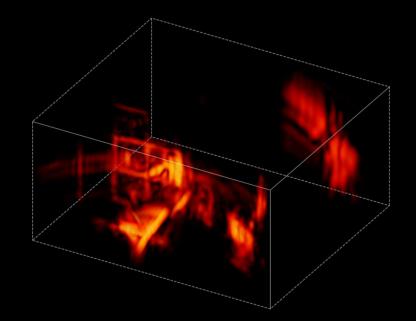
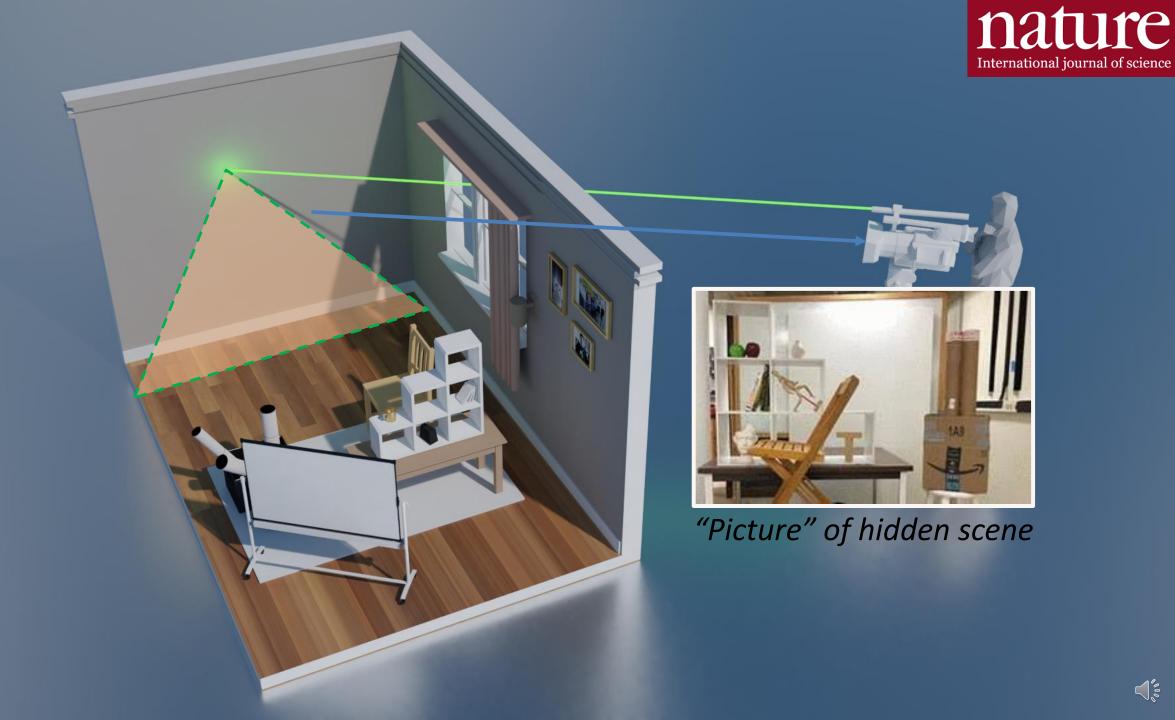
#### SPAD Arrays for Non-Line-of-Sight Imaging

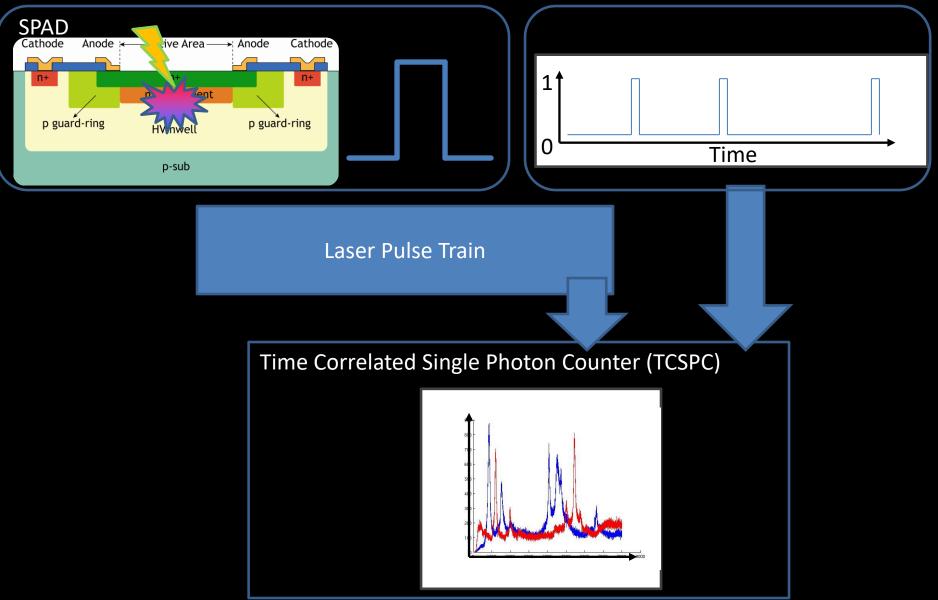
Andreas Velten Computational Optics Group Department of Biostatistics and Medical Informatics Department of Electrical and Computer Engineering University of Wisconsin-Madison, USA



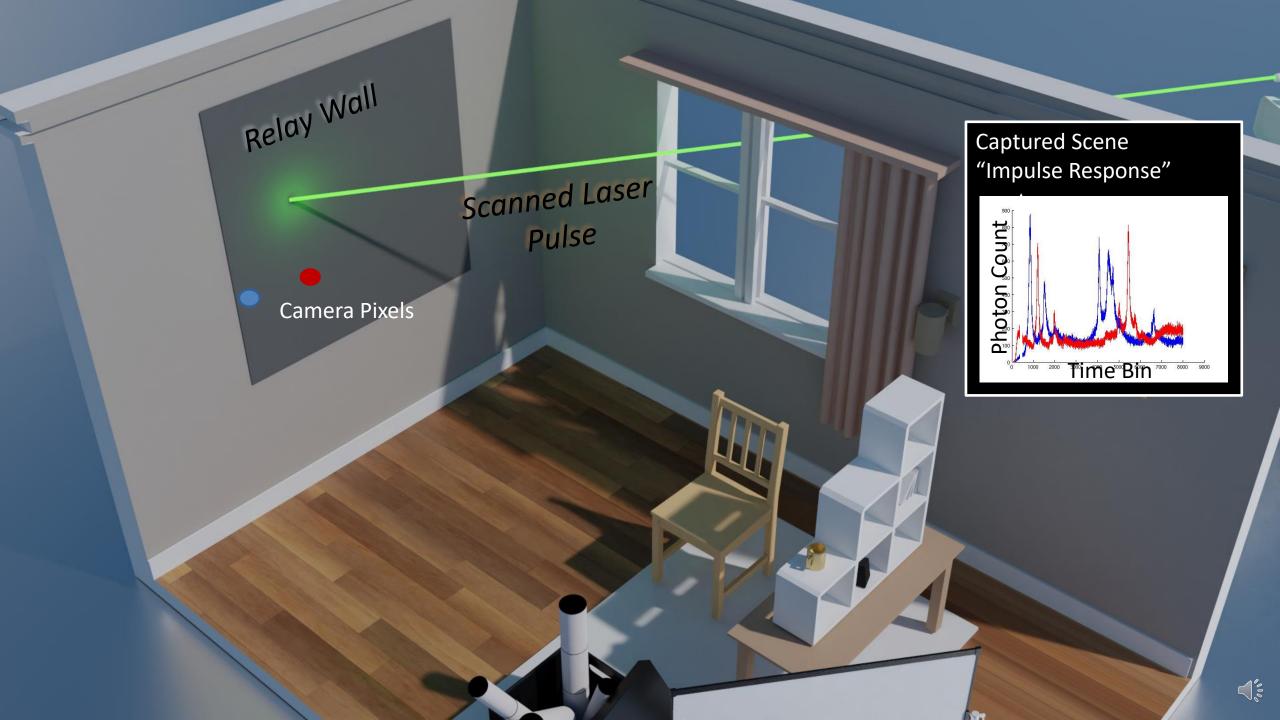


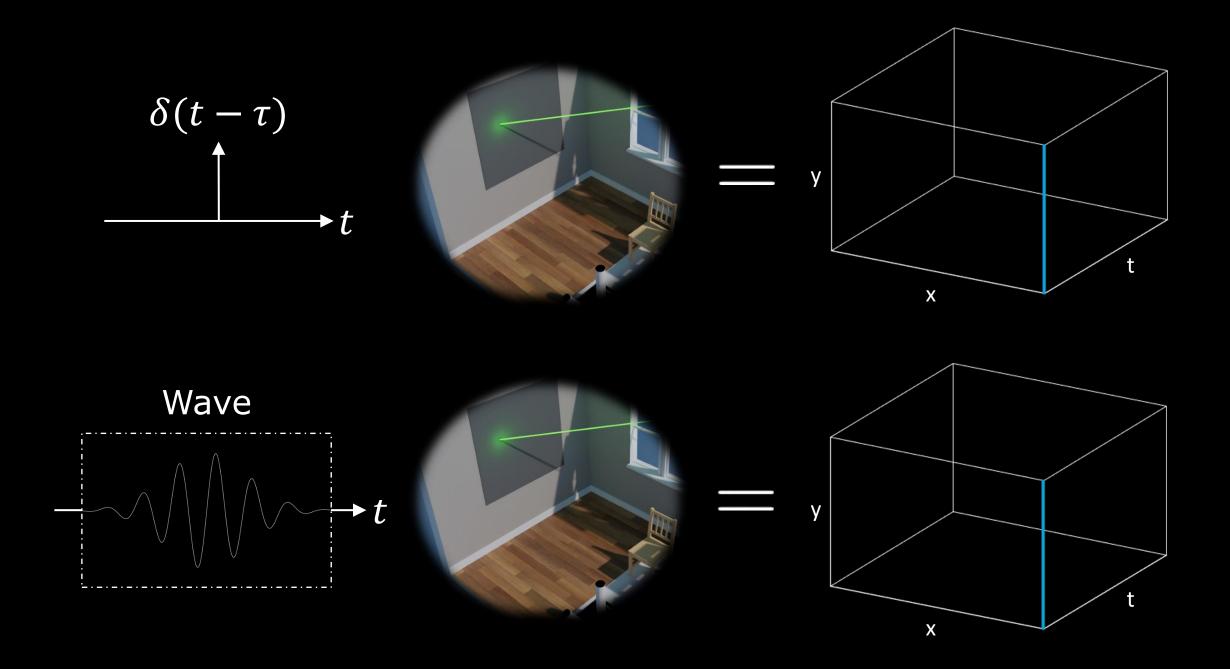


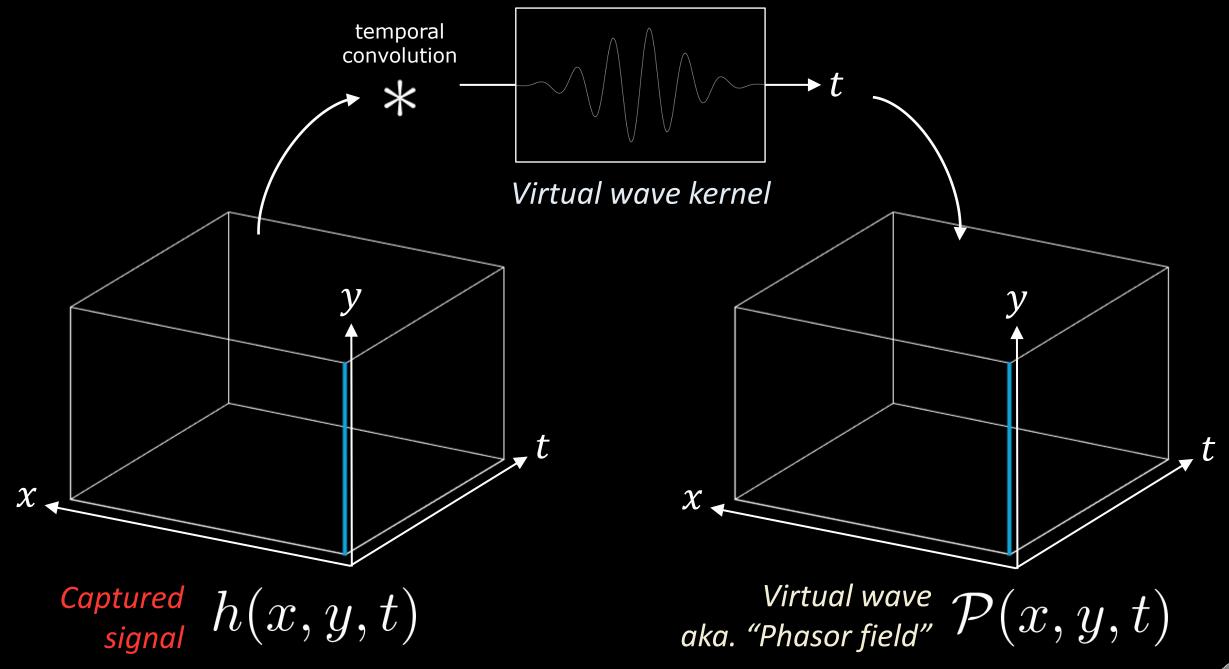
## Single Photon Avalanche Diodes (SPAD)



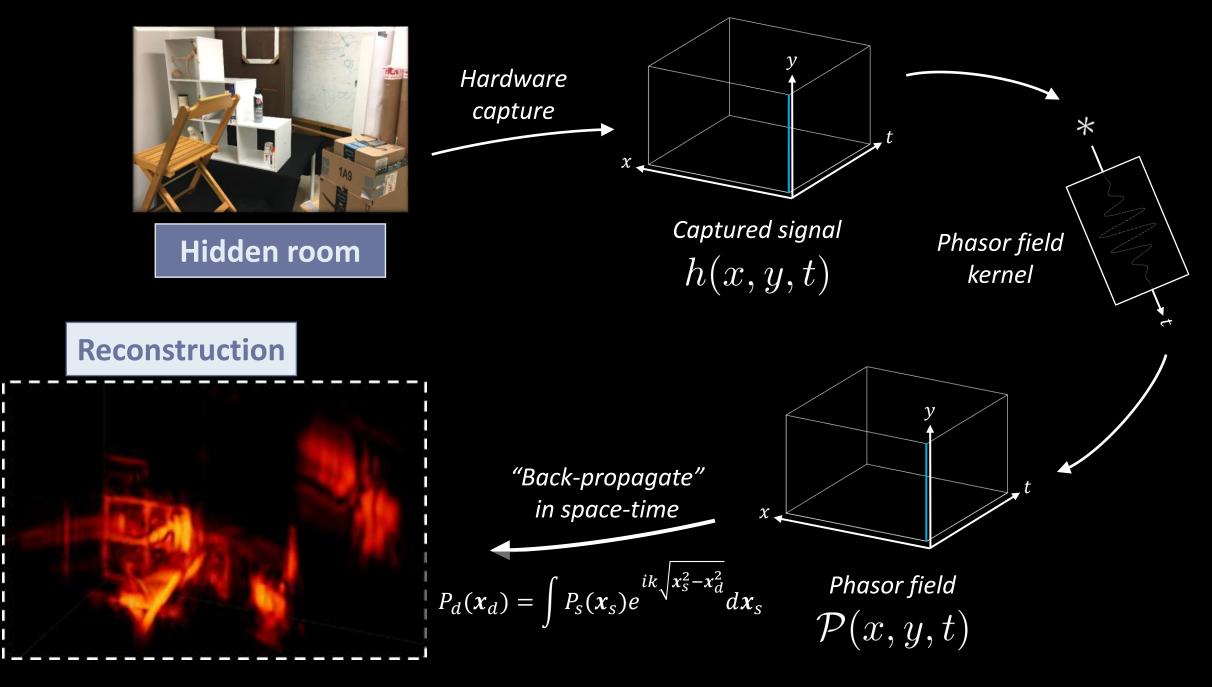
Mauro Buttafava, Alberto Tosi, Politecnico di Milano, Italy





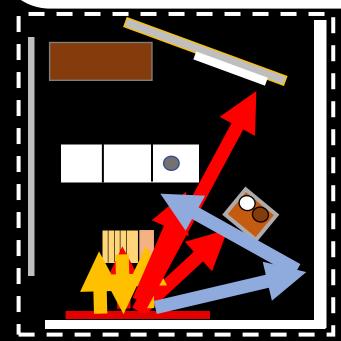


Relay Wall = Virtual Camera Aperture  $\mathcal{P}(x,y,t)^{ extsf{Scanned Laser}}_{ extsf{Pulse}}$  $P_d(\boldsymbol{x}_d) = \int P_s(\boldsymbol{x}_s) e^{ik\sqrt{x_s^2 - x_d^2}} d\boldsymbol{x}_s$ 

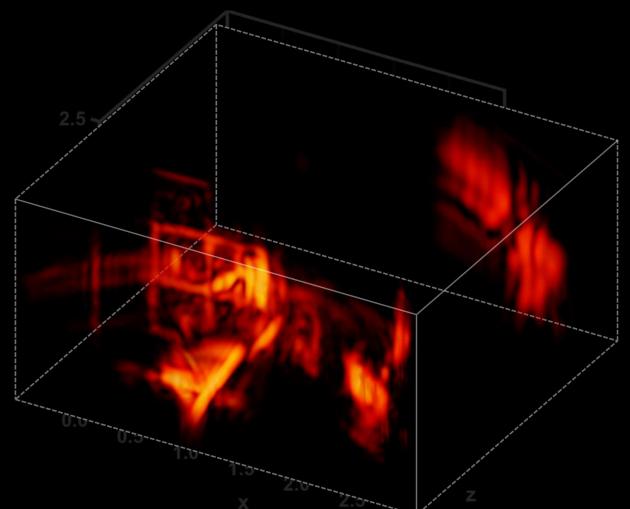


### Virtual Wave Reconstruction



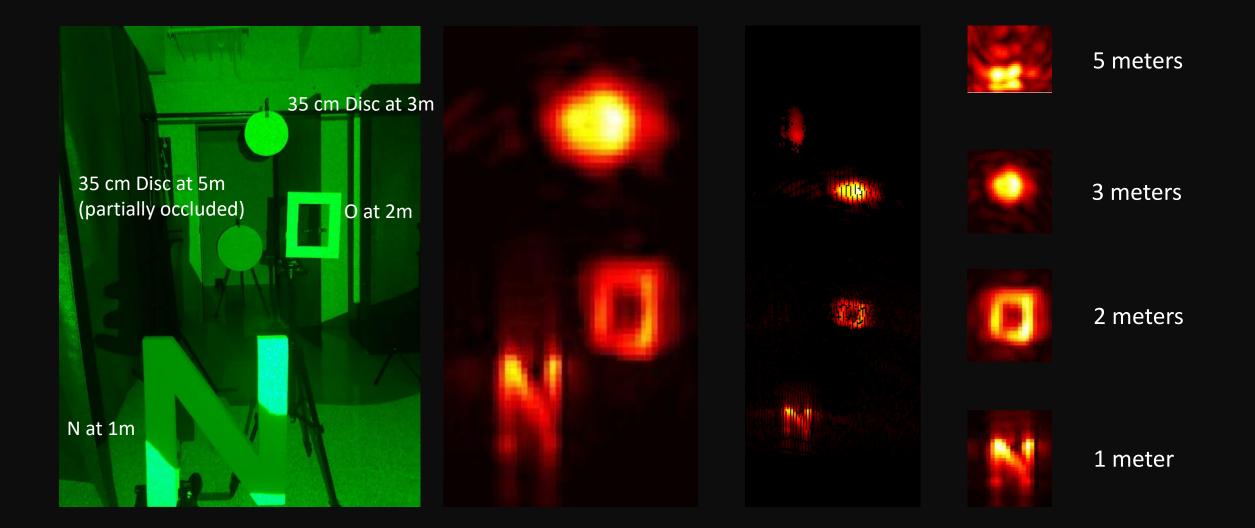


# 3<sup>rd</sup> Bounce 5<sup>th</sup> Bounce 4<sup>th</sup> Bounce



Virtual Wave Optics for Non-Line-of-Sight Imaging Xiaochun Liu, et. al., Arxiv, https://arxiv.org/abs/1810.07535 (2018)

## Phasor Field Reconstruction Results



 $P_d(x_d, y_d, z_d)$ 

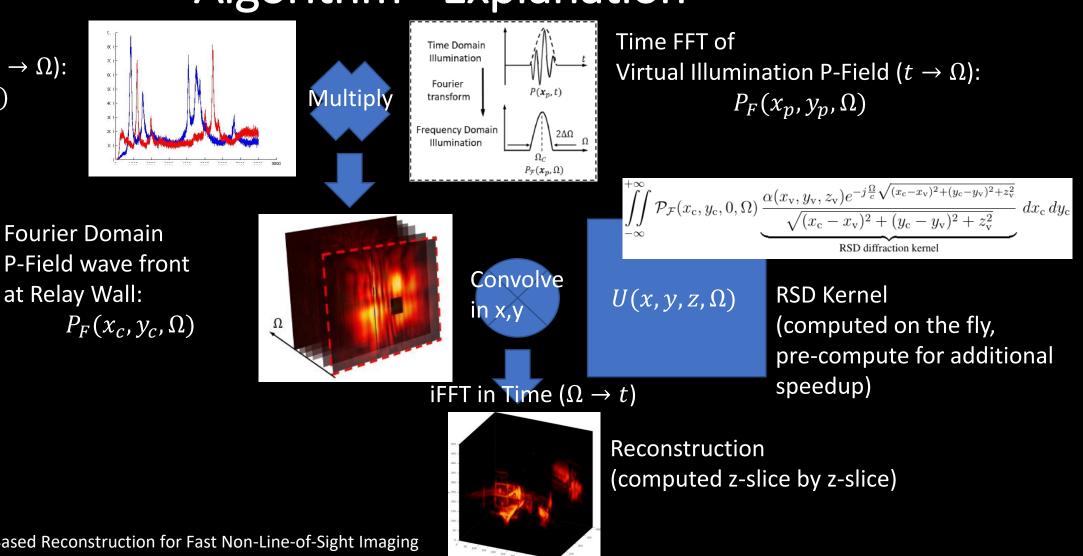
Rayleigh-Sommerfeld Diffraction (RSD):  $P_d(x_d) = \int P_s(x_s)e^{ik\sqrt{x_s^2 - x_d^2}} dx_s$ 

RSD as a Convolution:  $P_d(x_d, y_d) = \int P_s(x_s, y_s) e^{ik\sqrt{(x_s - x_d)^2 - (y_s - y_d)^2}} dx_s dy_s$ 

 $P_s(x_s, y_s, z_s)$ 

# Convolution Based Phasor Field Reconstruction Algorithm - Explanation

Time FFT of Captured Data  $(t \rightarrow \Omega)$ :  $H_F(x, y, \Omega)$ 



Phasor Field Diffraction Based Reconstruction for Fast Non-Line-of-Sight Imaging Systems, X. Liu, S. Bauer, and A. Velten, Nature Communications, 2020

# Convolution Based Phasor Field Reconstruction Algorithm - Results

Phasor Field (Nature 2019) Fast Phasor Field



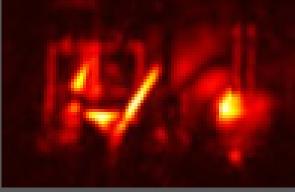
1300s (single thread) C++ code called from Matlab

2.8s (Matlab Script)





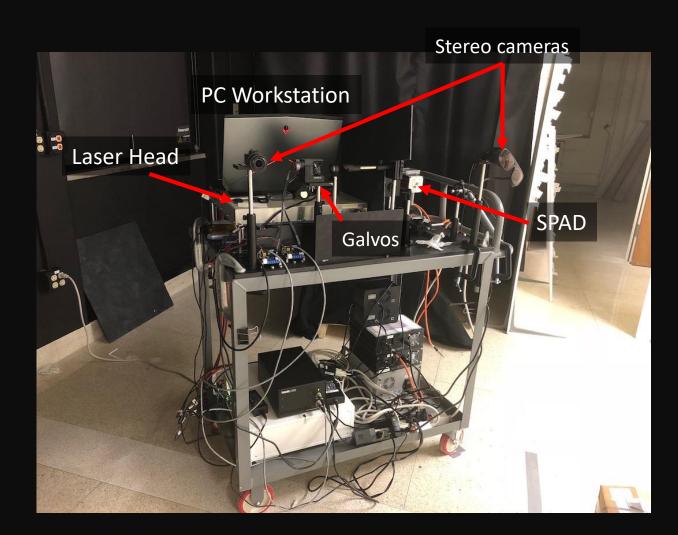
8000s (single thread) C++ code called from Matlab

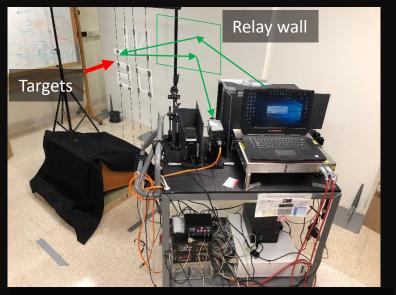


25s (Matlab Script)

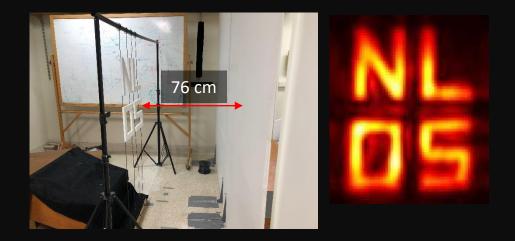
6s, ~20 MB (C++, on laptop)
0.2s, 5 GB (C++, using pre-computed kernels)
0.06s, CUDA on Quadro P5000 GPU

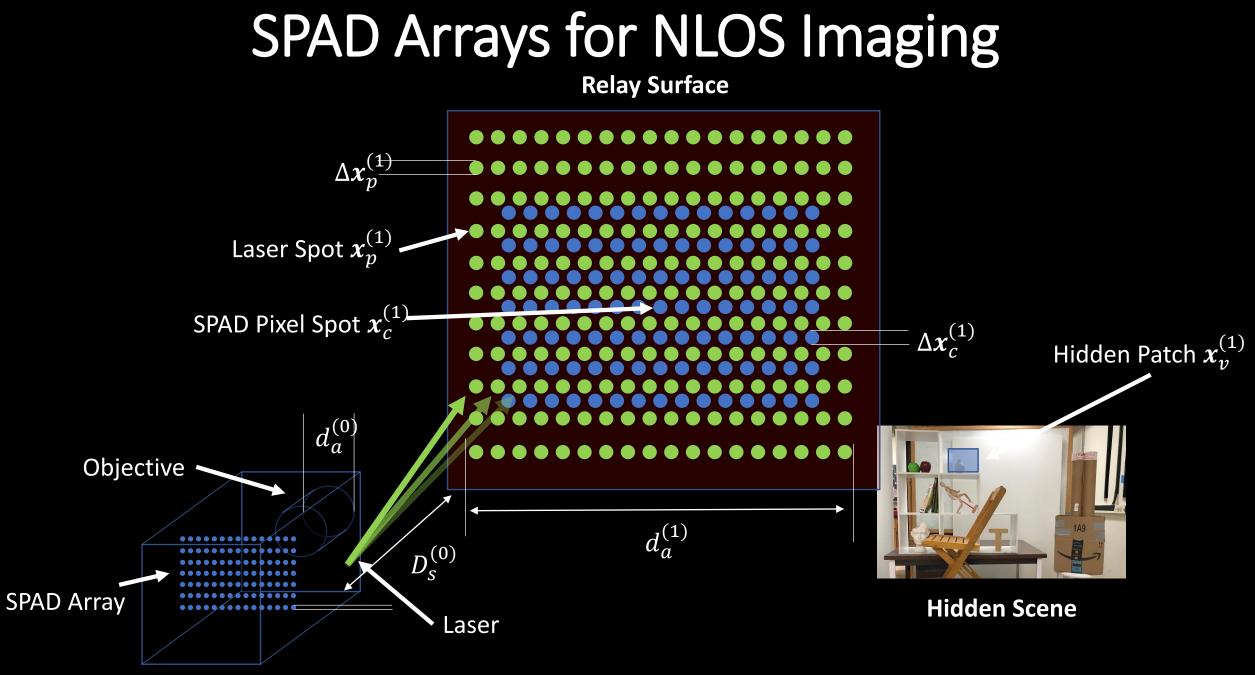
# Seeing Around Corners Setup





Note: Occluder wall was removed to show the imaging system and the scenario together





**NLOS Imaging System** 

# Problems with Prior LiDAR SPAD Arrays

- Low time resolution
- No Gate
- Small pixels optimal at large (>100m) stand-off distances ...
- Low repetition rate

#### **Fast-gated SPAD array**



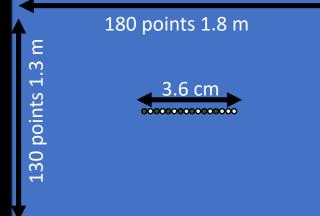
#### Linear 16 x 1 SPAD array coupled to fast-gating ASIC (M1)

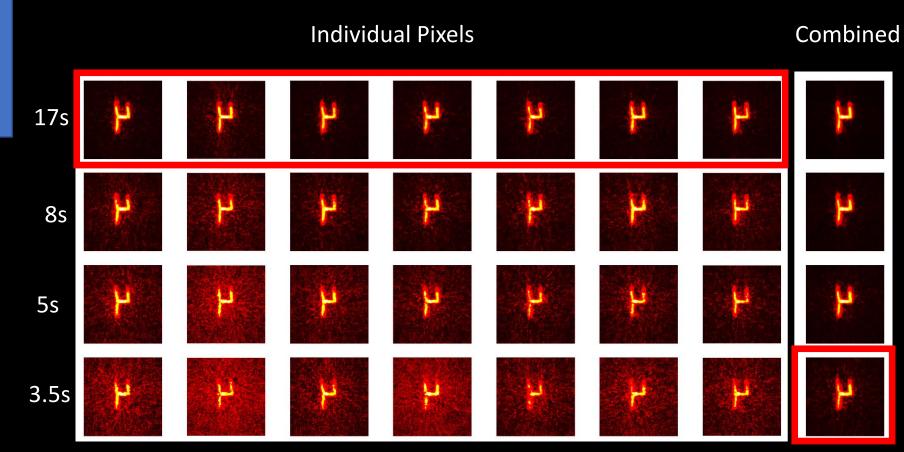
Built By The group of Alberto Tosi, Politechnico di Milano

- **50 micron pixels**
- 75% fill factor
- 75 ps time resolution
- Independent free running pixels
- 100 ns dead time
- Fast gated

Renna, M.; Nam, J.H.; Buttafava, M.; Villa, F.; Velten, A.; Tosi, A. Fast-Gated 16 × 1 SPAD Array for Non-Line-of-Sight Imaging Applications. *Instruments* **2020**, *4*, 14.

# **Reconstructions With Array**





Images have increased contrast to show noise

#### SPAD Arrays for Non-Line-of-Sight Imaging

Martin Laurenzis, French-German Resarch Institute, St. Louis, France

Mohit Gupta, CS, UW Madison

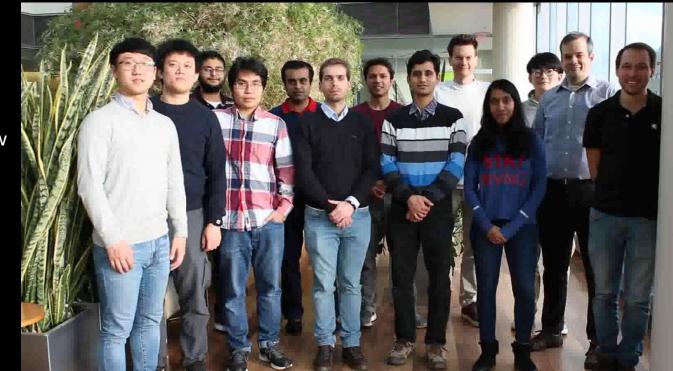
Mauro Buttafava, Alberto Tosi, **Politecnico di Milano, Italy** Karl Mitchell, James Ashley, Stephen Dawson, Nitin Arora, Andrew Shapiro, **NASA Jet Propulsion Lab, Pasadena, CA** 

Jeffrey Nosanov, Nosanov Consulting, LLC

Ibon Gulien, Belen Masia, Adrian Jarabo, Diego Gutierrez, Universidad de Zaragoza, Spain

Kevin Eliceiri, LOCI, UW Madison

Di Wu, Everett Lawson, Andy Bardagjy, Otkrist Gupta, Rohit Pandharkar, Nikhil Naik, Christopher Barsi, Amy Fritz, Ramesh Raskar, **MIT Media Lab, Cambridge, MA** Thomas Willwacher, **Harvard University** Ashok Veeraraghavan, **Rice University** 





#### biostat.wisc.edu/~compoptics