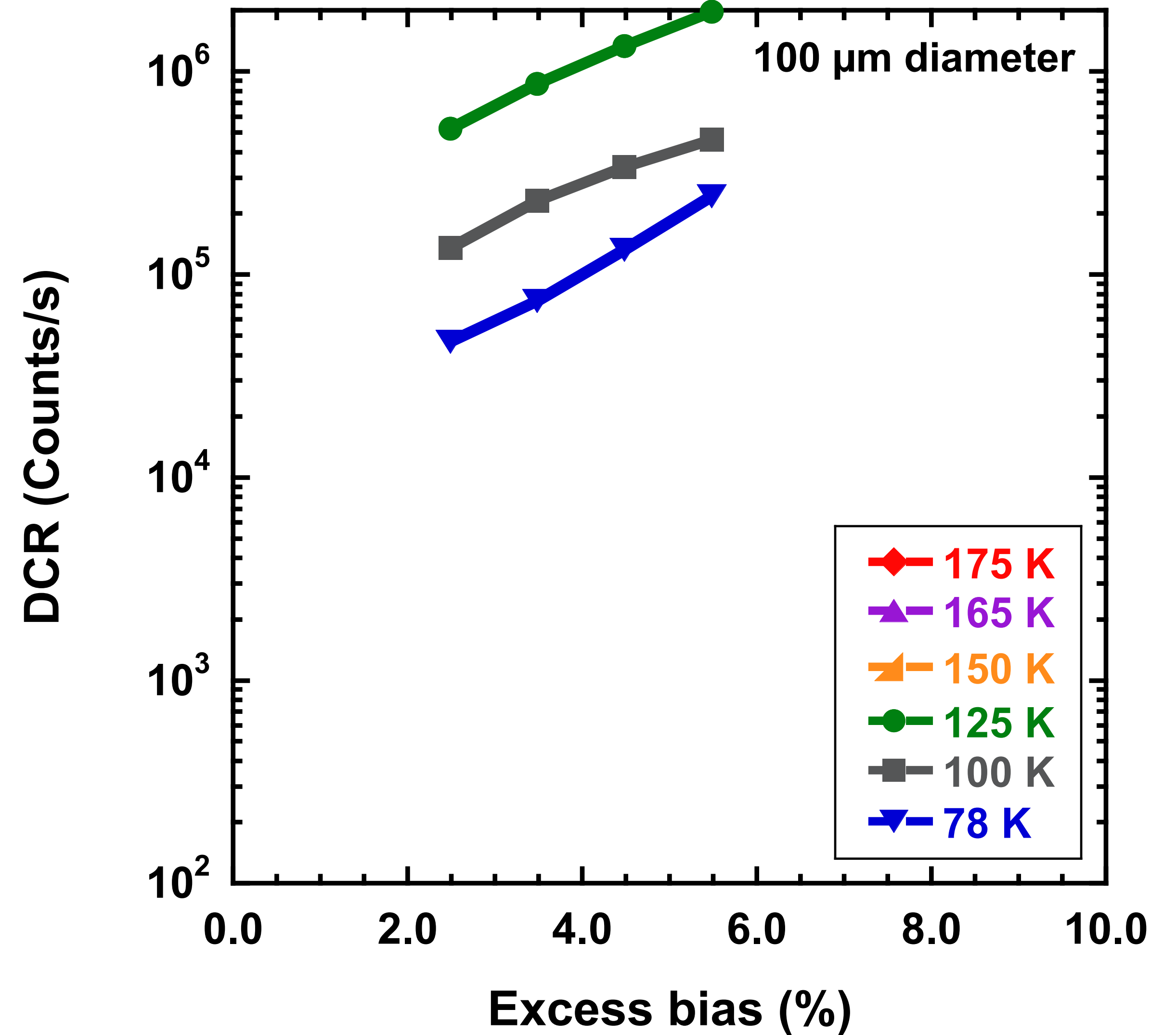
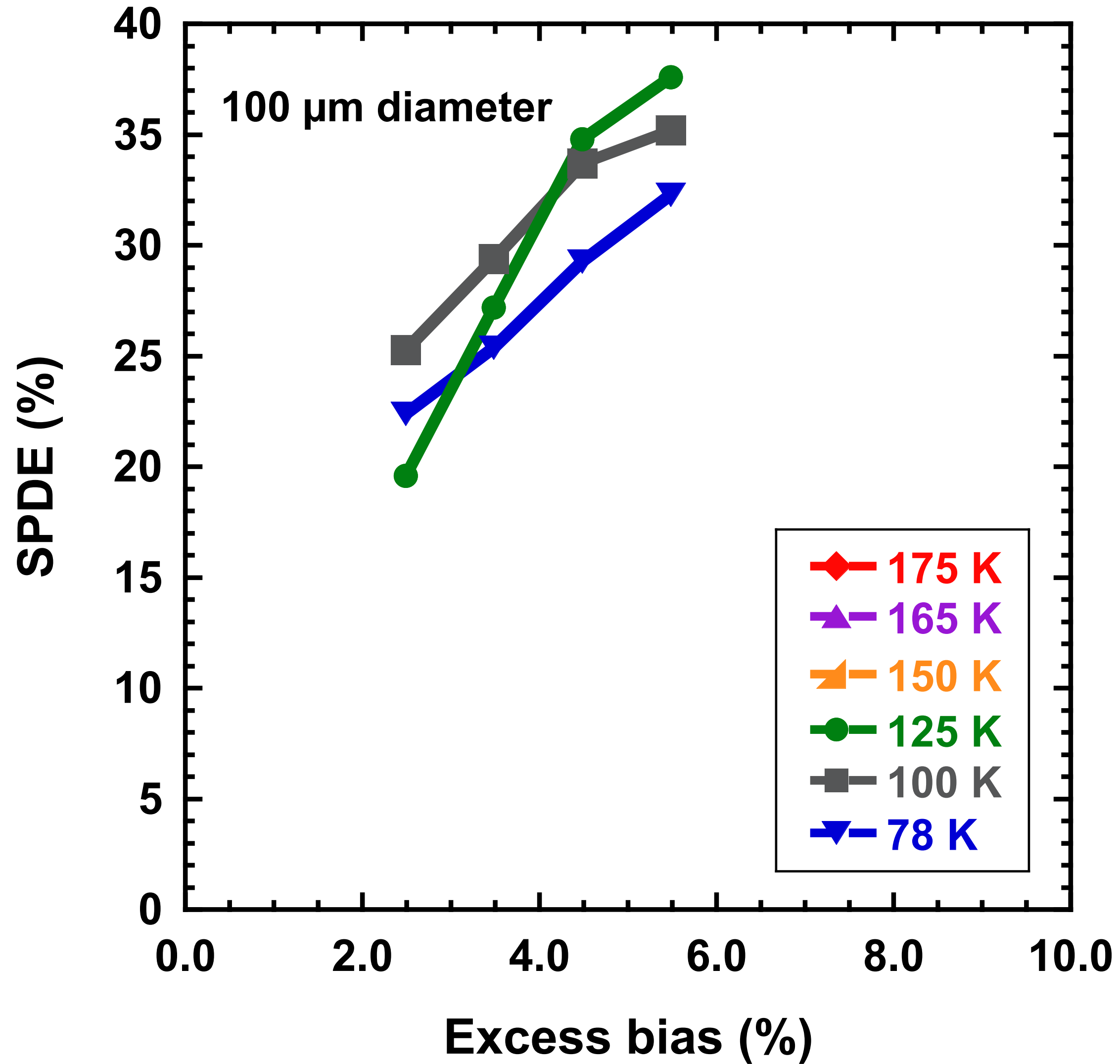
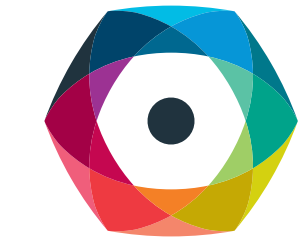


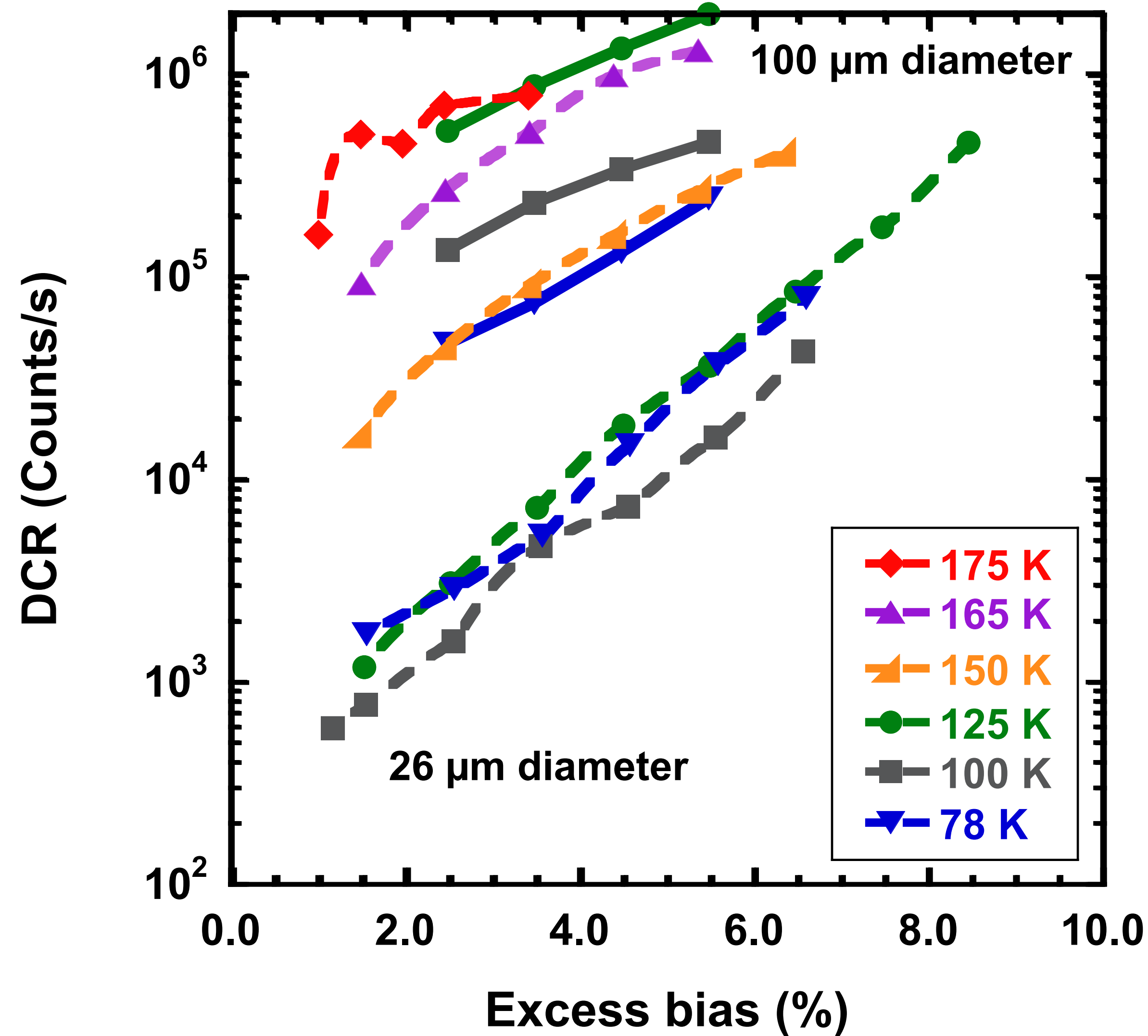
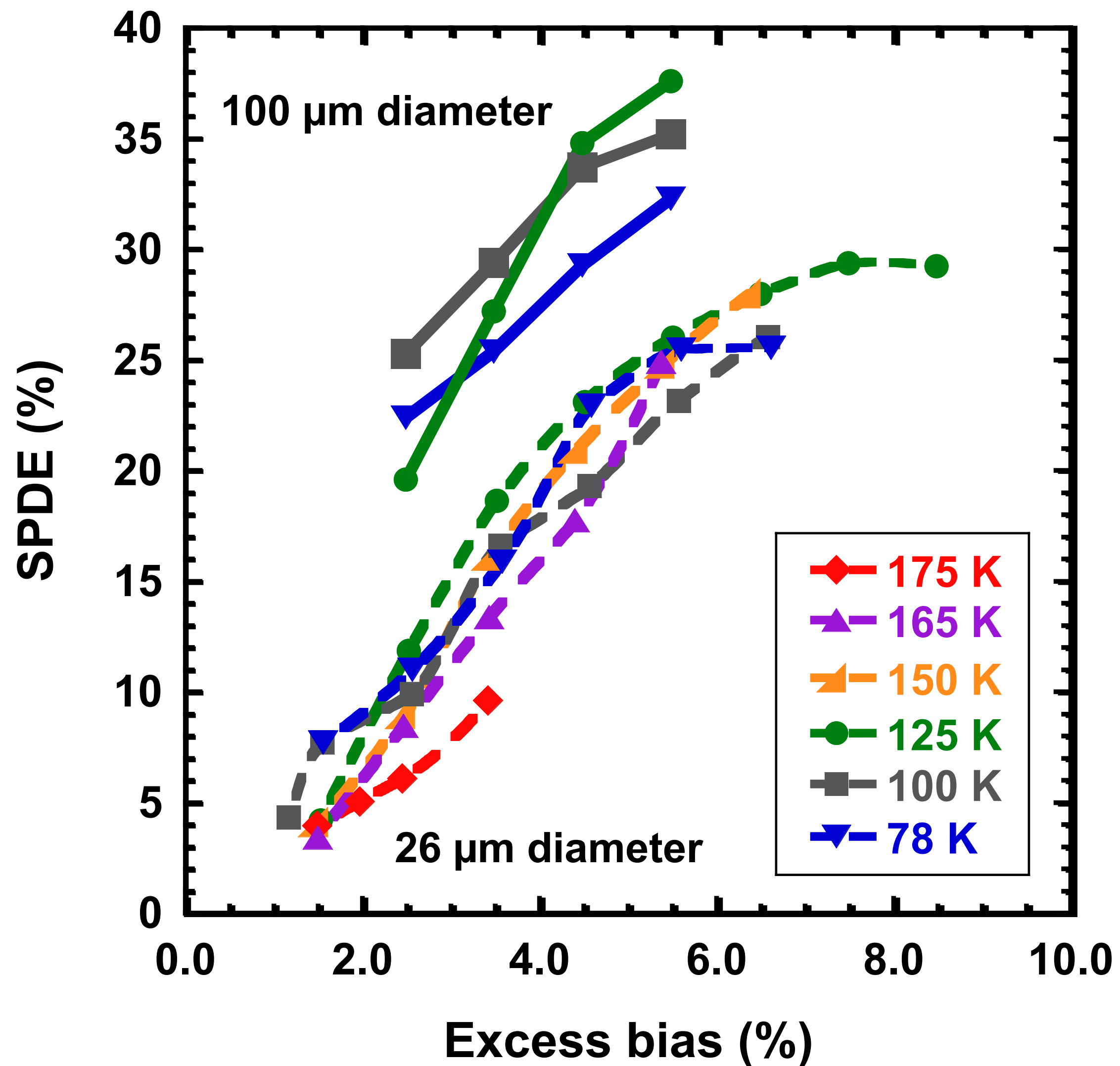
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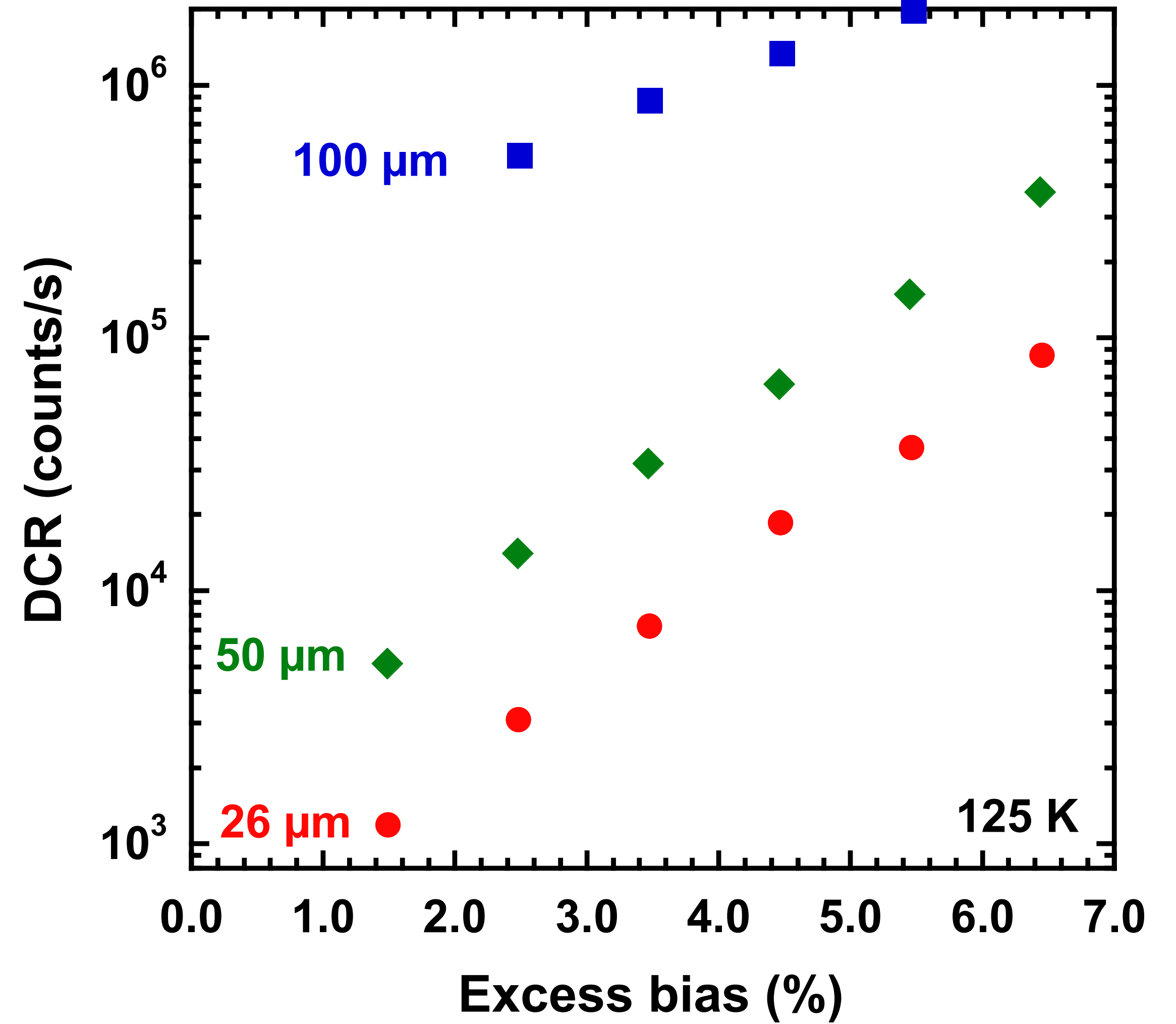
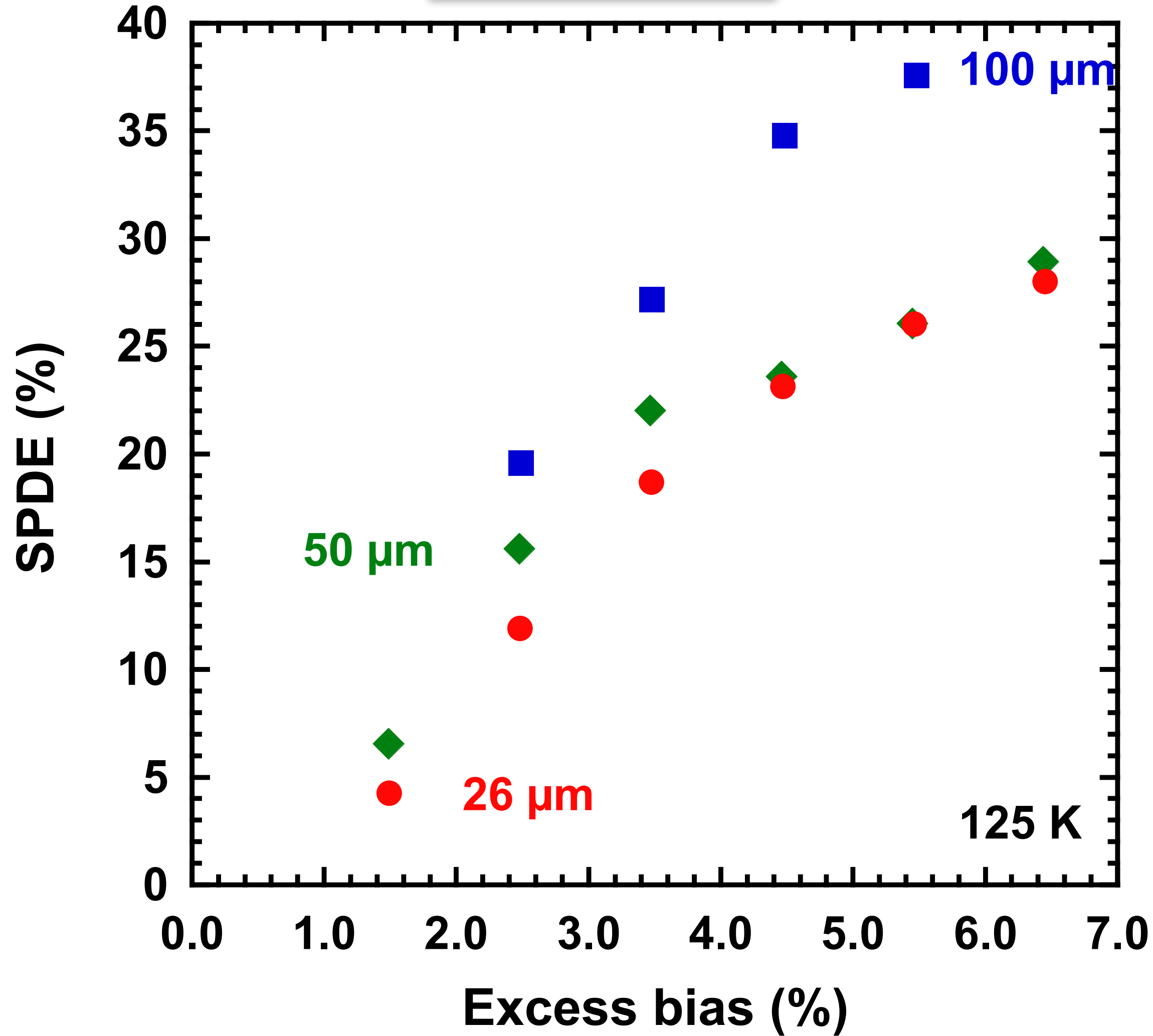
# 1310 nm Performance







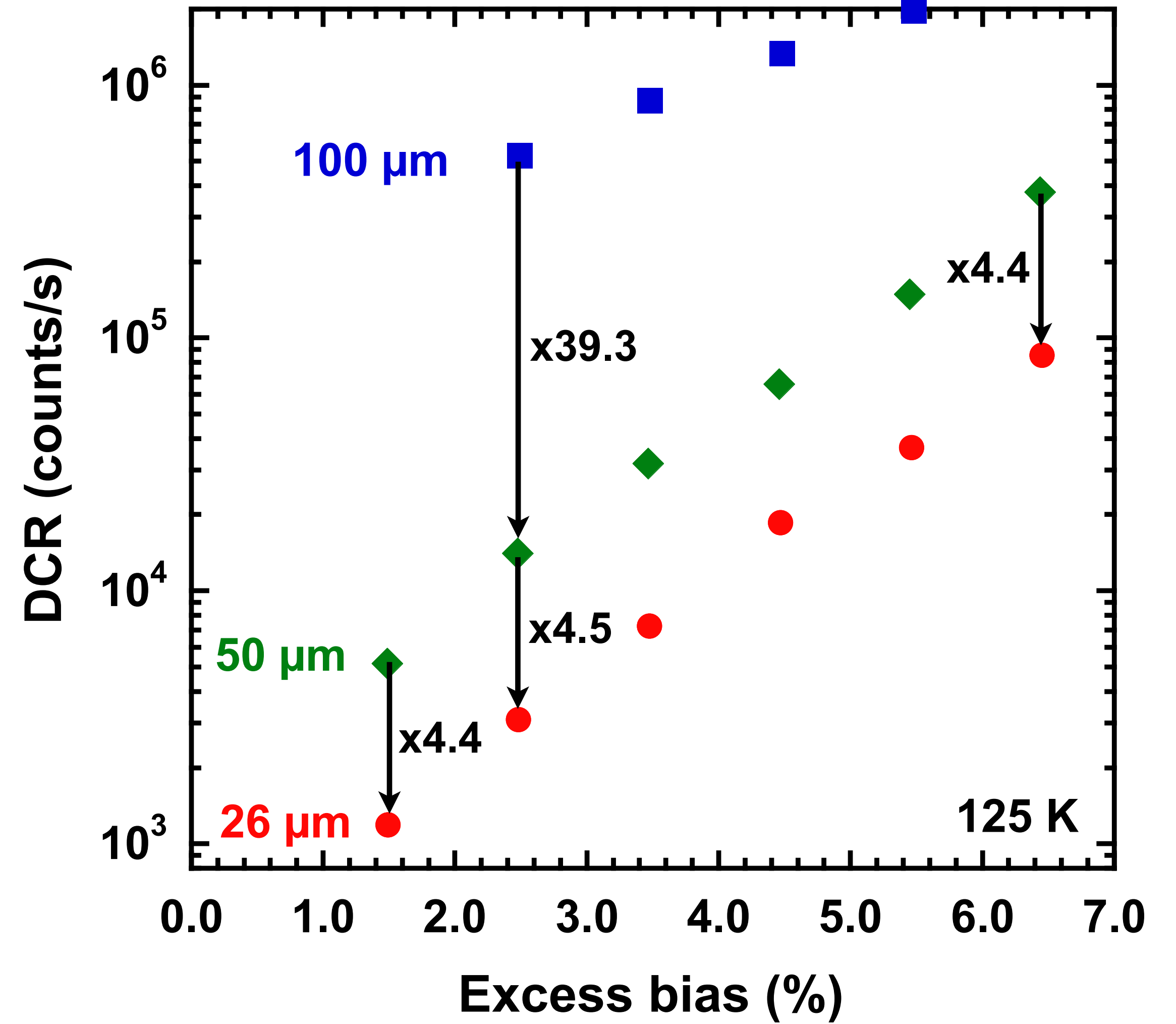
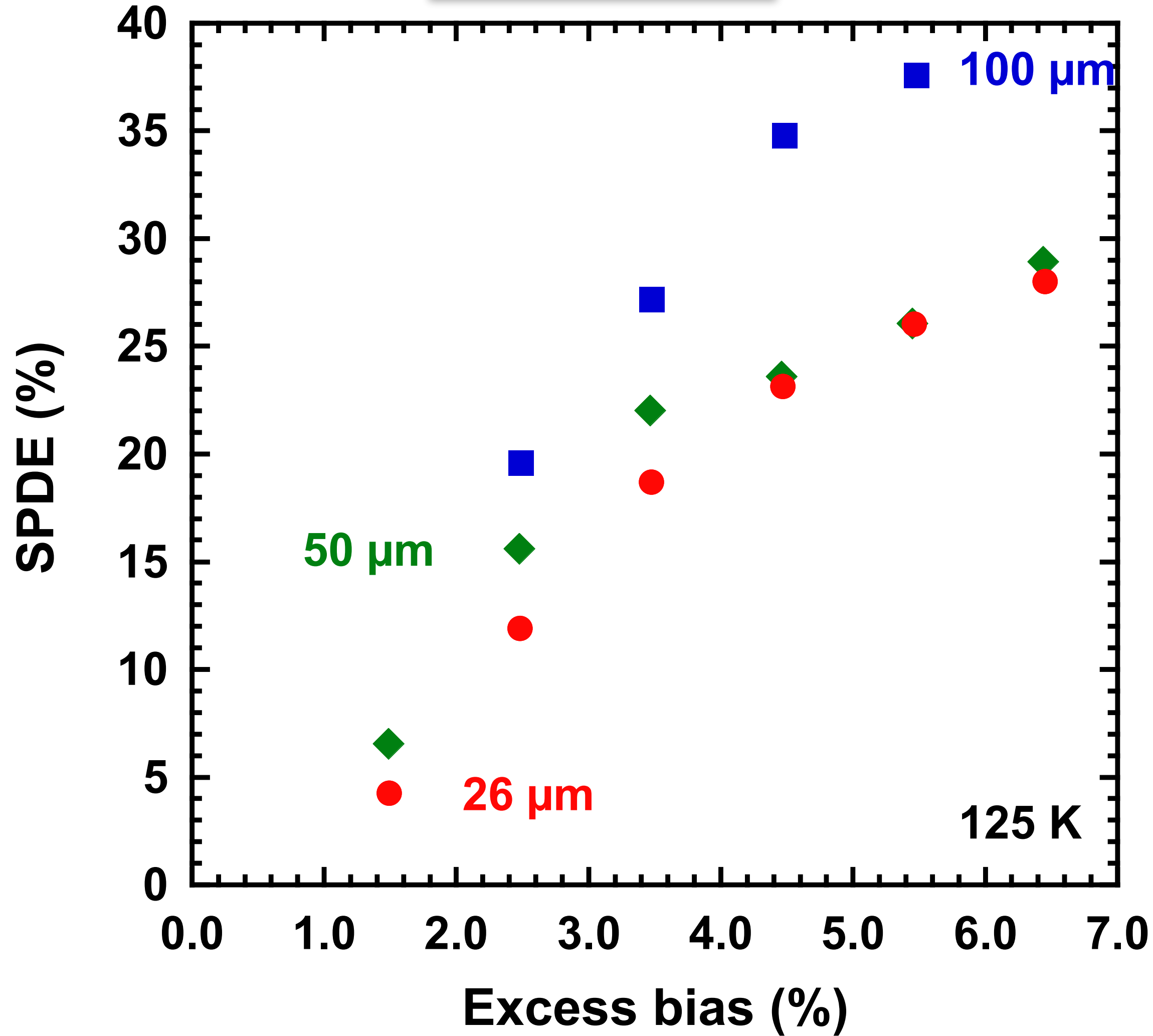
# Device Scaling



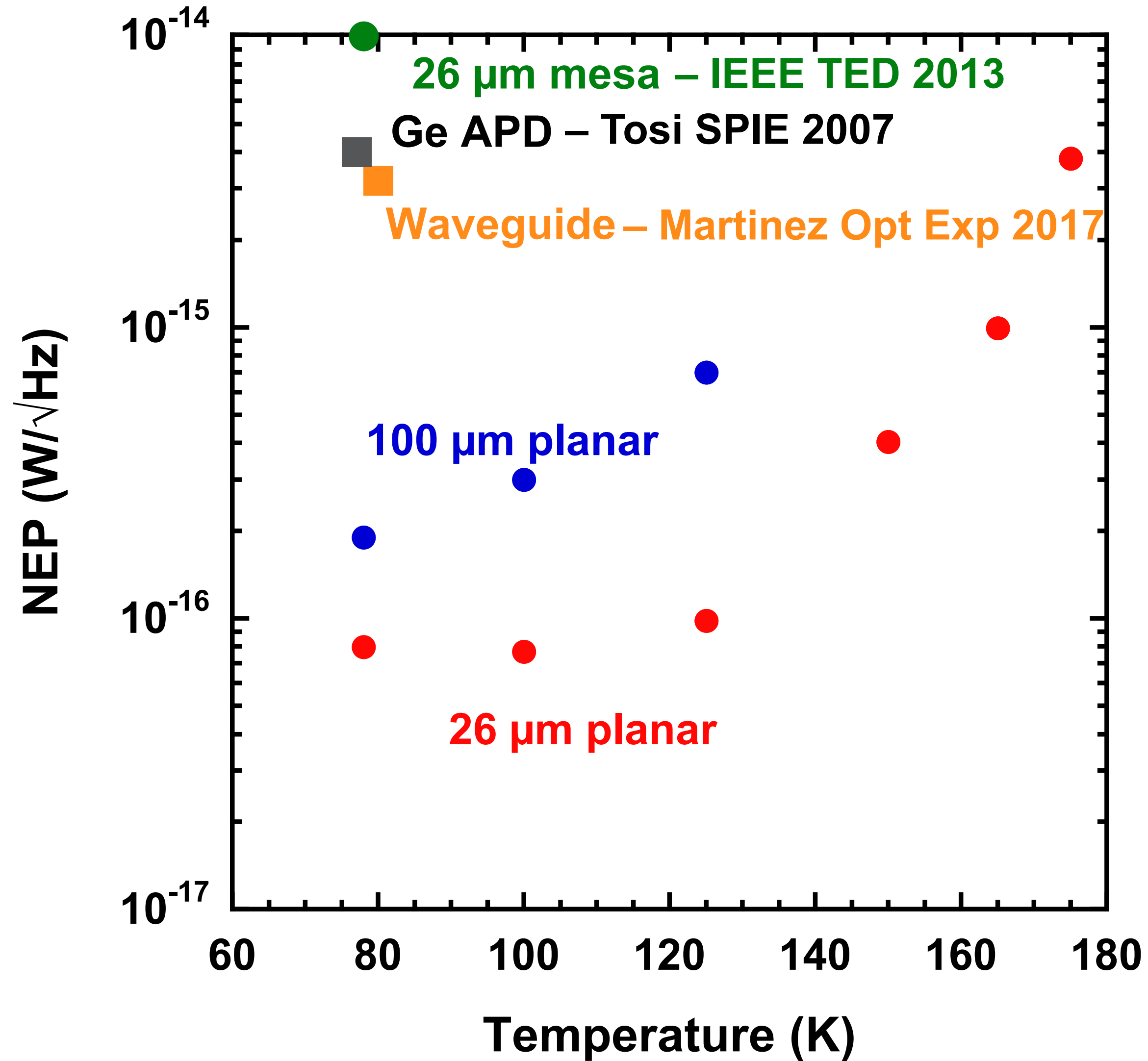




# Device Scaling

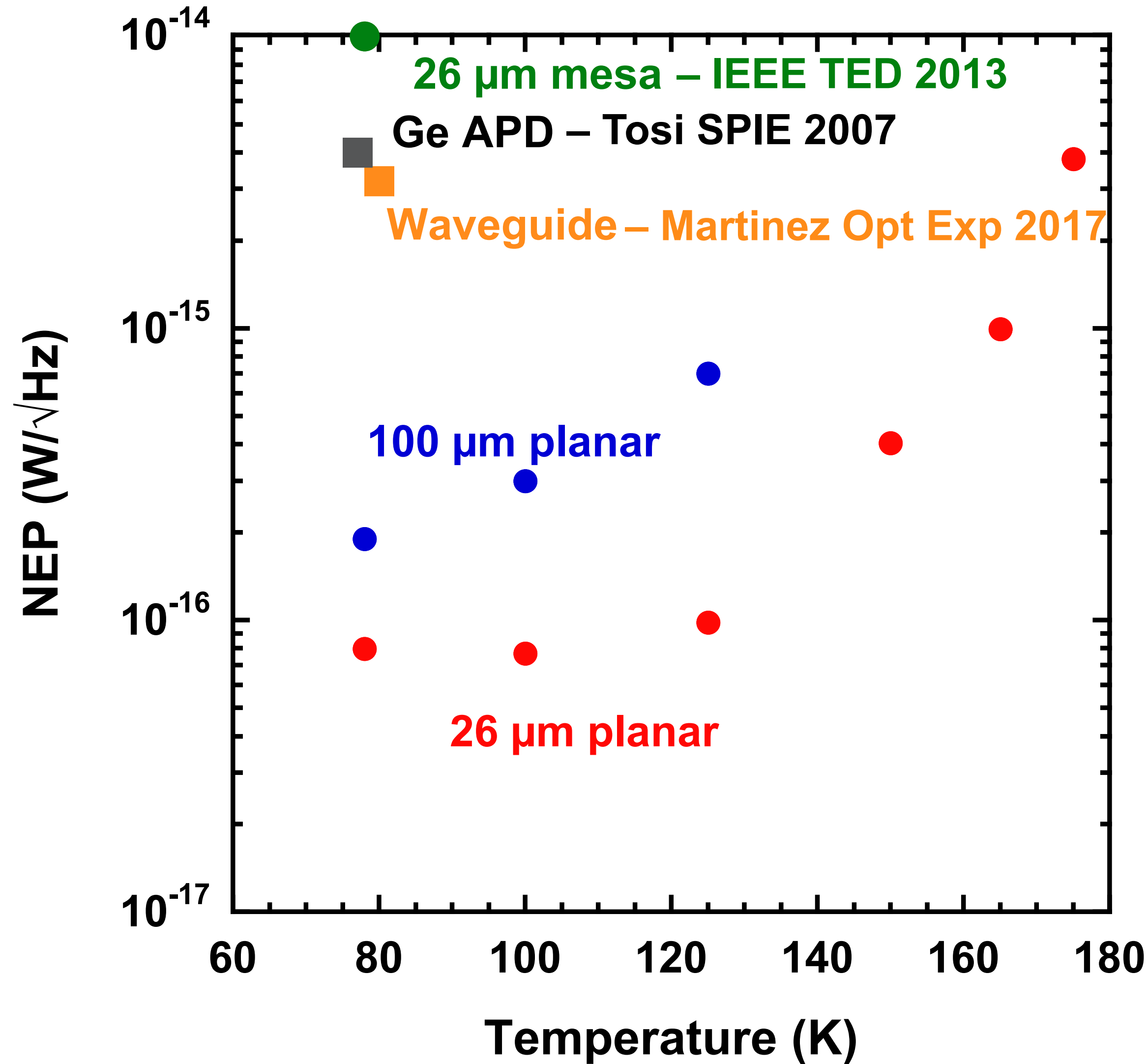


● DCR for 50 & 26 μm devices scales with Ge volume



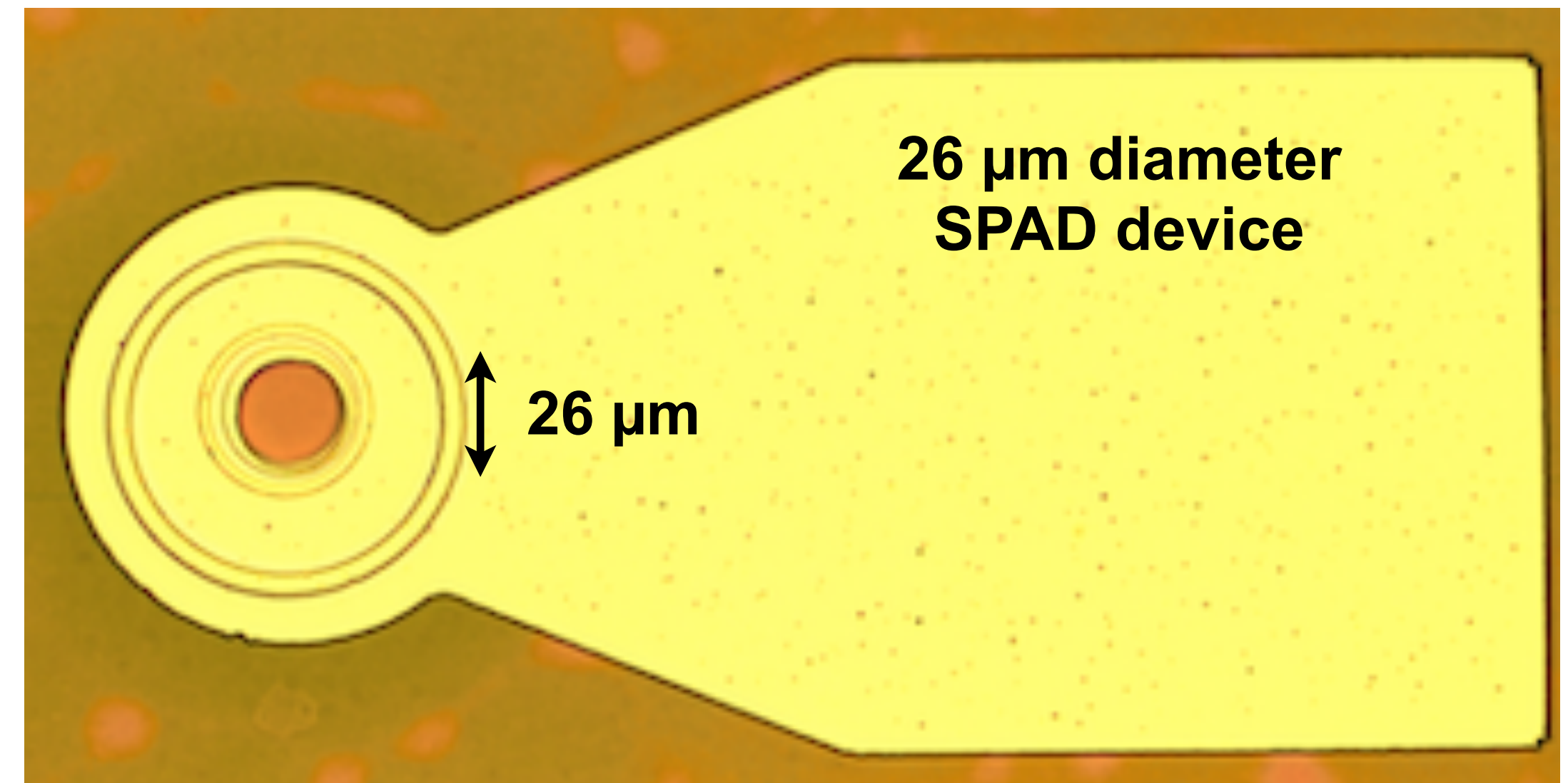
$$NEP = \frac{h\nu}{SPDE} \sqrt{2DCR}$$

● 26 μm InGaAs NEP = 1 × 10<sup>-17</sup> W/√Hz at 223 K and 1550 nm



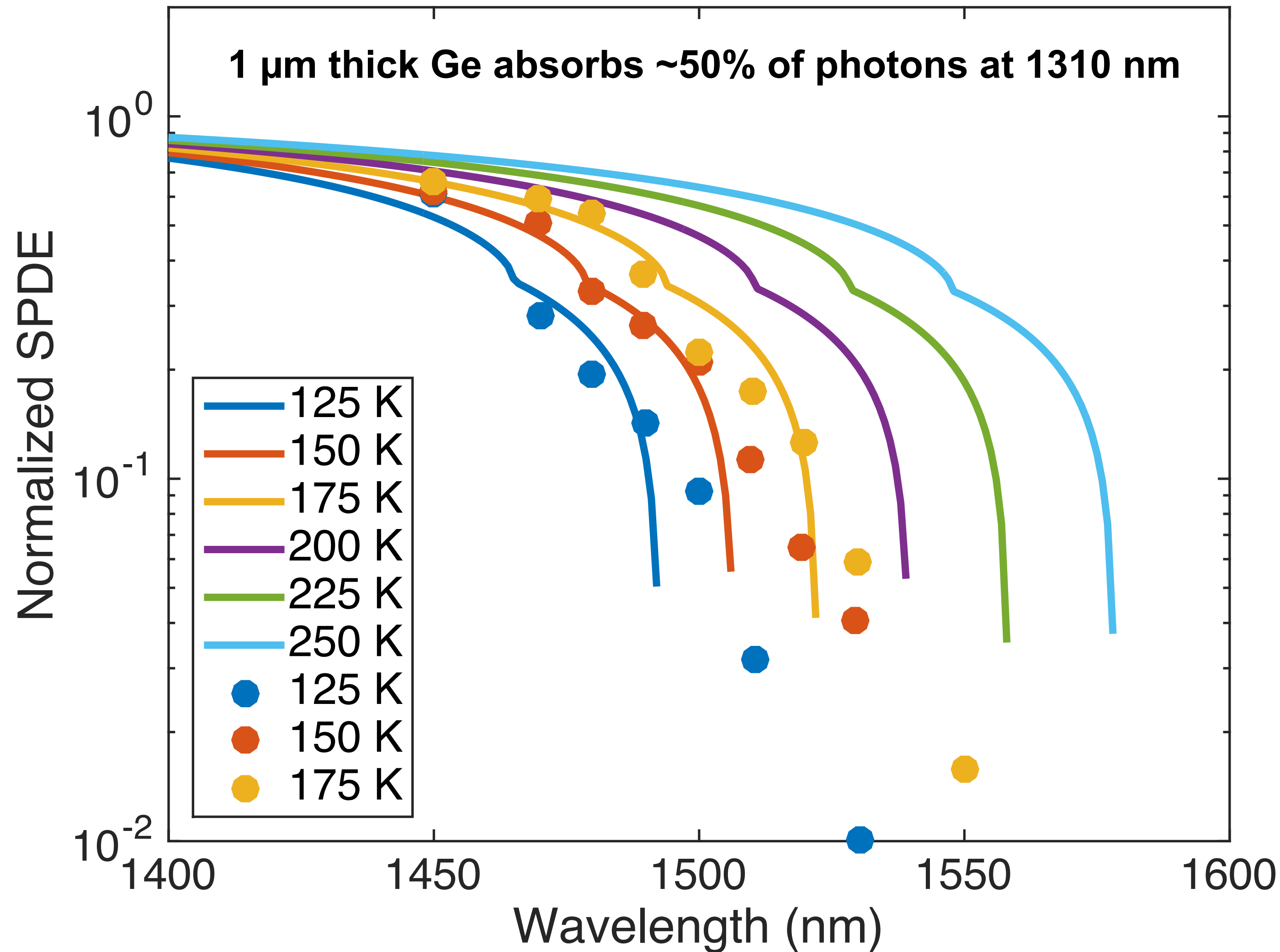
$$NEP = \frac{h\nu}{SPDE} \sqrt{2DCR}$$

- 310 ± 10 ps jitter for 100 μm diameter SPAD @ 78 K
- 134 ± 10 ps jitter for 26 μm diameter SPAD @ 100 K



19.5 ps timing bin for jitter measurements

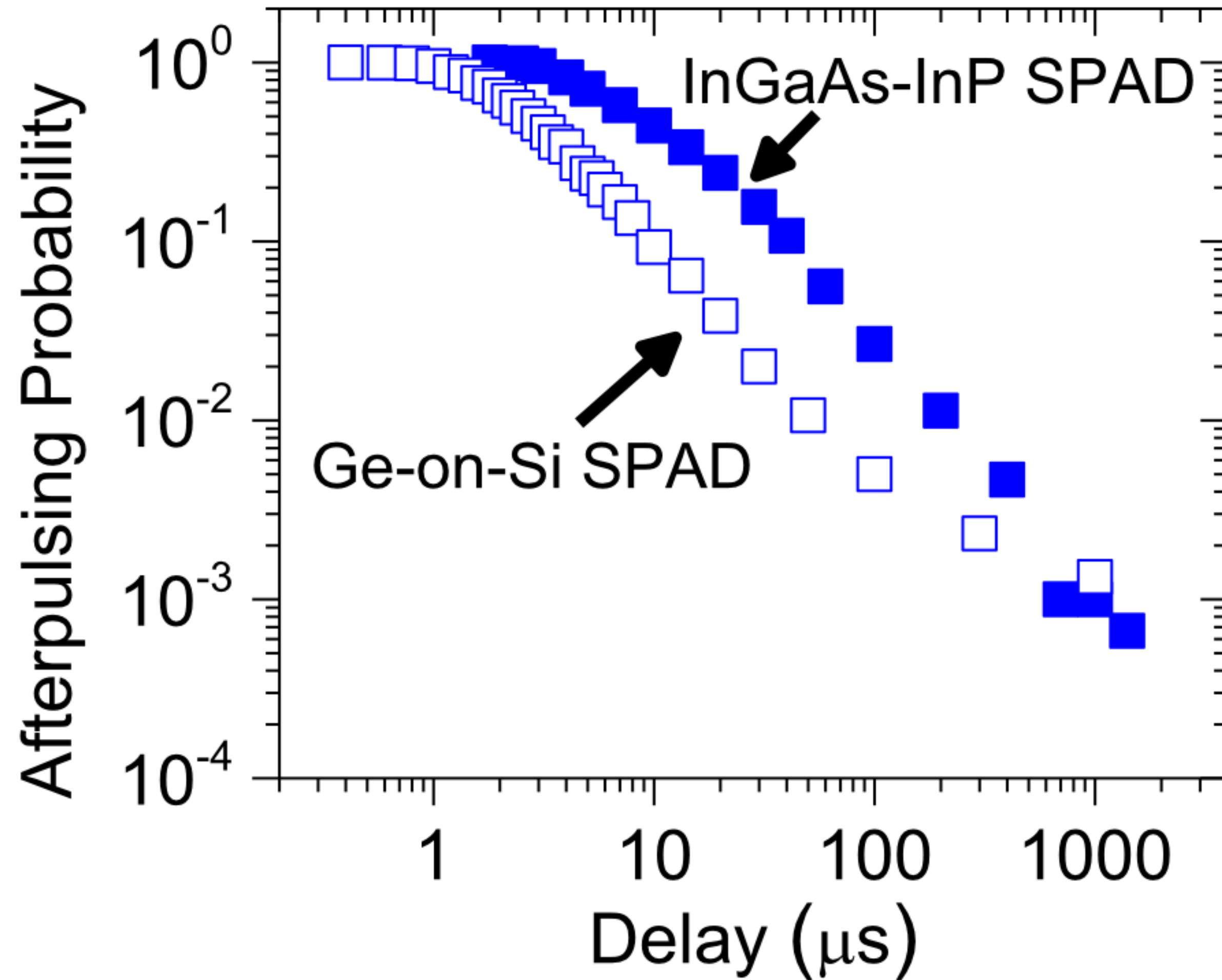
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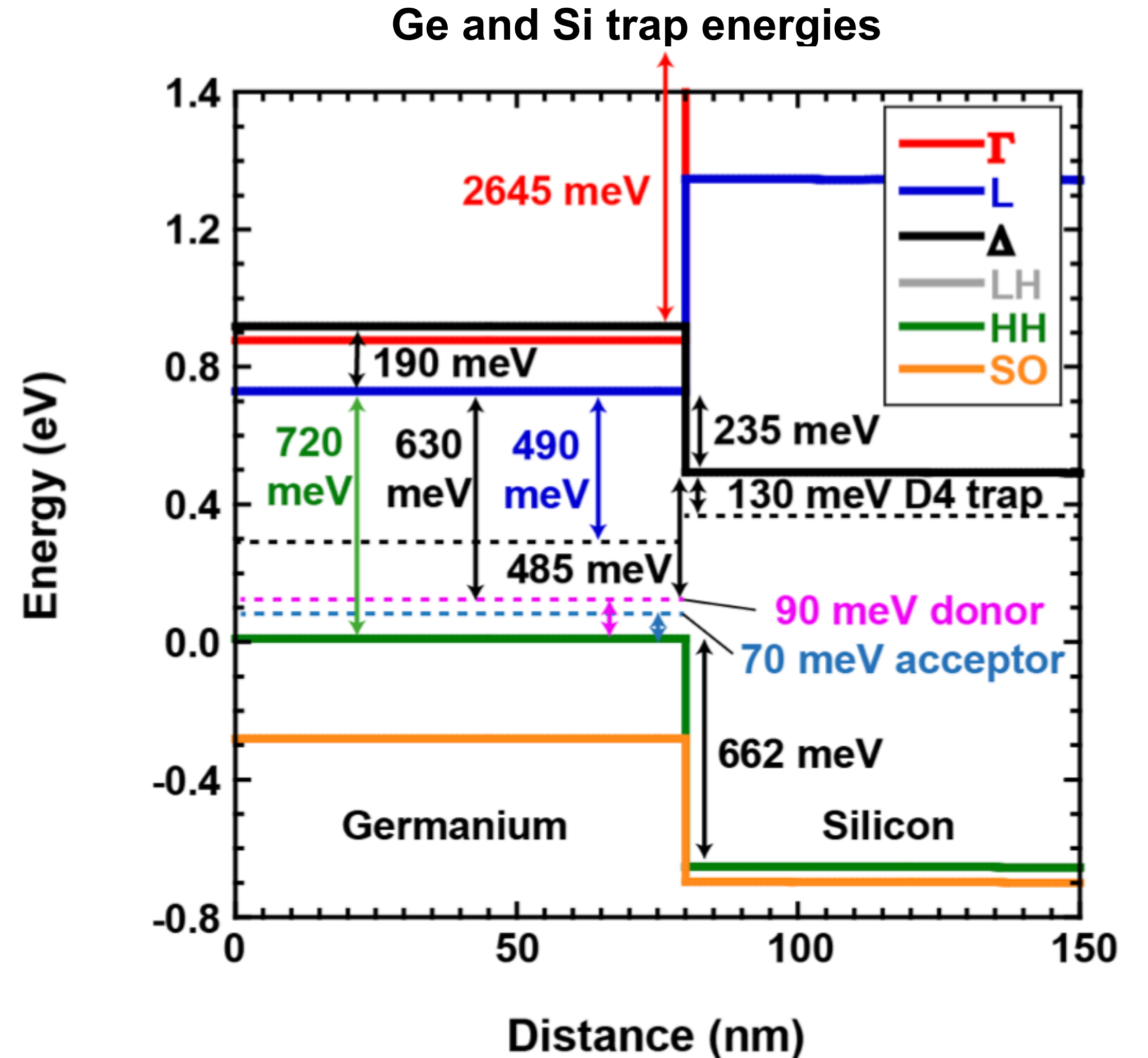
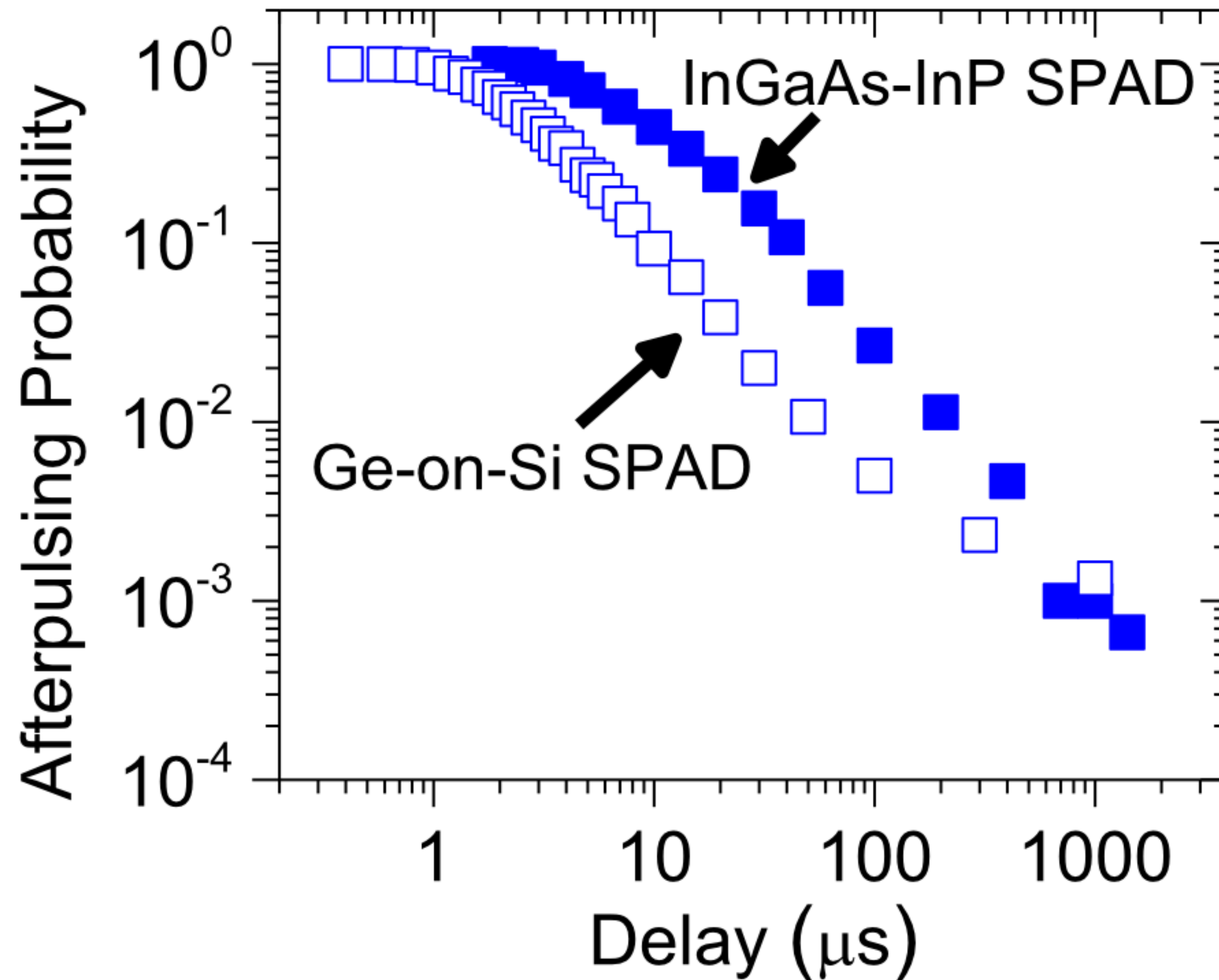
- Lines are model for direct band absorption coefficient normalised to 1 at 1.31  $\mu\text{m}$  for 300 K
- Experimental data follows indirect tails
- Discontinuity is due to 0.2% residual strain in the Ge splitting LH & HH
- Thicker Ge will increase SPDE
- 1550 nm operation requires thicker Ge & higher temperature operation
- 1550 nm operation also being pursued with GeSn (direct-band  $>1.7 \mu\text{m}$  at 4 K)



- Afterpulsing caused by traps in avalanche region: limit repetition rate due to dead time of detector



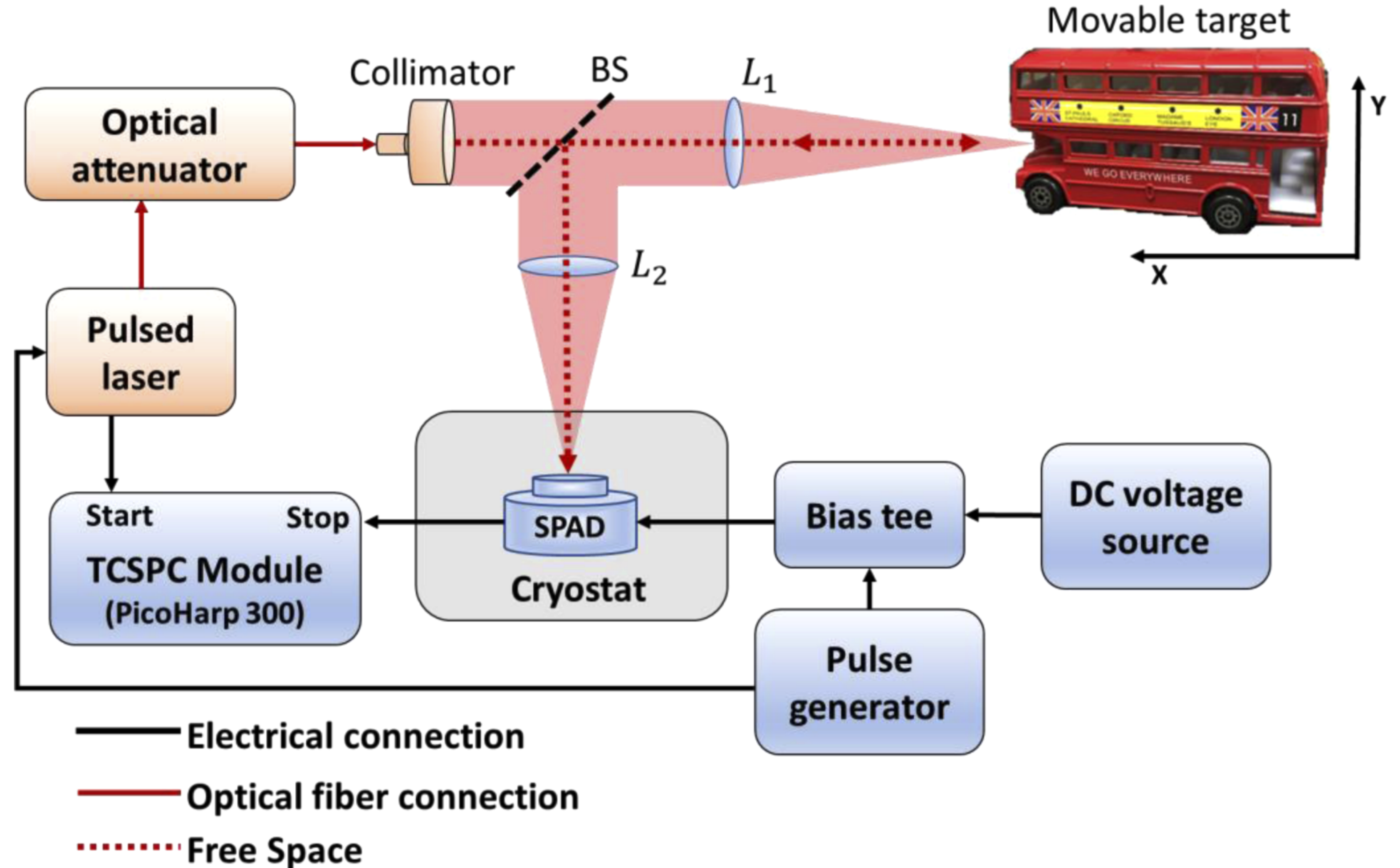
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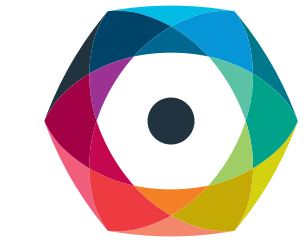
# LIDAR Imaging

- 912 pW laser after attenuation
- $\lambda = 1450 \text{ nm}$
- Repetition rate 104 kHz
- 100  $\mu\text{m}$  diameter SPAD at 100 K
- $V_{\text{ex}} = 1.5\%$ , SPDE = 10%
- DCR = 4.7 MHz
- 23 mm aperture
- Mechanical raster of single pixel
- 100 x 70 pixel raster for images





# LIDAR with Ge on Si SPADs



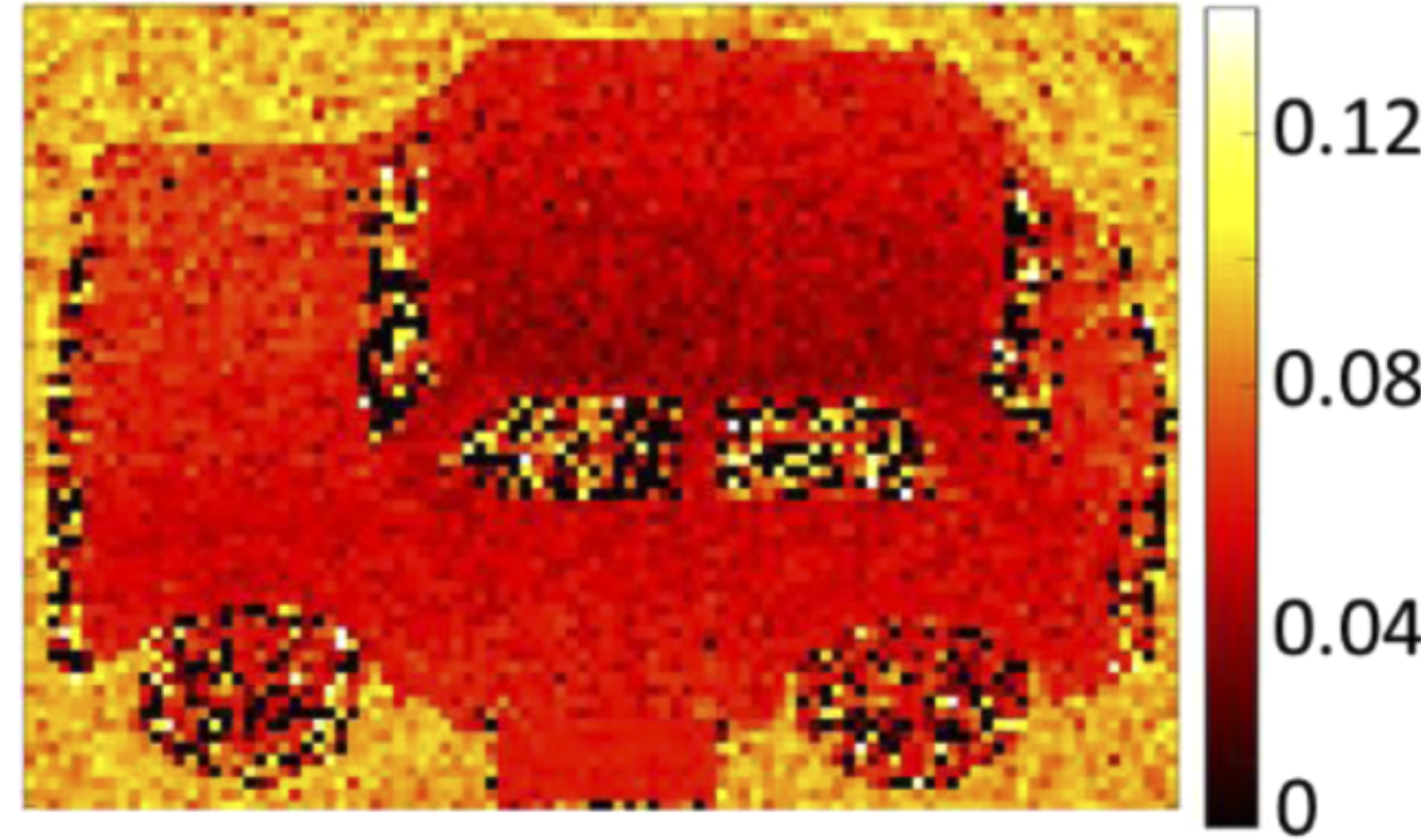
95mm x 60mm x 45mm (L x W x H)

- 912 pW laser
- $\lambda = 1450$  nm
- Repetition rate 104 kHz
- $V_{ex} = 1.5\%$ , SPDE = 10%
- DCR = 4.7 MHz
- 23 mm aperture
- 100 x 70 pixel raster

30 ms

Depth

Meters



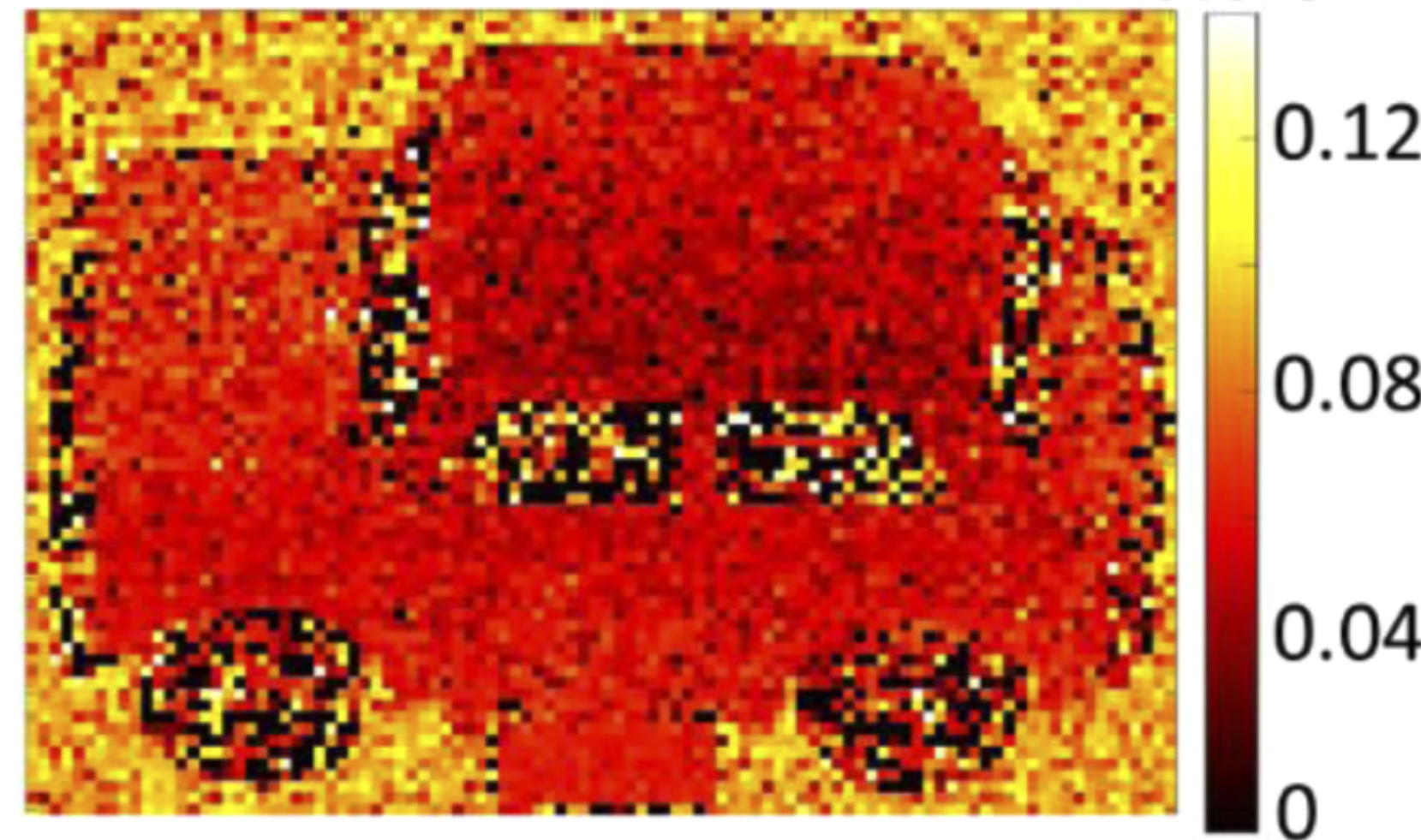
Intensity

Counts



10 ms

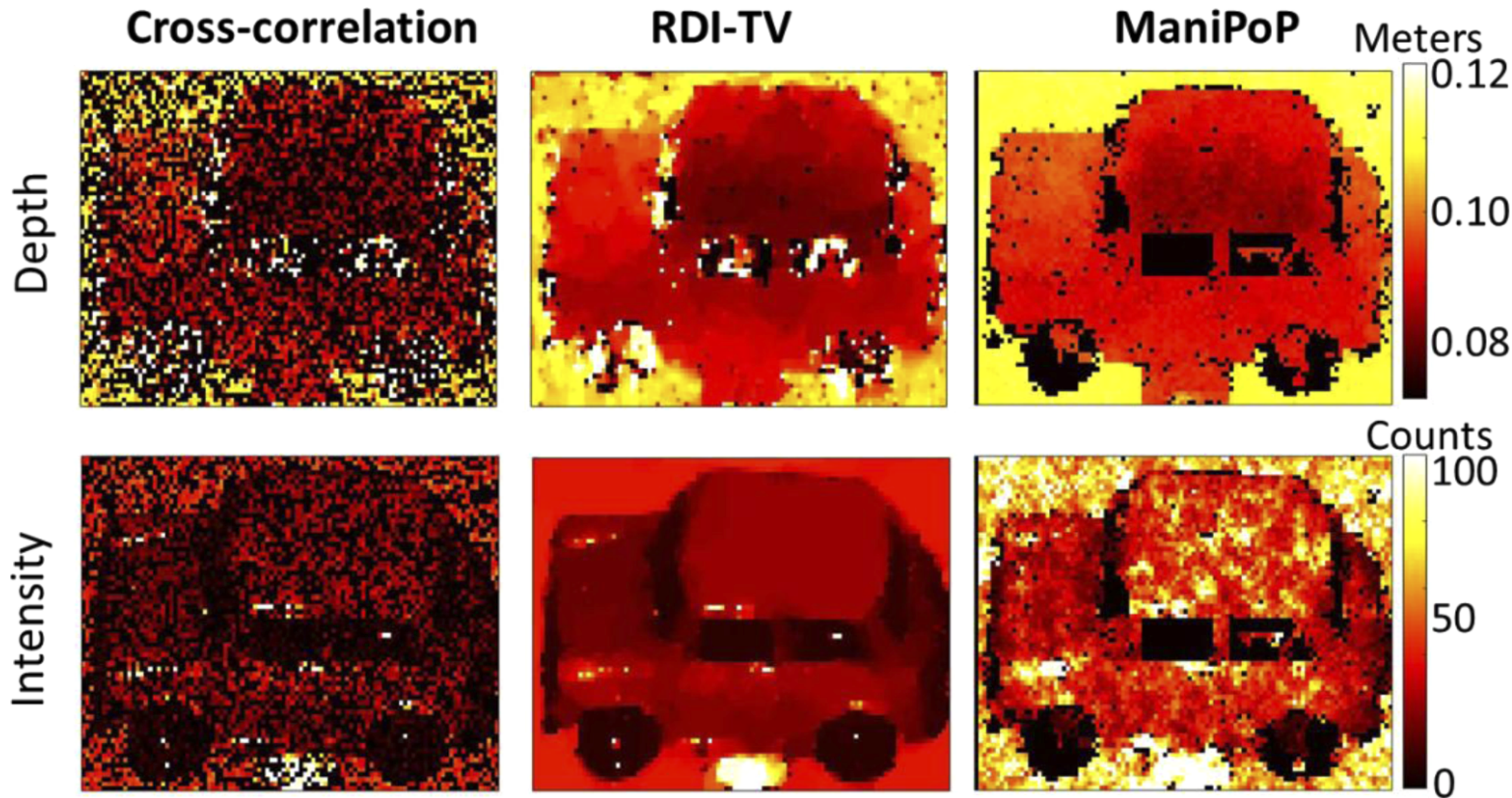
Meters



Counts







● 10 ms acquisition time with 50% of pixels removed



- Estimate of photon events recorded in timing bin corresponding to peak of photo return histogram:

$$n_p = \frac{E_{\text{pulse}} F \lambda}{hc} t \frac{A_{\text{lens}} \rho}{2\pi R^2} e^{-2\alpha R} C_{\text{in}} C_{\text{det}} \eta$$

- Background counts per bin:

$$n_b = t \text{DCR} \tau_b F$$

26 μm SPAD  
DCR = 2.6kc/s

- Signal-to-noise

$$\text{SNR} = \frac{n_p}{\sqrt{n_p + n_b}}$$

- Average laser power required for successful imaging at distance R:

$$P_{\text{out}} = \frac{hc}{\lambda} \frac{2\pi R^2 n_p}{A_{\text{lens}} \rho t \eta C_{\text{in}} C_{\text{det}}}$$

$E_{\text{pulse}}$  = laser pulse energy

$F$  = laser rep. rate

$\lambda$  = wavelength

$t$  = acquisition time

$A_{\text{lens}}$  = collection area of lens

$\rho$  = reflectivity of target (= 10%)

$R$  = distance to target

$\alpha$  = attenuation coefficient of environment

$C_{\text{in}}$  = internal loss of system (= 10 dB)

$C_{\text{det}}$  = temporal response of detector

$\eta$  = detector SPDE (= 15% or 9%)

$\tau_b$  = bin size (= 50 ns)

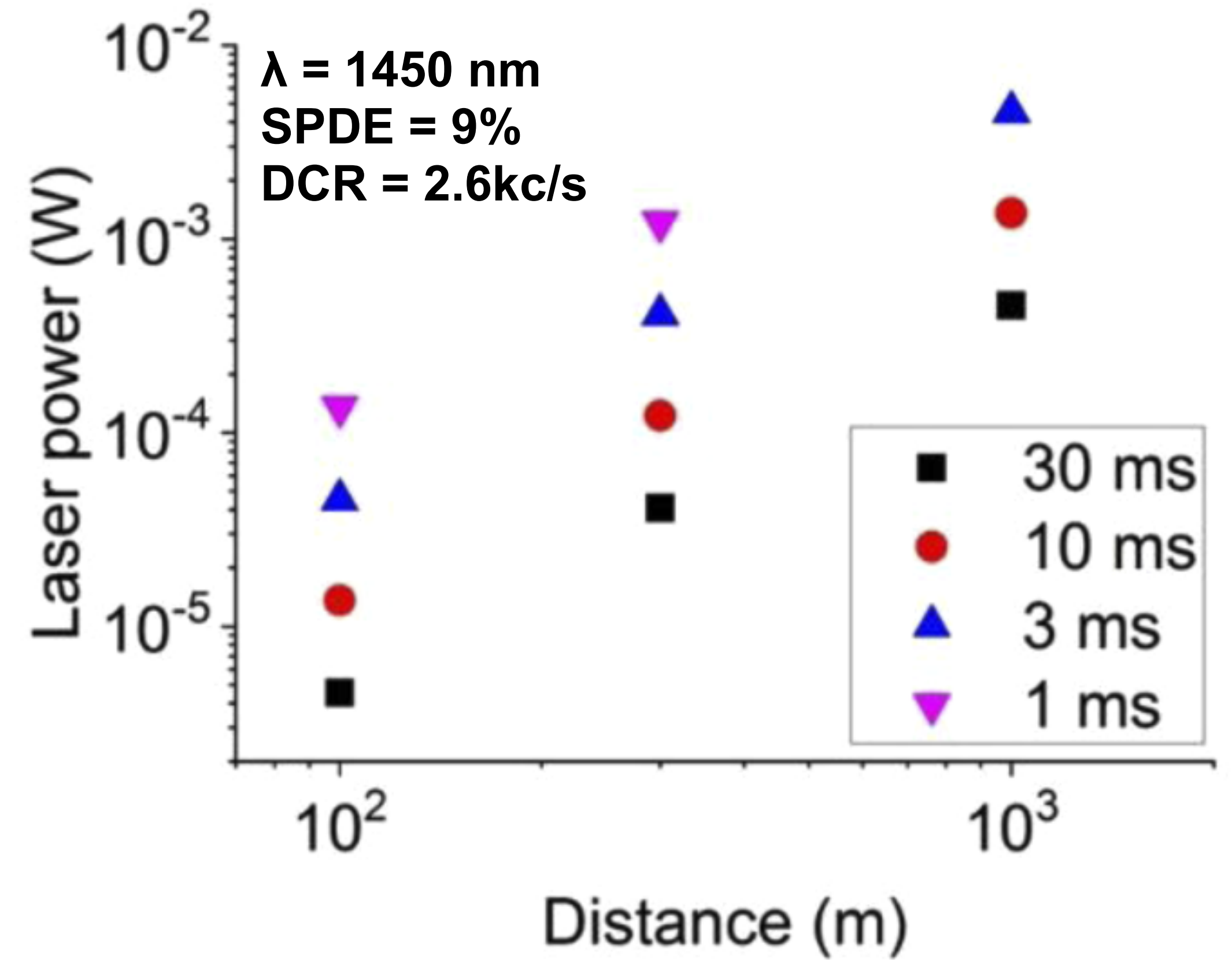
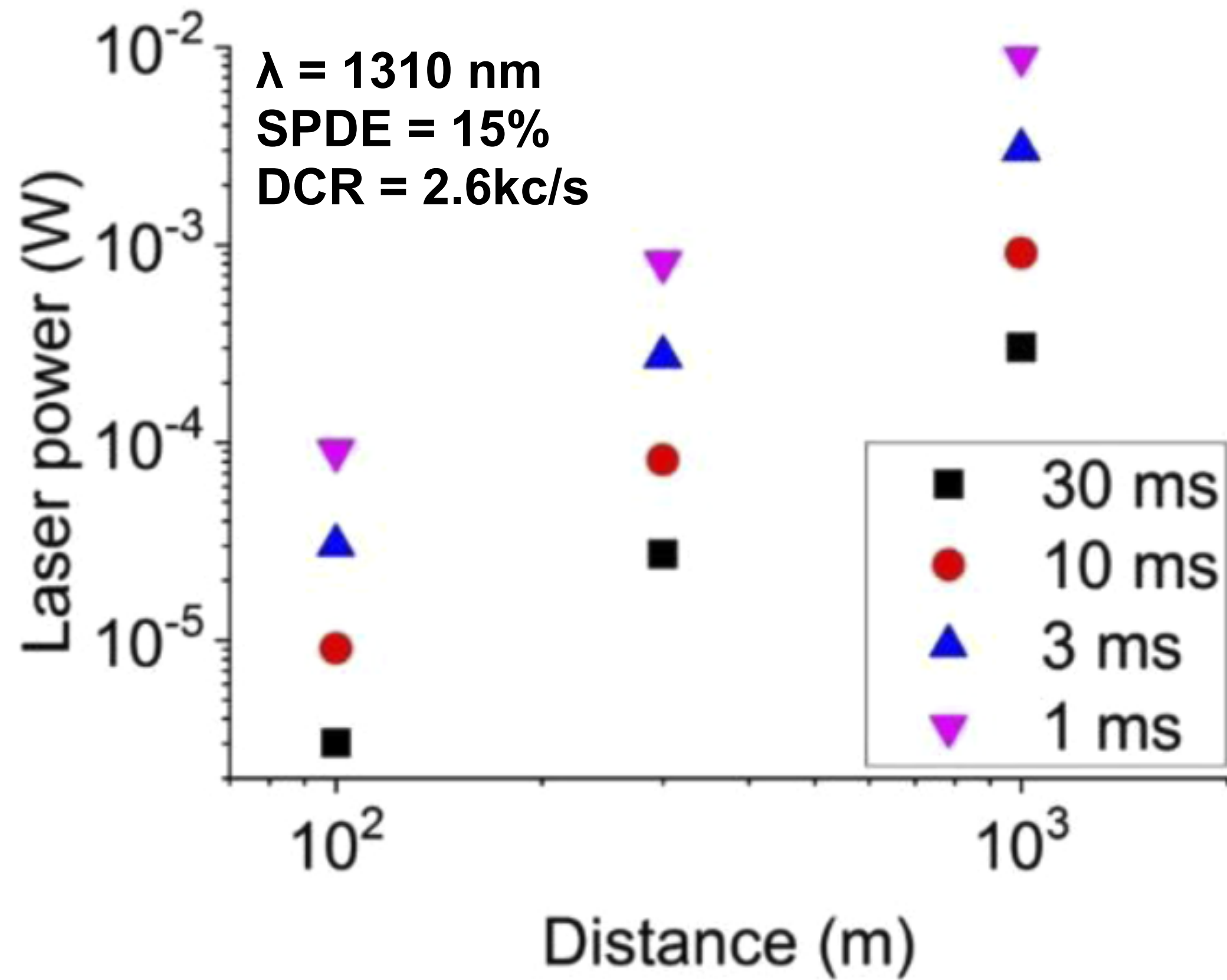
*K. Kuzmenko et al., Opt. Exp. 28, 1330 (2020)*



# LIDAR Range



- 23 mm aperture lens with 26  $\mu\text{m}$  Ge-on-Si SPAD operating at 125 K, 2.5% excess bias & 100 kHz rep. rate
- SNR = 1.4, internal system loss = 10 dB, reflectivity of target is Lambertian with 10% back-scatter



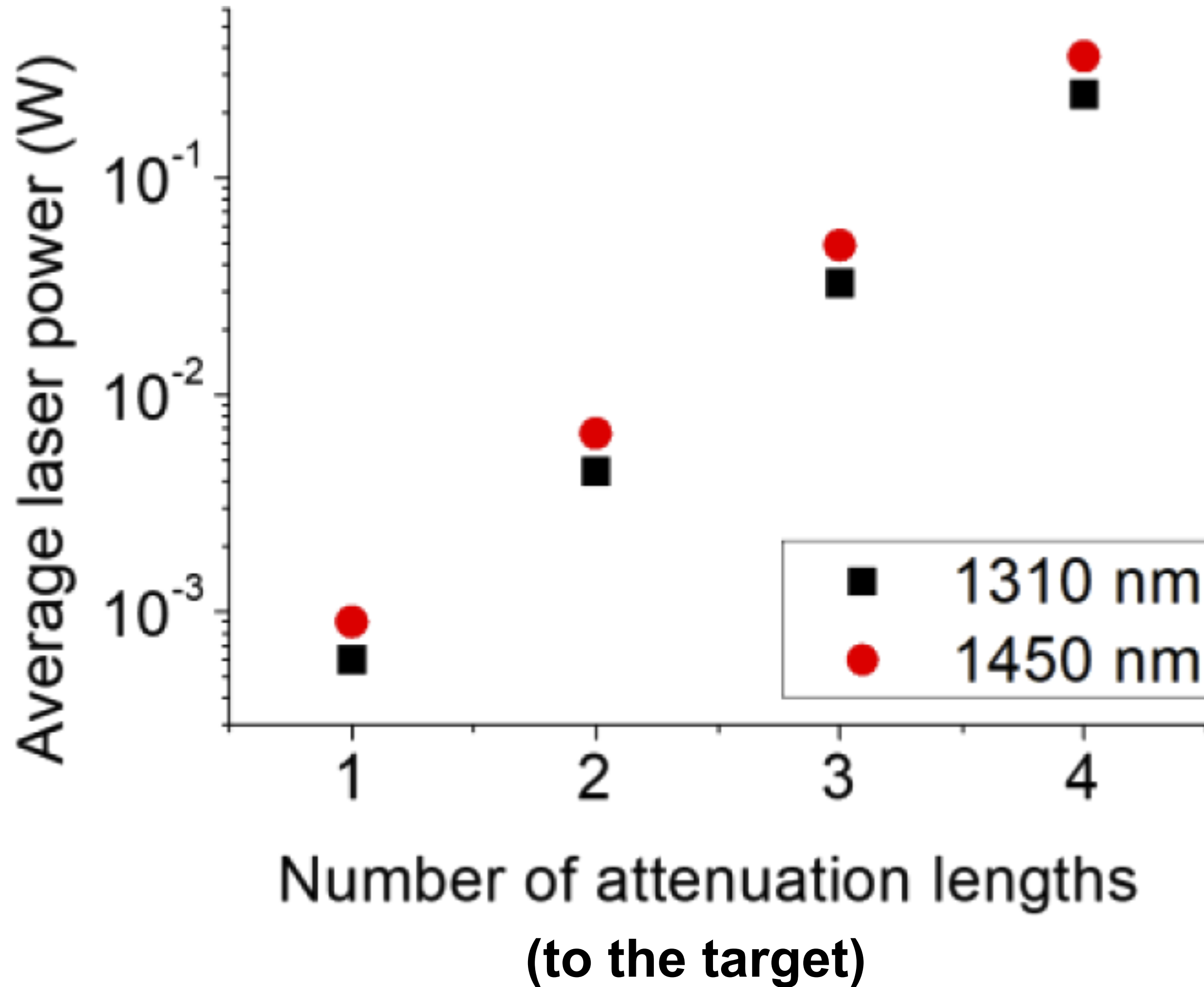
- $\geq 1 \text{ km}$  range for LIDAR for eye-safe laser powers (IEC-60825-1) for  $\geq 1 \text{ ms}$  averaging per pixel



# 300 m Through Obscurants



● 23 mm aperture lens with 26  $\mu\text{m}$  Ge-on-Si SPAD operating at 125 K, 2.5% excess bias & 100 kHz rep. rate



● 10 ms acquisition time per pixel

● Eye-safe lidar feasible for automotive motorway driving in weakly attenuating media

● Reconstruction algorithms & improved SPDE at longer  $\lambda$  will improve performance in obscurant media



# Summary



- Planar design key resulting in 3 orders of magnitude reduction of DCR
- SPDE up to 38% at 1310 nm & 125 K
- NEP =  $7.8 \times 10^{-17} \text{ W}/\sqrt{\text{Hz}}$  and  $134 \pm 10 \text{ ps}$  jitter for 26  $\mu\text{m}$  SPAD at 100 K
- Afterpulsing at least x5 lower than InGaAs under identical conditions
- Initial LIDAR demonstration at eye-safe wavelengths
- Aim for telecoms wavelengths on Si at Peltier cooler temperatures

- EPSRC QuantiC
- EPSRC Quantum Comms Hub
- EPSRC SPEXS Programme Grant
- InnovateUK AquaSec
- InnovateUK SPIDAR
- Dstl PhD scholarship

P. Vines et al., “High performance Ge-on-Si SPAD detectors” Nature Comms. 10, 1086 (2019)

K. Kuzmenko et al., “3D LIDAR imaging using Ge-on-Si SPAD detectors” Opt. Exp. 28, 1330 (2020)



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